Part VI: Type Systems

- Previously, we have considered statically untyped languages.
- We now look at type systems
- A type system is a set of rules which assigns types to parts of programs.
- If some part of a program cannot be assigned a type, the program is rejected with a type error.
- In the following, we will look at some simple type systems and their properties.

Strong/Weak typing vs Static/Dynamic typing

- A language is *strongly typed* or *safe* if violation of its rules will lead to an error, rather than leading to unspecified behavior. Otherwise, we say that the language is *weakly typed* or *untyped*.
- A language is *statically typed* if there is a type system which will disallow certain programs before such programs are run.
- Static and strong typing are not the same:

static dynamic		strong	weak
dynamic	static		
ľ	dynamic		
		I	

- Usually, some safety checks are left until run-time (example: array bounds checking) because they are impractical at compile-time.
- There are languages which guarantee complete safety at compile time, e.g. Martin Loef's type theories.
- But these require proofs of safety properties to be encoded explicitly in the program.

Questions

- What to types signify or guarantee? (\Rightarrow type soundness).
- Is type checking or type reconstruction possible?

The Simply Typed λ Calculus

- Task: Add types to λ calculus.
- Two versions:
 - With explicitly given parameter types (Church)
 - Without (Curry)
- We present the Curry version here.



Alphabets

Variablesx, y, zType Variablesa, b, cType ConstructorsK

In practice, we use arbitrary words instead of single letters. We write type constructors in upper case, type variables in lower case. Examples:

x, f, true, width	Variables
a,b,c	Type variables
Boolean, List	Type constructors

Syntax

TermsE, F::= xVariable| $\lambda x. E$ Abstraction|F EApplicationTypesT, U::= aType variable| $T \rightarrow U$ Function type| $K[T_1, \dots, T_n]$ Data type

For type constructors without parameters, we simply write K instead of K[].

Function arrows associate to the right: $T_1 \to T_2 \to T_3 = T_1 \to (T_2 \to T_3)$

Type Assignments

True	:	Boolean
Nil	:	List[Boolean]
$\lambda x.x$:	$Boolean \rightarrow Boolean$
	:	$List[Boolean] \rightarrow List[Boolean]$
	:	$a \rightarrow a$
$\lambda x.\lambda y.x$:	$a \rightarrow b \rightarrow a$
$(\lambda x.\lambda y.x)TrueNil$:	Boolean
$(\lambda f.\lambda x.fx)$:	
$(\lambda f.\lambda g.\lambda x.f(gx)$:	
x	:	
$\lambda x.xy$:	

Type Judgments

... are of the form $\Gamma \vdash E:T$.

where $\Gamma = (x_1 : T_1, \ldots, x_n : T_n)$ is a *type environment* consisting of a series of variable/type bindings, one for each free variable $x \in \text{fn}(E)$. *Read:* "Under assumptions Γ , E has type T".

Special case for closed terms (i.e. $fn(E) = \emptyset$):

$$\vdash E:T$$
 " *E* has type *T* "

Deduction Systems

A Deduction system defines a formal language of *judgments* \mathcal{J} , together with rules which let one decide whether a judgment is *derivable* or not.

Rules take the form of axioms \mathcal{J} and of deduction rules

$$rac{\mathcal{J}_1 \quad \dots \quad \mathcal{J}_n}{\mathcal{J}'}$$

A judgment \mathcal{J} is derivable iff there is a proof tree such that

- Each leaf of the tree is an instance of an axiom.
- Each internal node of the tree is an instance of a deduction rule
- The root of the tree is the judgment \mathcal{J} .

Intuitionistic Logic

The first deduction systems have been developed for logic calculi.

Example: positive intuitionistic logic.

Let P, Q range over propositions with constant **true**, operators \land, \lor and \Rightarrow (missing is **false**, \neg).

Let Π be a *hypothesis*, i.e. a set of propositions which is assumed to be true.

Problem: How to decide whether Π implies P.

Solution: Give a deduction system for judgments of the form $\Pi \vdash P$.



Example Proof

Let
$$\Pi \stackrel{\text{def}}{\equiv} (P \lor Q), (P \Rightarrow Q).$$

Then:

$\Pi \ \vdash \ P \lor Q$	$\begin{array}{c c} \Pi, P \vdash (P \Rightarrow R) & \Pi, P \vdash P \\ \hline \Pi, P \vdash R \\ \hline \Pi, P \vdash Q \lor R \end{array}$	$\begin{array}{c c} \Pi, Q \ \vdash \ Q \\ \hline \Pi, Q \ \vdash \ Q \lor R \end{array}$
	$\Pi \ \vdash \ Q \lor R$	
	$(P \lor Q) \vdash (P \Rightarrow R) \Rightarrow Q \lor R$ $\vdash (P \lor Q) \Rightarrow ((P \Rightarrow R) \Rightarrow Q \lor R)$	
	$(1 \lor Q) \rightarrow ((1 \rightarrow 1t) \rightarrow Q \lor 1t)$	

How to derive type judgments

Assume as given for each constant C a set typeof(C) of types. Then we can derive type judgments by the following rules.

(VAR)
$$\Gamma, x: T, \Gamma' \vdash x: T$$
 $(x \notin \operatorname{dom}(\Gamma'))$

$$(\rightarrow \mathbf{I}) \frac{\Gamma, x: T \vdash E: U}{\Gamma \vdash \lambda x. E: T \rightarrow U}$$

$$(\rightarrow E) \frac{\Gamma \vdash M : T \rightarrow U \qquad \Gamma \vdash N : T}{\Gamma \vdash M N : U}$$

Examples

id $\equiv \lambda x.x$: ?apply $\equiv \lambda f. \lambda x. f x$: ?twice $\equiv \lambda f. \lambda x. f (f x)$:compose $\equiv \lambda f. \lambda g. f (g x)$:

Exercise: : Construct proofs for these judgements.

Constants and Polymorphism

Nearly all programs are not closed terms but make use of predefined constants such as true or **if**.

We'd like to add these to an *initial environment* which is used to type whole programs.

But some constants have multiple types.

Example:

Nil : List[Int] Nil : List[List[Int]] Nil : List[a]

We subsume all of these types by a *type scheme* (or: *polymorphic type*).

Type Scheme $S ::= T \mid \forall a.S$

Instantiation

Type schemes can be instantiated by the following elimination rule:

$$(\forall \mathbf{E}) \frac{\Gamma \vdash E : \forall a.S}{\Gamma \vdash E : [T/a]S}$$

 $([T/a] \text{ is substitution. } \forall a.S \text{ is called a type scheme or polymorphic type}).$ Example:

$$\frac{\Gamma \vdash Nil : \forall a.List[a]}{\Gamma \vdash Nil : List[Int]}$$

For the moment, we will admit polymorphism only for predefined constants, therefore an introduction rule for \forall is missing.

Some Useful Constants and their types

```
Nil
              : ∀a.List[a]
             : \forall \mathsf{a}.\mathsf{a} \to \mathsf{List}[\mathsf{a}] \to \mathsf{List}[\mathsf{a}]
Cons
             : \forall a.List[a] \rightarrow a
head
               : \forall a.List[a] \rightarrow List[a]
tail
is Empty : \forall a. List[a] \rightarrow Boolean
              : Boolean
true
false
              : Boolean
if
               : \forall a. Boolean \rightarrow a \rightarrow a \rightarrow a
0, 1, 2, ...: Int
             : Int \rightarrow Int \rightarrow Int
plus
\mathsf{eq} \qquad : \mathsf{Int} \to \mathsf{Int} \to \mathsf{Boolean}
fix : \forall a. (a \rightarrow a) \rightarrow a
```

Example

Let

```
\begin{array}{l} \mathsf{length} = \\ \mathsf{fix} \; (\lambda \; \mathsf{length.} \lambda \; \mathsf{xs.} \\ & \mathbf{if} \; (\mathsf{isEmpty} \; \mathsf{xs}) \\ & 0 \\ & (\mathsf{plus} \; 1 \; (\mathsf{length} \; (\mathsf{tail} \; (\mathsf{xs})))) \end{array}
```

Show

 $\vdash \mathsf{ length: List[a]} \to \mathsf{Int}$

Question: What do types signify?

Answer: "Types are sets of values". E.g.

 $T \approx \{V \mid V : T\}$

where

Value
$$V ::= x \mid \lambda x.E$$

Question: Why is this useful?

Answer: Type judgements are preserved under reduction.

Subject Reduction and Type Soundness

Theorem: (Subject-Reduction) $\Gamma \vdash E : T$ and $E \twoheadrightarrow F$ imply $\Gamma \vdash F : T$.

Note: the converse of subject-reduction does not hold. I.e.

$$\Gamma \vdash F: T \land E \twoheadrightarrow F \not\Rightarrow \Gamma \vdash E: T$$

Definition: A language of terms E is *type-sound* if whenever $\vdash E:T$ then either E diverges or E reduces to a value of type T.

Type soundness is more than subject-reduction, since subject reduction still admits reduction of terms to "get stuck" in a non-value.

Theorem: Simply-typed lambda calculus is type-sound.

Product- and Sum-Types

In system discussed so far does not yet have types for products and sums.

The product type $T \times U$ represents all pairs whose first component is of type T and whose second component is of type U.

Problem: Design syntax and typing rules for formation of pairs and operations on them.

The sum type T + U represents a tagged union of the types T and U.

Problem: Design syntax and typing rules for formation of tagged unions and operations on them.

The Curry-Howard Isomorphism

The deduction system for intuitionistic logic and the deduction system for simply typesd lambda calculus are remarkably similar!

We observe:

Formula	\approx	Type
Hypothesis	\approx	Type environment
\Rightarrow	\approx	\rightarrow
\wedge	\approx	×
\lor	\approx	+

If types in lambda calculus are formulas of logic, what are the terms of lambda calculus?

Terms Are Proofs

Given a type judgement $\Gamma \vdash E: T$, we can interpret E as a proof of the formula represented by T.

Example 1: The deduction rule

$$\Gamma \vdash E_1 : T_1 \qquad \Gamma \vdash E_2 : T_2$$

$$\Gamma \vdash (E_1, E_2) : T_1 \times T_2$$

can be interpreted as:

"Given a proof E_1 of T_1 and a proof E_2 of T_2 we combine the two proofs to yield a proof of $T_1 \wedge T_2$."

Logical Frameworks

The Curry-Howard Isomorphism is used in interactive theorem provers such as LCF, ELF, HOL, Isabelle.

The user of such a prover encodes a proposition as a type and then proves the proposition by presenting a term which has this type.

Type systems are usually richer than the one we have seen – in particular they admit often admit types which depend on values.

Example: Array(N) – the types of arrays with length N.

Type Checking and Type Reconstruction

We now come to the question of type checking and type reconstruction.

Type checking:

Given Γ , E and T, check whether $\Gamma \vdash E: T$

Type reconstruction:

Given Γ and E, find a type T such that $\Gamma \vdash E: T$

Type checking and reconstruction seem difficult since parameters in lambda calculus do not carry their types with them.

Type reconstruction also suffers from the problem that a term can have many types.

Idea: : We construct all type derivations in parallel, reducing type reconstruction to a unification problem.



Constants

Constants are treated as variables in the initial environment.

However, we have to make sure we create a new instance of their type as follows:

```
newInstance(\forall a_1, ..., a_n.S) =
let \ b_1, ..., b_n \ fresh \ in
[b_1/a_1, ..., b_n/a_n]S
TP(\Gamma \vdash E : T) =
case \ E \ of
x \quad : \ \{newInstance(\Gamma(x)) \stackrel{\circ}{=} T\}
...
```

Soundness and Completeness I

Definition: In general, a type reconstruction algorithm \mathcal{A} assigns to an environment Γ and a term E a set of types $\mathcal{A}(\Gamma, E)$.

The algorithm is *sound* if for every type $T \in \mathcal{A}(\Gamma, E)$ we can prove the judgement $\Gamma \vdash E : T$.

The algorithm is *complete* if for every provable judgement $\Gamma \vdash E : T$ we have that $T \in \mathcal{A}(\Gamma, E)$.

Theorem: TP is sound and complete. Specifically: $\Gamma \vdash E: T$ iff $\exists \overline{b}.[T/a]EQNS$ where a is a new type variable $EQNS = TP(\Gamma \vdash E:a)$ $\overline{b} = tv(EQNS) \setminus tv(\Gamma)$ Here, tv denotes the set of free type varibales (of a term, and environment, an equation set).

Type Reconstruction and Unification

Problem: : Transform set of equations

$$\{T_i \stackrel{\circ}{=} U_i\}_{i=1,\,\ldots,\,m}$$

into equivalent substitution

$$\{a_j \stackrel{}{=} T'_j\}_{j=1,\ldots,n}$$

where type variables do not appear recursively on their right hand sides (directly or indirectly). That is:

$$a_j \notin \operatorname{tv}(T'_k)$$
 for $j = 1, \ldots, n, k = j, \ldots, n$

Substitutions

A substitution s is an idempotent mapping from type variables to types which maps all but a finite number of type variables to themselves.

We often represent a substitution is as set of equations $a \stackrel{\circ}{=} T$ with a not in tv(T).

Substitutions can be generalized to mappings from types to types by definining

$$s(T \to U) = sT \to sU$$
$$s(K[T_1, \dots, T_n]) = K[sT_1, \dots, sT_n]$$

Substitutions are idempotent mappings from types to types, i.e. s(s(T)) = s(T). (why?) The \circ operator denotes composition of substitutions (or other functions): $(f \circ g) x = f(gx)$.

A Unification Algorithm

We present an incremental version of Robinson's algorithm (1965).

 $\begin{array}{rcl}mgu&:&(Type \triangleq Type) \to Subst \to Subst\\mgu(T \triangleq U) \ s&=mgu'(sT \triangleq sU) \ s\\mgu'(a \triangleq a) \ s&=s\\mgu'(a \triangleq T) \ s&=s \cup \{a \triangleq T\} & \text{if } a \notin tv(T)\\mgu'(T \triangleq a) \ s&=s \cup \{a \triangleq T\} & \text{if } a \notin tv(T)\\mgu'(T \to T' \triangleq U \to U') \ s&=(mgu(T' \triangleq U') \circ mgu(T \triangleq U)) \ s\\mgu'(K[T_1, \dots, T_n] \triangleq K[U_1, \dots, U_n]) \ s\\mgu'(T \triangleq U) \ s&=error & \text{in all other cases}\end{array}$

Soundness and Completeness of Unification

Definition: A substitution u is a *unifier* of a set of equations $\{T_i = U_i\}_{i=1,...,m}$ if $uT_i = uU_i$, for all i. It is a *most general unifier* if for every other unifier u' of the same equations there exists a substitution s such that $u' = s \circ u$.

Theorem: Given a set of equations EQNS. If EQNS has a unifier then $mgu \ EQNS$ {} computes the most general unifier of EQNS. If EQNS has no unifier then $mgu \ EQNS$ {} fails.





Soundness and Completeness II

One can show by comparison with the previous algorithm:

Theorem: TP is sound and complete. Specifically:

 $\Gamma \vdash E: T \quad \text{iff} \quad T = r(s(t))$

where

t is a new type variable

 $s = TP \ (\Gamma \ \vdash \ E:t) \ \{\}$

r is a substitution on $tv(s t) \setminus tv(s \Gamma)$

Strong Normalization

Question: Can Ω be given a type?

$$\Omega = (\lambda x.xx)(\lambda x.xx) :?$$

What about Y?

Self-application is not typable!

In fact, we have more:

Theorem: (Strong Normalization) If $\vdash E:T$, then there is a value V such that $E \rightarrow V$.

Corollary: Simply typed lambda calculus is not Turing complete.