1. Warmup

- **Output for asynchronous pi** Rewrite the labelled transition rule OUT for asynchronous pi processes.
- **Communication for asynchronous pi** Rewrite the reduction rule REACT for asynchronous pi processes.

2. Elastic buffers

We may define an unbounded buffer of names built from cells $\mathsf{E}\langle i, o \rangle$ as

$$\begin{split} \mathsf{E}(i,o) &:= i(x).\mathsf{F}\langle i,o,x \rangle \\ \mathsf{F}(i,o,x) &:= \overline{o}\langle x \rangle.\mathsf{E}\langle i,o \rangle + i(y).(\boldsymbol{\nu}c) \left(\mathsf{F}\langle i,c,y \rangle | \mathsf{F}\langle c,o,x \rangle \right) \end{split}$$

- 1. Give the transitions for an empty buffer cell performing the following sequence of operations.
 - (a) Storing two names
 - (b) Reading back one name
 - (c) Storing one name
 - (d) Reading back one name

What is the resulting term?

Note that "useless" bound names can be removed using structural congruence.

2. Using the name-passing capability of the pi-calculus, redefine the cell so that empty cells can disappear when they are next to a full cell.

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Hint: Chose whether disappearance is triggered by having a full cell on the left, on the right or either. You will need another channel.
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3. Encoding Polyadic pi

A homomorphic (with respect to parallel composition, restriction and addition) encoding of the polyadic pi calculus into the monadic pi calculus is given by

$$\begin{bmatrix} \overline{a} \langle \vec{b} \rangle . P \end{bmatrix} \stackrel{\text{def}}{=} \overline{a} \langle b_1 \rangle . \cdots . \overline{a} \langle b_n \rangle . \llbracket P \rrbracket$$
$$\begin{bmatrix} a(\vec{b}) . P \end{bmatrix} \stackrel{\text{def}}{=} a(b_1) . \cdots . a(b_n) . \llbracket P \rrbracket$$

- 1. Show that for $P \stackrel{\text{def}}{=} (\boldsymbol{\nu} a) (\overline{a} \langle a, c \rangle . \overline{a} \langle \rangle . \mathbf{0} \mid a(x, y) . x() . \mathbf{0}), P \rightarrow^* \equiv \mathbf{0}.$
- 2. Why does the encoding not work for all processes? Give an example of a process *Q* such that *Q* and $\llbracket Q \rrbracket$ behave differently.
- 3. Change the definition of $[\cdot]$ such that it does work for all processes *P*. *Hint: This couldn't be done in value-passing CCS.*

4. Encoding Input-guarded Choice (Homework)

We study the extension of the *asynchronous* π -calculus by *input-guarded* summation

$$P ::= \ldots \mid \sum_{i \in I} y_i(\vec{x}) . P_i \mid \text{ if } x \text{ then } P \text{ else } P$$

where, in addition to names, also *primitive boolean values* (denoted t and f) may be transmitted in communications, and used in the above *conditional operator*.

Find an encoding of this calculus into its summation-free fragment of the calculus, implementing input-guarded summation by means of the other operators. The essential idea is to use parallel composition to run the branches of a summation concurrently, and to use a simple locking mechanism that implements their mutual exclusion, roughly as follows:

$$\begin{bmatrix} \sum_{i \in I} y_i(\vec{x}) \cdot P_i \end{bmatrix} \stackrel{\text{def}}{=} (\boldsymbol{\nu}l) \left(\dots \right| \prod_{i \in I} \llbracket y_i(\vec{x}) \cdot P_i \rrbracket_l \right)$$
$$\begin{bmatrix} y(\vec{x}) \cdot P \rrbracket_l \stackrel{\text{def}}{=} \end{bmatrix}$$

where all other operators (including messages) are just translated homomorphically. Note that the translation of an input guard (a branche of a summation) is parameterized on some name l to access the locking mechanism of the summation that it belongs to.

- 1. Complete the two encoding clauses above.
- 2. Argue informally for why your solution makes sense.