Foundations of Software Fall Semester 2009

Week 3

Review (and more details)

Recall: Simple Arithmetic Expressions

The set \mathcal{T} of terms is defined by the following abstract grammar:

Recall: Inference Rule Notation

More explicitly: The set \mathcal{T} is the *smallest* set *closed* under the following rules.

$$\begin{array}{ll} \text{true} \in \mathcal{T} & \text{false} \in \mathcal{T} & 0 \in \mathcal{T} \\ \\ \frac{\mathtt{t}_1 \in \mathcal{T}}{\mathtt{succ} \ \mathtt{t}_1 \in \mathcal{T}} & \frac{\mathtt{t}_1 \in \mathcal{T}}{\mathtt{pred} \ \mathtt{t}_1 \in \mathcal{T}} & \frac{\mathtt{t}_1 \in \mathcal{T}}{\mathtt{iszero} \ \mathtt{t}_1 \in \mathcal{T}} \\ \\ \frac{\mathtt{t}_1 \in \mathcal{T} \quad \mathtt{t}_2 \in \mathcal{T} \quad \mathtt{t}_3 \in \mathcal{T}}{\mathtt{if} \ \mathtt{t}_1 \ \mathtt{then} \ \mathtt{t}_2 \ \mathtt{else} \ \mathtt{t}_3 \in \mathcal{T}} \end{array}$$

Generating Functions

Each of these rules can be thought of as a generating function that, given some elements from \mathcal{T} , generates some other element of \mathcal{T} . Saying that \mathcal{T} is closed under these rules means that \mathcal{T} cannot be made any bigger using these generating functions — it already contains everything "justified by its members."

$$\begin{array}{ll} \text{true} \in \mathcal{T} & \text{false} \in \mathcal{T} & 0 \in \mathcal{T} \\ \\ \frac{\textbf{t}_1 \in \mathcal{T}}{\text{succ } \textbf{t}_1 \in \mathcal{T}} & \frac{\textbf{t}_1 \in \mathcal{T}}{\text{pred } \textbf{t}_1 \in \mathcal{T}} & \frac{\textbf{t}_1 \in \mathcal{T}}{\text{iszero } \textbf{t}_1 \in \mathcal{T}} \\ \\ \frac{\textbf{t}_1 \in \mathcal{T} & \textbf{t}_2 \in \mathcal{T} & \textbf{t}_3 \in \mathcal{T}}{\text{if } \textbf{t}_1 \text{ then } \textbf{t}_2 \text{ else } \textbf{t}_3 \in \mathcal{T}} \end{array}$$

Let's write these generating functions explicitly.

```
\begin{array}{lll} F_1(U) &=& \{ \text{true} \} \\ F_2(U) &=& \{ \text{false} \} \\ F_3(U) &=& \{ 0 \} \\ F_4(U) &=& \{ \text{succ } t_1 \mid t_1 \in U \} \\ F_5(U) &=& \{ \text{pred } t_1 \mid t_1 \in U \} \\ F_6(U) &=& \{ \text{iszero } t_1 \mid t_1 \in U \} \\ F_7(U) &=& \{ \text{if } t_1 \text{ then } t_2 \text{ else } t_3 \mid t_1, t_2, t_3 \in U \} \end{array}
```

Each one takes a set of terms U as input and produces a set of "terms justified by U" as output.

If we now define a generating function for the whole set of inference rules (by combining the generating functions for the individual rules),

$$F(U) = F_1(U) \cup F_2(U) \cup F_3(U) \cup F_4(U) \cup F_5(U) \cup F_6(U) \cup F_7(U)$$

then we can restate the previous definition of the set of terms \mathcal{T} like this:

Definition:

- ▶ A set U is said to be "closed under F" (or "F-closed") if $F(U) \subseteq U$.
- ▶ The set of terms \mathcal{T} is the smallest F-closed set. (I.e., if \mathcal{O} is another set such that $F(\mathcal{O}) \subseteq \mathcal{O}$, then $\mathcal{T} \subseteq \mathcal{O}$.)

Our alternate definition of the set of terms can also be stated using the generating function F:

$$S_0 = \emptyset$$

$$S_{i+1} = F(S_i)$$

$$S = \bigcup_i S_i$$

Compare this definition of S with the one we saw last time:

$$\begin{array}{lll} \mathcal{S}_0 & = & \emptyset \\ \mathcal{S}_{i+1} & = & \{\texttt{true}, \texttt{false}, 0\} \\ & \cup & \{\texttt{succ} \ \texttt{t}_1, \texttt{pred} \ \texttt{t}_1, \texttt{iszero} \ \texttt{t}_1 \mid \texttt{t}_1 \in \mathcal{S}_i\} \\ & \cup & \{\texttt{if} \ \texttt{t}_1 \ \texttt{then} \ \texttt{t}_2 \ \texttt{else} \ \texttt{t}_3 \mid \texttt{t}_1, \texttt{t}_2, \texttt{t}_3 \in \mathcal{S}_i\} \end{array}$$

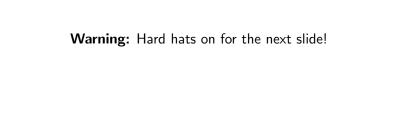
$$S = \bigcup_i S_i$$

We have "pulled out" F and given it a name.

Note that our two definitions of terms characterize the same set from different directions:

- "from above," as the intersection of all F-closed sets;
- "from below," as the limit (union) of a series of sets that start from ∅ and get "closer and closer to being F-closed."

Proposition 3.2.6 in the book shows that these two definitions actually define the same set.



The principle of structural induction on terms can also be re-stated using generating functions:

```
Suppose T is the smallest F-closed set.
```

```
If, for each set U, from the assumption "P(u) holds for every u \in U" we can show "P(v) holds for any v \in F(U)," then P(t) holds for all t \in T.
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If, for each set U,

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we can show "P(v) holds for any v \in F(U),"

then P(t) holds for all t \in T.
```

Why?

Why? Because:

- ▶ We assumed that T was the *smallest F*-closed set, i.e., that $T \subseteq O$ for any other F-closed set O.
- But showing

```
for each set U,

given P(u) for all u \in U

we can show P(v) for all v \in F(U)
```

amounts to showing that "the set of all terms satisfying P" (call it O) is itself an F-closed set.

▶ Since $T \subseteq O$, every element of T satisfies P.

Compare this with the structural induction principle for terms from last lecture:

```
If, for each term s,

given P(r) for all immediate subterms r of s

we can show P(s),

then P(t) holds for all t.
```

Recall, from the definition of S, it is clear that, if a term t is in S_i , then all of its immediate subterms must be in S_{i-1} , i.e., they must have strictly smaller depths. Therefore:

```
If, for each term s,
given P(r) for all immediate subterms r of s
we can show P(s),
then P(t) holds for all t.
```

Slightly more explicit proof:

- Assume that for each term s, given P(r) for all immediate subterms of s, we can show P(s).
- ► Then show, by induction on i, that P(t) holds for all terms t with depth i.
- ▶ Therefore, P(t) holds for all t.

Operational Semantics and

Reasoning

Recall: Abstract Machines

An abstract machine consists of:

- a set of states
- ▶ a transition relation on states, written →

For the simple languages we are considering at the moment, the term being evaluated is the whole state of the abstract machine.

Recall: Syntax for Booleans

Terms and values

Recall: Operational Semantics for Booleans

The evaluation relation $t \longrightarrow t'$ is the smallest relation closed under the following rules:

$$\begin{array}{c} \text{if true then } t_2 \text{ else } t_3 \longrightarrow t_2 \quad \text{(E-IFTRUE)} \\ \\ \text{if false then } t_2 \text{ else } t_3 \longrightarrow t_3 \quad \text{(E-IFFALSE)} \\ \\ \\ \frac{t_1 \longrightarrow t_1'}{\text{if } t_1 \text{ then } t_2 \text{ else } t_3 \longrightarrow \text{if } t_1' \text{ then } t_2 \text{ else } t_3} \text{(E-IF)} \end{array}$$

Derivations

We can record the "justification" for a particular pair of terms that are in the evaluation relation in the form of a tree.

(on the board)

Terminology:

- These trees are called derivation trees (or just derivations).
- ▶ The final statement in a derivation is its conclusion.
- We say that the derivation is a witness for its conclusion (or a proof of its conclusion) it records all the reasoning steps that justify the conclusion.

Observation

Lemma: Suppose we are given a derivation tree \mathcal{D} witnessing the pair (t, t') in the evaluation relation. Then either

- 1. the final rule used in \mathcal{D} is E-IFTRUE and we have t=if true then t_2 else t_3 and $t'=t_2$, for some t_2 and t_3 , or
- 2. the final rule used in $\mathcal D$ is E-IFFALSE and we have $\mathtt t=\mathtt{if}$ false then $\mathtt t_2$ else $\mathtt t_3$ and $\mathtt t'=\mathtt t_3$, for some $\mathtt t_2$ and $\mathtt t_3$, or
- 3. the final rule used in \mathcal{D} is E-IF and we have $t=if\ t_1\ then\ t_2\ else\ t_3$ and $t'=if\ t_1'\ then\ t_2\ else\ t_3$, for some $t_1,\ t_1',\ t_2$, and t_3 ; moreover, the immediate subderivation of \mathcal{D} witnesses $(t_1,\ t_1')\in\longrightarrow$.

Induction on Derivations

We can now write proofs about evaluation "by induction on derivation trees."

Given an arbitrary derivation \mathcal{D} with conclusion $\mathbf{t} \longrightarrow \mathbf{t}'$, we assume the desired result for its immediate sub-derivation (if any) and proceed by a case analysis (using the previous lemma) of the final evaluation rule used in constructing the derivation tree.

E.g....

Induction on Derivations — Example

Theorem: If $t \longrightarrow t'$, i.e., if $(t, t') \in \longrightarrow$, then size(t) > size(t'). **Proof:** By induction on a derivation \mathcal{D} of $t \longrightarrow t'$.

- 1. Suppose the final rule used in \mathcal{D} is E-IFTRUE, with $t = \text{if true then } t_2 \text{ else } t_3 \text{ and } t' = t_2$. Then the result is immediate from the definition of *size*.
- 2. Suppose the final rule used in \mathcal{D} is E-IFFALSE, with t=if false then t_2 else t_3 and $t'=t_3$. Then the result is again immediate from the definition of size.
- 3. Suppose the final rule used in \mathcal{D} is E-IF, with $\mathtt{t} = \mathtt{if} \ \mathtt{t}_1 \ \mathtt{then} \ \mathtt{t}_2 \ \mathtt{else} \ \mathtt{t}_3 \ \mathtt{and} \ \mathtt{t}' = \mathtt{if} \ \mathtt{t}_1' \ \mathtt{then} \ \mathtt{t}_2 \ \mathtt{else} \ \mathtt{t}_3, \ \mathtt{where} \ (\mathtt{t}_1, \ \mathtt{t}_1') \in \longrightarrow \ \mathtt{is} \ \mathtt{witnessed} \ \mathtt{by} \ \mathtt{a} \ \mathtt{derivation} \ \mathcal{D}_1. \ \mathtt{By} \ \mathtt{the} \ \mathtt{induction} \ \mathtt{hypothesis}, \ size(\mathtt{t}_1) > size(\mathtt{t}_1'). \ \mathtt{But} \ \mathtt{then}, \ \mathtt{by} \ \mathtt{the} \ \mathtt{definition} \ \mathtt{of} \ size, \ \mathtt{we} \ \mathtt{have} \ size(\mathtt{t}) > size(\mathtt{t}').$

Normal forms

A normal form is a term that cannot be evaluated any further — i.e., a term t is a normal form (or "is in normal form") if there is no t' such that $t \longrightarrow t'$.

A normal form is a state where the abstract machine is halted — i.e., it can be regarded as a "result" of evaluation.

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A normal form is a state where the abstract machine is halted — i.e., it can be regarded as a "result" of evaluation.

Recall that we intended the set of *values* (the boolean constants true and false) to be exactly the possible "results of evaluation." Did we get this definition right?

Theorem: A term t is a value iff it is in normal form.

Proof:

The \Longrightarrow direction is immediate from the definition of the evaluation relation.

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The \Longrightarrow direction is immediate from the definition of the evaluation relation.

For the \Leftarrow direction, it is convenient to prove the contrapositive: If t is *not* a value, then it is *not* a normal form.

Theorem: A term t is a value iff it is in normal form.

Proof:

The \Longrightarrow direction is immediate from the definition of the evaluation relation.

For the \iff direction, it is convenient to prove the contrapositive: If t is *not* a value, then it is *not* a normal form. The argument goes by induction on t.

Note, first, that t must have the form if t_1 then t_2 else t_3 (otherwise it would be a value). If t_1 is true or false, then rule E-IFTRUE or E-IFFALSE applies to t, and we are done.

Otherwise, t_1 is not a value and so, by the induction hypothesis, there is some t_1' such that $t_1 \longrightarrow t_1'$. But then rule E-IF yields

```
if t_1 then t_2 else t_3 \longrightarrow if t_1' then t_2 else t_3
```

i.e., t is not in normal form.

Numbers

New syntactic forms

```
succ t
      pred t
       iszero t
       nv
nv :=
       succ nv
```

```
terms
constant zero
successor
predecessor
zero test
```

```
values
numeric value
```

```
numeric values
zero value
successor value
```

New evaluation rules

$$\mathtt{t} \longrightarrow \mathtt{t}'$$

$$egin{array}{c} rac{ extbf{t}_1 \longrightarrow extbf{t}_1'}{ extsf{succ } extbf{t}_1} \longrightarrow extsf{succ } extbf{t}_1' \ pred \ 0 \longrightarrow 0 \ pred \ (\text{E-PREDZERO}) \ pred \ (extsf{succ } extsf{nv}_1) \longrightarrow extsf{nv}_1 \ pred \ extsf{t}_1 \longrightarrow extsf{t}_1' \ pred \ extsf{t}_1 \longrightarrow extsf{pred } extsf{t}_1' \ pred \ extsf{t}_1 \longrightarrow extsf{t}_1 \ pred \ extsf{t}_1 \longrightarrow extsf{t}_1' \ pred \ extsf{t}_1' \ pred \ extsf{t}_1 \longrightarrow extsf{t}_1' \ pred \ extsf{t}_1'' \ pred \ \ extsf{t}_1'' \ pred \ \ extsf{t}_1'' \ pred \ \ \ \ \ \ \ \ \$$

Our observation a few slides ago that all values are in normal form still holds for the extended language.

Is the converse true? I.e., is every normal form a value?

Values are normal forms, but we have stuck terms

Our observation a few slides ago that all values are in normal form still holds for the extended language.

Is the converse true? I.e., is every normal form a value? No: some terms are *stuck*.

Formally, a stuck term is one that is a normal form but not a value. What are some examples?

Stuck terms model run-time errors.

Multi-step evaluation.

The multi-step evaluation relation, \longrightarrow^* , is the reflexive, transitive closure of single-step evaluation.

I.e., it is the smallest relation closed under the following rules:

$$\frac{t \longrightarrow t'}{t \longrightarrow^* t'}$$

$$t \longrightarrow^* t$$

$$\frac{t \longrightarrow^* t' \qquad t' \longrightarrow^* t''}{t \longrightarrow^* t''}$$

Termination of evaluation

Theorem: For every t there is some normal form t' such that

 $\mathsf{t} \longrightarrow^* \mathsf{t}'.$

Proof:

Termination of evaluation

Theorem: For every t there is some normal form t' such that $t \longrightarrow^* t'$.

Proof:

► First, recall that single-step evaluation strictly reduces the size of the term:

if
$$t \longrightarrow t'$$
, then $size(t) > size(t')$

Now, assume (for a contradiction) that

$$t_0, t_1, t_2, t_3, t_4, \ldots$$

is an infinite-length sequence such that

$$t_0 \longrightarrow t_1 \longrightarrow t_2 \longrightarrow t_3 \longrightarrow t_4 \longrightarrow \cdots$$

► Then

$$size(t_0) > size(t_1) > size(t_2) > size(t_3) > \dots$$

But such a sequence cannot exist — contradiction!

Termination Proofs

Most termination proofs have the same basic form:

Theorem: The relation $R \subseteq X \times X$ is terminating — i.e., there are no infinite sequences x_0 , x_1 , x_2 , etc. such that $(x_i, x_{i+1}) \in R$ for each i.

Proof:

- 1. Choose
 - ▶ a well-founded set (W, <) i.e., a set W with a partial order < such that there are no infinite descending chains $w_0 > w_1 > w_2 > \dots$ in W
 - ▶ a function f from X to W
- 2. Show f(x) > f(y) for all $(x, y) \in R$
- 3. Conclude that there are no infinite sequences x_0 , x_1 , x_2 , etc. such that $(x_i, x_{i+1}) \in R$ for each i, since, if there were, we could construct an infinite descending chain in W.

The Lambda Calculus

The lambda-calculus

- ▶ If our previous language of arithmetic expressions was the simplest nontrivial programming language, then the lambda-calculus is the simplest *interesting* programming language...
 - Turing complete
 - higher order (functions as data)
- ▶ Indeed, in the lambda-calculus, *all* computation happens by means of function abstraction and application.
- ▶ The *e. coli* of programming language research
- ► The foundation of many real-world programming language designs (including ML, Haskell, Scheme, Lisp, ...)

Suppose we want to describe a function that adds three to any number we pass it. We might write

```
plus3 x = succ (succ (succ x))

That is, "plus3 x is succ (succ (succ x))."
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Q: What is plus3 itself?

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Q: What is plus3 itself?
A: plus3 is the function that, given x, yields
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```

That is, "plus3 x is succ (succ (succ x))."

Q: What is plus3 itself?

A: plus3 is the function that, given x, yields succ (succ (succ x)).

```
plus3 = \lambda x. succ (succ (succ x))
```

This function exists independent of the name plus3.

 λx . t is written "fun $x \to t$ " in OCaml and " $x \Rightarrow t$ " in Scala.

So plus3 (succ 0) is just a convenient shorthand for "the function that, given x, yields succ (succ (succ x)), applied to succ 0."

```
plus3 (succ 0)
= (\lambda x. \text{ succ (succ (succ x))) (succ 0)}
```

Abstractions over Functions

Consider the λ -abstraction

```
g = \lambda f. f (f (succ 0))
```

Note that the parameter variable f is used in the function position in the body of g. Terms like g are called higher-order functions. If we apply g to an argument like plus3, the "substitution rule" yields a nontrivial computation:

```
g plus3
= (\lambda f. f (f (succ 0))) (\lambda x. succ (succ (succ x)))
i.e. (\lambda x. succ (succ (succ x)))
((\lambda x. succ (succ (succ x))) (succ 0))
i.e. (\lambda x. succ (succ (succ x)))
(succ (succ (succ (succ 0))))
i.e. succ (succ (succ (succ (succ (succ 0)))))
```

Abstractions Returning Functions

Consider the following variant of g:

```
double = \lambda f. \lambda y. f (f y)
```

I.e., double is the function that, when applied to a function f, yields a *function* that, when applied to an argument y, yields f (f y).

Example

```
double plus3 0
= (\lambda f. \lambda y. f (f y))
        (\lambda x. succ (succ (succ x)))
i.e. (\lambda y. (\lambda x. succ (succ (succ x)))
               ((\lambda x. succ (succ (succ x))) y))
i.e. (\lambda x. succ (succ (succ x)))
               ((\lambda x. succ (succ (succ x))) 0)
i.e. (\lambda x. \text{ succ (succ (succ x))})
               (succ (succ (succ 0)))
i.e. succ (succ (succ (succ (succ (succ 0)))))
```

The Pure Lambda-Calculus

As the preceding examples suggest, once we have λ -abstraction and application, we can throw away all the other language primitives and still have left a rich and powerful programming language.

In this language — the "pure lambda-calculus" — *everything* is a function.

- Variables always denote functions
- Functions always take other functions as parameters
- The result of a function is always a function

Formalities

Syntax

```
egin{array}{ccccc} {\sf t} & & & & {\sf terms} \\ {\sf x} & & & {\sf variable} \\ {$\lambda {\sf x}. {\sf t}} & & & {\sf abstraction} \\ {\sf t} & {\sf t} & & & {\sf application} \end{array}
```

Terminology:

- terms in the pure λ -calculus are often called λ -terms
- ▶ terms of the form λx . t are called λ -abstractions or just abstractions

Syntactic conventions

Since λ -calculus provides only one-argument functions, all multi-argument functions must be written in curried style.

The following conventions make the linear forms of terms easier to read and write:

Application associates to the left

E.g.,
$$t$$
 u v means $(t$ $u)$ v , not t $(u$ $v)$

 \blacktriangleright Bodies of λ - abstractions extend as far to the right as possible

E.g.,
$$\lambda x$$
. λy . x y means λx . $(\lambda y$. x $y)$, not λx . $(\lambda y$. $x)$ y

Scope

The λ -abstraction term $\lambda x.t$ binds the variable x.

The *scope* of this binding is the *body* t.

Occurrences of x inside t are said to be *bound* by the abstraction.

Occurrences of \mathbf{x} that are *not* within the scope of an abstraction binding \mathbf{x} are said to be *free*.

Test:

$$\lambda x$$
. λy . x y z

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Test:

$$\lambda x. \lambda y. x y z$$

 $\lambda x. (\lambda y. z y) y$

Values

v ..- λ x.t

values abstraction value

Operational Semantics

Computation rule:

$$(\lambda x.t_{12})$$
 $v_2 \longrightarrow [x \mapsto v_2]t_{12}$ (E-APPABS)

Notation: $[x \mapsto v_2]t_{12}$ is "the term that results from substituting free occurrences of x in t_{12} with v_2 ."

Operational Semantics

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Notation: $[x \mapsto v_2]t_{12}$ is "the term that results from substituting free occurrences of x in t_{12} with v_2 ."

Congruence rules:

$$\frac{\mathtt{t}_1 \longrightarrow \mathtt{t}_1'}{\mathtt{t}_1 \ \mathtt{t}_2 \longrightarrow \mathtt{t}_1' \ \mathtt{t}_2} \tag{E-APP1}$$

$$\frac{\mathtt{t}_2 \longrightarrow \mathtt{t}_2'}{\mathtt{v}_1 \ \mathtt{t}_2 \longrightarrow \mathtt{v}_1 \ \mathtt{t}_2'} \tag{E-App2}$$

Terminology

A term of the form $(\lambda x.t)$ v — that is, a λ -abstraction applied to a *value* — is called a *redex* (short for "reducible expression").

Alternative evaluation strategies

Strictly speaking, the language we have defined is called the *pure*, *call-by-value lambda-calculus*.

The evaluation strategy we have chosen — *call by value* — reflects standard conventions found in most mainstream languages.

Some other common ones:

- Call by name (cf. Haskell)
- Normal order (leftmost/outermost)
- ► Full (non-deterministic) beta-reduction

Classical Lambda Calculus

Full beta reduction

The classical lambda calculus allows full beta reduction.

- ▶ The argument of a β -reduction to be an arbitrary term, not just a value.
- Reduction may appear anywhere in a term.

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 \triangleright The argument of a β -reduction to be an arbitrary term, not just a value.

 $\lambda_{x} + \longrightarrow \lambda_{x} + \prime$

Reduction may appear anywhere in a term.

Computation rule:

$$(\lambda x.t_{12})$$
 $t_2 \longrightarrow [x \mapsto t_2]t_{12}$ (E-APPABS)

Congruence rules:

$$\frac{t_1 \longrightarrow t'_1}{t_1 \ t_2 \longrightarrow t'_1 \ t_2} \qquad (E-App1)$$

$$\frac{t_2 \longrightarrow t'_2}{t_1 \ t_2 \longrightarrow t_1 \ t'_2} \qquad (E-App2)$$

$$\frac{t \longrightarrow t'}{t_1 \ t_2 \longrightarrow t'} \qquad (E-App2)$$

Substitution revisited

Remember: $[x \mapsto v_2]t_{12}$ is "the term that results from substituting free occurrences of x in t_{12} with v_2 ."

This is trickier than it looks! For example:

```
(\lambda x. (\lambda y. x)) y
\longrightarrow [x \mapsto y]\lambda y. x
= ???
```

Substitution revisited

Remember: $[x \mapsto v_2]t_{12}$ is "the term that results from substituting free occurrences of x in t_{12} with v_2 ."

This is trickier than it looks! For example:

$$(\lambda x. (\lambda y. x)) y$$

$$\longrightarrow [x \mapsto y]\lambda y. x$$

$$= ???$$

Solution:

need to rename bound variables before performing the substitution.

$$(\lambda x. (\lambda y. x)) y$$

$$= (\lambda x. (\lambda z. x)) y$$

$$\longrightarrow [x \mapsto y]\lambda z. x$$

$$= \lambda z. y$$

Alpha conversion

Renaming bound variables is formalized as α -conversion.

Conversion rule:

$$\frac{y \notin fv(t)}{\lambda x. \ t =_{\alpha} \lambda y.[x \mapsto y]t}$$
 (\alpha)

Equivalence rules:

$$\frac{\mathsf{t}_1 =_{\alpha} \mathsf{t}_2}{\mathsf{t}_2 =_{\alpha} \mathsf{t}_1} \qquad (\alpha \text{-SYMM})$$

$$\frac{\mathsf{t}_1 =_\alpha \mathsf{t}_2 \qquad \mathsf{t}_2 =_\alpha \mathsf{t}_3}{\mathsf{t}_1 =_\alpha \mathsf{t}_3} \qquad (\alpha\text{-Trans})$$

Congruence rules: the usual ones.

Confluence

Full β -reduction makes it possible to have different reduction paths.

Q: Can a term evaluate to more than one normal form?

Confluence

Full β -reduction makes it possible to have different reduction paths.

Q: Can a term evaluate to more than one normal form?

The answer is no; this is a consequence of the following

Theorem [Church-Rosser]

Let t, t_1 , t_2 be terms such that $t \longrightarrow^* t_1$ and $t \longrightarrow^* t_2$. Then there exists a term t_3 such that $t_1 \longrightarrow^* t_3$ and $t_2 \longrightarrow^* t_3$.

Lambda-Calculus

Programming in the

Multiple arguments

Consider the function double, which returns a function as an argument.

double =
$$\lambda f$$
. λy . f (f y)

This idiom — a λ -abstraction that does nothing but immediately yield another abstraction — is very common in the λ -calculus.

In general, λx . λy . t is a function that, given a value v for x, yields a function that, given a value u for y, yields t with v in place of x and u in place of y.

That is, λx . λy . t is a two-argument function.

(Recall the discussion of currying in OCaml.)

The "Church Booleans"

```
tru = \lambdat. \lambdaf. t
fls = \lambdat. \lambdaf. f
```

Functions on Booleans

```
not = \lambda b. b fls tru
```

That is, not is a function that, given a boolean value v, returns fls if v is tru and tru if v is fls.

Functions on Booleans

and =
$$\lambda b$$
. λc . b c fls

That is, and is a function that, given two boolean values v and w, returns w if v is tru and fls if v is fls

Thus and v w yields tru if both v and w are tru and fls if either v or w is fls.

Pairs

```
pair = \lambda f. \lambda s. \lambda b. b f s
fst = \lambda p. p tru
snd = \lambda p. p fls
```

That is, pair v w is a function that, when applied to a boolean value b, applies b to v and w.

By the definition of booleans, this application yields v if b is tru and w if b is fls, so the first and second projection functions fst and snd can be implemented simply by supplying the appropriate boolean.

Example

Church numerals

Idea: represent the number n by a function that "repeats some action n times."

```
c_0 = \lambda s. \lambda z. z

c_1 = \lambda s. \lambda z. s z

c_2 = \lambda s. \lambda z. s (s z)

c_3 = \lambda s. \lambda z. s (s (s z))
```

That is, each number n is represented by a term c_n that takes two arguments, s and z (for "successor" and "zero"), and applies s, n times, to z.

Successor:

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$$scc = \lambda n. \lambda s. \lambda z. s (n s z)$$

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Addition:

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$$scc = \lambda n. \lambda s. \lambda z. s (n s z)$$

Addition:

```
plus = \lambdam. \lambdan. \lambdas. \lambdaz. m s (n s z)
```

Successor:

$$scc = \lambda n. \lambda s. \lambda z. s (n s z)$$

Addition:

plus =
$$\lambda m$$
. λn . λs . λz . m s $(n$ s z)

Multiplication:

Successor:

$$scc = \lambda n. \lambda s. \lambda z. s (n s z)$$

Addition:

plus =
$$\lambda m$$
. λn . λs . λz . m s $(n$ s $z)$

Multiplication:

```
times = \lambdam. \lambdan. m (plus n) c<sub>0</sub>
```

Successor:

$$scc = \lambda n. \lambda s. \lambda z. s (n s z)$$

Addition:

plus =
$$\lambda$$
m. λ n. λ s. λ z. m s (n s z)

Multiplication:

```
times = \lambda m. \lambda n. m (plus n) c_0
```

Zero test:

Successor:

```
scc = \lambda n. \lambda s. \lambda z. s (n s z)
```

Addition:

```
plus = \lambda m. \lambda n. \lambda s. \lambda z. m s (n s z)
```

Multiplication:

```
times = \lambdam. \lambdan. m (plus n) c<sub>0</sub>
```

Zero test:

```
iszro = \lambdam. m (\lambdax. fls) tru
```

Successor:

$$scc = \lambda n. \lambda s. \lambda z. s (n s z)$$

Addition:

plus =
$$\lambda m$$
. λn . λs . λz . m s $(n$ s $z)$

Multiplication:

times =
$$\lambda m$$
. λn . m (plus n) c_0

Zero test:

```
iszro = \lambdam. m (\lambdax. fls) tru
```

Predecessor

```
zz = pair c_0 c_0 ss = \lambda p. pair (snd p) (scc (snd p)) prd = \lambda m. fst (m ss zz)
```

Lambda-Calculus

Recursion in the

Recursion and divergence

Recursion and divergence are intertwined, so we need to consider divergent terms.

omega =
$$(\lambda x. x x) (\lambda x. x x)$$

Note that omega evaluates in one step to itself! So evaluation of omega never reaches a normal form: it *diverges*.

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Note that omega evaluates in one step to itself! So evaluation of omega never reaches a normal form: it *diverges*.

Being able to write a divergent computation does not seem very useful in itself. However, there are variants of omega that are *very* useful...

Recall: Normal forms

- ▶ A *normal form* is a term that cannot take an evaluation step.
- A stuck term is a normal form that is not a value.

Does every term evaluate to a normal form?

No, omega is not in normal form.

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- ▶ A *normal form* is a term that cannot take an evaluation step.
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Does every term evaluate to a normal form?

No, omega is not in normal form.

But are there any stuck terms in the pure λ -calculus?

Towards recursion: Iterated application

Suppose ${\bf f}$ is some λ -abstraction, and consider the following variant of omega:

```
Y_f = (\lambda x. f(x x)) (\lambda x. f(x x))
```

Towards recursion: Iterated application

Suppose f is some λ -abstraction, and consider the following variant of omega:

```
Y_f = (\lambda x. f(x x)) (\lambda x. f(x x))
```

Now the "pattern of divergence" becomes more interesting:

```
(\lambda x. f (x x)) (\lambda x. f (x x))
     f ((\lambda x. f (x x)) (\lambda x. f (x x)))
  f (f ((\lambda x. f (x x)) (\lambda x. f (x x))))
f (f (f ((\lambda x. f (x x)) (\lambda x. f (x x)))))
```

 Y_f is still not very useful, since (like omega), all it does is diverge.

Is there any way we could "slow it down"?

Delaying divergence

```
poisonpill = \lambda y. omega
```

Note that poisonpill is a value — it it will only diverge when we actually apply it to an argument. This means that we can safely pass it as an argument to other functions, return it as a result from functions, etc.

A delayed variant of omega

Here is a variant of omega in which the delay and divergence are a bit more tightly intertwined:

omegav =
$$\lambda y$$
. $(\lambda x. (\lambda y. x x y)) (\lambda x. (\lambda y. x x y)) y$

Note that omegav is a normal form. However, if we apply it to any argument v, it diverges:

omegav v
$$= \frac{(\lambda y. (\lambda x. (\lambda y. x x y)) (\lambda x. (\lambda y. x x y)) y) v}{\longrightarrow}$$

$$\frac{(\lambda x. (\lambda y. x x y)) (\lambda x. (\lambda y. x x y))}{\longrightarrow} v$$

$$(\lambda y. (\lambda x. (\lambda y. x x y)) (\lambda x. (\lambda y. x x y)) y) v$$

$$= 0$$
omegav v

Another delayed variant

Suppose f is a function. Define

```
z_f = \lambda y. (\lambda x. f (\lambda y. x x y)) (\lambda x. f (\lambda y. x x y)) y
```

This term combines the "added f" from Y_f with the "delayed divergence" of omegav.

If we now apply \mathbf{z}_f to an argument \mathbf{v} , something interesting happens:

$$\begin{array}{c} z_f \ v \\ = \\ \underline{(\lambda y.\ (\lambda x.\ f\ (\lambda y.\ x\ x\ y))\ (\lambda x.\ f\ (\lambda y.\ x\ x\ y))\ y)\ v} \\ \longrightarrow \\ \underline{(\lambda x.\ f\ (\lambda y.\ x\ x\ y))\ (\lambda x.\ f\ (\lambda y.\ x\ x\ y))\ v} \\ = \\ \underline{f\ z_f\ v}$$

Since z_f and v are both values, the next computation step will be the reduction of f z_f — that is, before we "diverge," f gets to do some computation.

Now we are getting somewhere.

Recursion

Let

```
 \begin{array}{rcl} \mathbf{f} &=& \lambda \mathbf{f} \mathbf{c} \mathbf{t}. \\ && \lambda \mathbf{n}. \\ && \text{if n=0 then 1} \\ && \text{else n} * (\mathbf{f} \mathbf{c} \mathbf{t} \; (\mathbf{p} \mathbf{r} \mathbf{e} \mathbf{d} \; \mathbf{n})) \end{array}
```

f looks just the ordinary factorial function, except that, in place of a recursive call in the last time, it calls the function fct, which is passed as a parameter.

N.b.: for brevity, this example uses "real" numbers and booleans, infix syntax, etc. It can easily be translated into the pure lambda-calculus (using Church numerals, etc.).

We can use z to "tie the knot" in the definition of f and obtain a real recursive factorial function:

$$z_f$$
 3 \longrightarrow^*
 f z_f 3 $=$
 $(\lambda fct. \lambda n. \ldots) z_f$ 3 \longrightarrow

if 3=0 then 1 else 3 * $(z_f$ (pred 3))
 \longrightarrow^*
 $3 * (z_f$ (pred 3)))
 \longrightarrow
 $3 * (z_f$ 2)
 \longrightarrow^*
 $3 * (f$ z_f 2)
 \longrightarrow

A Generic z

If we define

$$z = \lambda f. z_f$$

i.e.,

$$\lambda f$$
. λy . $(\lambda x. f (\lambda y. x x y)) (\lambda x. f (\lambda y. x x y)) y$

then we can obtain the behavior of z_f for any f we like, simply by applying z to f.

$$z f \longrightarrow z_f$$

For example:

```
fact = z ( \lambdafct.

\lambdan.

if n=0 then 1

else n * (fct (pred n)) )
```

Technical Note

The term z here is essentially the same as the fix discussed the book.

```
z = \lambda f. \lambda y. (\lambda x. f (\lambda y. x x y)) (\lambda x. f (\lambda y. x x y)) y
fix = \lambda f. (\lambda x. f (\lambda y. x x y)) (\lambda x. f (\lambda y. x x y))
```

z is hopefully slightly easier to understand, since it has the property that $z f v \longrightarrow^* f (z f) v$, which fix does not (quite) share.