

# **Concurrency: Languages, Programming and Theory**

**– CCS –**

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# Plan

- Session 4
  - from  $\lambda$ -calculus to CCS: towards concurrency
  - Structural Operational Semantics (SOS)
- Session 5
  - examples ...
  - ... using the Scala-library
- Session 6
  - from CCS to  $\pi$ -calculus: pragmatics, syntax, semantics
  - more SOS
- Session 7
  - from  $\pi$ -calculus to Java ... and back again
  - ... using the Scala-library

# Foundational Calculi ?

We are interested in the foundations of programming.  
We use “foundational” mini-languages as vehicles that guide our intuition and style of expression. When does such a mini-language deserve to be called a “calculus”?

- few primitives
- mathematically tractable
  - *calculate* computational steps
  - notion of equivalence
- *computationally complete* (Turing, URM, GOTO, ...)
- “*naturally complete*”: design of programming languages
  - easily “extensible” via *encodings*
  - *higher-order* principles

# $\lambda$ -Calculus

- **Syntax** (for example)  
a BNF-grammar generates the set of expressions ...

$$M, N ::= x \quad | \quad \lambda x.N \quad | \quad MN$$

- **Semantics** (for example)  
a set of inference rules generates (and controls) the possible reductions of terms

$$(\beta) \frac{}{(\lambda x.N)M \rightarrow [M/x]N}$$

$$(\text{FUN}) \frac{M \rightarrow M'}{MN \rightarrow M'N}$$

$$(\text{ARG}) \frac{N \rightarrow N'}{MN \rightarrow MN'}$$

# Concurrency?

- parallelism:  $\geq 1$  independent threads of control
- distribution:
  - logical concurrency
  - physical concurrency
  - failures
- synchronization / cooperation / coordination communication

$\implies$  foundational calculus for (just) concurrency ?

# Functional vs Concurrent

- functional / reduction systems:
  - reduce a term to value form
  - *only* the resulting value is interesting
  - observation after termination
- concurrent / reactive systems:
  - describe the possible interactions *during* evaluation
  - the resulting value is *not* (necessarily) interesting
  - observation through and during interaction

The notion of *interaction (communication)* is important !

Hoare (CSP) and Milner (CCS) proposed handshake-communication as the primitive form of interaction.

# Functional vs Concurrent

	functional	concurrent
determinism	possible	?
confluence	wanted/needed	?
termination	?	?
foundation	$\lambda$	CCS, $\pi$ , (Petri nets, ...)
ff-language	ML, Scala, ...	Pict, Join, Scala, ...

# CCS

$\mathcal{I}$  process identifiers  $A, B \dots$

$\mathcal{N}$  names  $a, b, c \dots$

$\overline{\mathcal{N}}$  co-names  $\bar{a}, \bar{b}, \bar{c} \dots$

$\mathcal{L}$  labels (buttons) metavariables  $\lambda \dots \in \mathcal{L} := \mathcal{N} \cup \overline{\mathcal{N}}$

$\mathcal{A}$  actions metavariables  $\mu, \beta \dots \in \mathcal{L} \cup \{\tau\}$

- visible/external actions: labels
- invisible/internal actions:  $\tau$
- finite sequences**  $\vec{a}$  for *names*  $a_1 \dots, a_n$  (*not co-names!*)
- parametric processes**  $A\langle a, c \rangle$  with *name* parameters (neither co-names, nor labels, ...)



# Sequential Process Expressions (I)

**Definition:** The sets  $\mathcal{P}^{\text{seq}}$  and  $\mathcal{M}^{\text{seq}}$  of sequential process expressions is defined (precisely) by the following BNF-syntax:

$$\begin{array}{l} P ::= A\langle \vec{a} \rangle \quad | \quad M \\ M ::= \mathbf{0} \quad | \quad \mu.P \quad | \quad M + M \end{array}$$

We use  $P, Q, P_i \dots$  to stand for *process expressions*, while  $M, M_i$  always stand for *choices* or *summations*. We also use the abbreviation

$$\sum_{i \in I} \mu_i.P_i := \mu_1.P_1 + \dots + \mu_n.P_n$$

where  $I$  is the finite indexing set  $\{1 \dots, n\}$ .

Note that then the order of summands is not fixed.

# Sequential Process Expressions (II)

- each process identifier  $A$  is assumed to have a **defining equation** (note the brackets)

$$A(\vec{a}) \stackrel{\text{def}}{=} M$$

where  $M$  is a summation,  $\vec{a}$  is (or: includes)  $\text{fn}(M)$ .

Note:  $\vec{a}$  does only include *names* ( $\in \mathcal{N}$ ), not co-names!

- $\text{fn}(P)$ : the set of all of the **(free) names** of  $P$
- $A\langle \vec{b} \rangle$  means the same as  $[\vec{b}/\vec{a}]M$
- **substitution**  $[\vec{b}/\vec{a}]P$  (for matching  $\vec{b}$  and  $\vec{a}$ ) replaces *all* occurrences of  $a_i$  in  $P$  by  $b_i$ .

# Free Names, Inductively

**Definition:** The set  $\text{fn}(P)$  is defined inductively by:

$$\text{fn}(\mu) \stackrel{\text{def}}{=} \begin{cases} \{b\} & \text{if } \mu = b \\ \{b\} & \text{if } \mu = \bar{b} \\ \emptyset & \text{if } \mu = \tau \end{cases}$$

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$$\text{fn}(\mathbf{0}) \stackrel{\text{def}}{=} \emptyset$$

$$\text{fn}(\mu.P) \stackrel{\text{def}}{=} \text{fn}(\mu) \cup \text{fn}(P)$$

$$\text{fn}(M_1 + M_2) \stackrel{\text{def}}{=} \text{fn}(M_1) \cup \text{fn}(M_2)$$

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$$\text{fn}(A\langle \vec{a} \rangle) \stackrel{\text{def}}{=} \{\vec{a}\}$$

# Substitution, Inductively

## Definition:

$$\begin{array}{l} [b/c]\mu \stackrel{\text{def}}{=} \begin{cases} b & \text{if } \mu = c \\ \bar{b} & \text{if } \mu = \bar{c} \\ \mu & \text{otherwise} \end{cases} \\ \hline [b/c]\mathbf{0} \stackrel{\text{def}}{=} \mathbf{0} \\ [b/c](\mu.P) \stackrel{\text{def}}{=} [b/c]\mu.[b/c]P \\ [b/c](M_1 + M_2) \stackrel{\text{def}}{=} [b/c]M_1 + [b/c]M_2 \\ \hline [b/c](A\langle \vec{a} \rangle) \stackrel{\text{def}}{=} A\langle [b/c]\vec{a} \rangle \end{array}$$

# Simultaneous Substitution, Inductively

## Definition:

Let  $\vec{b} = b_1 \dots, b_n$  and  $\vec{c} = c_1 \dots, c_n$ .

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$$[\vec{b}/\vec{c}]\mu \stackrel{\text{def}}{=} \begin{cases} b_i & \text{if } \exists 1 \leq i \leq n \text{ with } \mu = c_i \\ \bar{b}_i & \text{if } \exists 1 \leq i \leq n \text{ with } \mu = \bar{c}_i \\ \dots & \text{otherwise} \end{cases}$$

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$$[\vec{b}/\vec{c}]\mathbf{0} \stackrel{\text{def}}{=} \mathbf{0}$$

$$[\vec{b}/\vec{c}](\mu.P) \stackrel{\text{def}}{=} [\vec{b}/\vec{c}]\mu.[\vec{b}/\vec{c}]P$$

$$[\vec{b}/\vec{c}](M_1 + M_2) \stackrel{\text{def}}{=} [\vec{b}/\vec{c}]M_1 + [\vec{b}/\vec{c}]M_2$$

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$$[\vec{b}/\vec{c}](A\langle \vec{a} \rangle) \stackrel{\text{def}}{=} A\langle [\vec{b}/\vec{c}]\vec{a} \rangle$$

# Example: 1-Place Binary Buffer

$$\mathcal{N} \quad := \quad \{ \text{in}_i, \text{out}_i \mid i \in \{0, 1\} \}$$

$$s \quad \in \quad \{\epsilon, 0, 1\}$$

$$\vec{a} \quad := \quad \text{in}_0, \text{in}_1, \text{out}_0, \text{out}_1$$

$$\text{Buff}_s^{(1)} \quad : \quad \text{1-place buffer containing } s$$

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$$\text{Buff}^{(1)}(\vec{a}) \quad \stackrel{\text{def}}{=} \quad \sum_{i \in \{0,1\}} \text{in}_i . \text{Buff}_i^{(1)} \langle \vec{a} \rangle$$

$$\text{Buff}_i^{(1)}(\vec{a}) \quad \stackrel{\text{def}}{=} \quad \overline{\text{out}_i} . \text{Buff}^{(1)} \langle \vec{a} \rangle$$

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# Example: 2-Place Binary Buffer

$$\mathcal{N} \quad := \quad \{ \text{in}_i, \text{out}_i \mid i \in \{0, 1\} \}$$

$$s \quad \in \quad \{ \epsilon, 0, 1, 00, 01, 10, 11 \}$$

$$\vec{a} \quad := \quad \text{in}_0, \text{in}_1, \text{out}_0, \text{out}_1$$

$$\text{Buff}_s^{(2)} \quad : \quad \text{2-place buffer containing } s$$

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$$\text{Buff}^{(2)}(\vec{a}) \quad \stackrel{\text{def}}{=} \quad \sum_{i \in \{0,1\}} \text{in}_i . \text{Buff}_i^{(2)} \langle \vec{a} \rangle$$

$$\text{Buff}_i^{(2)}(\vec{a}) \quad \stackrel{\text{def}}{=} \quad \overline{\text{out}_i} . \text{Buff}^{(2)} \langle \vec{a} \rangle + \sum_{j \in \{0,1\}} \text{in}_j . \text{Buff}_{ji}^{(2)} \langle \vec{a} \rangle$$

$$\text{Buff}_{ij}^{(2)}(\vec{a}) \quad \stackrel{\text{def}}{=} \quad \overline{\text{out}_j} . \text{Buff}_i^{(2)} \langle \vec{a} \rangle$$

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- modify  $\text{Buff}_s^{(2)}$  to release values in either order
- write an analogous definition for  $\text{Buff}_s^{(3)}$  ...

# Labeled Transition Systems

## Definition:

An **LTS**  $(Q, \mathcal{T})$  over an **action alphabet**  $\mathcal{A}$ :

- a set of **states**  $Q = \{q_0, q_1 \dots\}$
- a ternary **transition relation**  $\mathcal{T} \subseteq (Q \times \mathcal{A} \times Q)$

A transition  $(q, \mu, q') \in \mathcal{T}$  is also written  $q \xrightarrow{\mu} q'$ .

If  $q \xrightarrow{\mu_1} q_1 \dots \xrightarrow{\mu_n} q_n$  we call  $q_n$  a **derivative** of  $q$ .

LTSs are automata, but ignoring starting and accepting states.  
*Transition Graphs* are useful ...



# LTS - Sequential Expressions

**Definition:** The LTS  $(\mathcal{P}^{\text{seq}}, \mathcal{T})$  of sequential process expressions over  $\mathcal{A}$  has  $\mathcal{P}^{\text{seq}}$  as states, and its transitions  $\mathcal{T}$  are precisely generated by the following rules:

$$\text{PRE: } \mu.P \xrightarrow{\mu} P$$

$$\text{SUM}_1: \frac{M_1 \xrightarrow{\mu} M'_1}{M_1 + M_2 \xrightarrow{\mu} M'_1}$$

$$\text{SUM}_2: \frac{M_2 \xrightarrow{\mu} M'_2}{M_1 + M_2 \xrightarrow{\mu} M'_2}$$

$$\text{DEF: } \frac{[\vec{b}/\vec{a}]M_A \xrightarrow{\mu} P'}{A\langle \vec{b} \rangle \xrightarrow{\mu} P'} \quad \text{IF } A(\vec{a}) \stackrel{\text{def}}{=} M_A$$

Note that transition under prefix is not allowed/included.

# Concurrent Process Expressions (I)

**Definition:** The set  $\mathcal{P}$  of concurrent process expressions is defined (precisely) by the following BNF-syntax:

$$\begin{aligned} P & ::= A\langle \vec{a} \rangle \quad | \quad M \quad | \quad P|P \quad | \quad (\nu a) P \\ M & ::= \mathbf{0} \quad | \quad \alpha.P \quad | \quad M + M \end{aligned}$$

We use  $P, Q, P_i$  to stand for process expressions.

- $(\nu a) P$  restricts the scope of  $a$  to  $P$
- $(\nu ab) P$  abbreviates  $(\nu a) (\nu b) P$

# Concurrent Process Expressions (II)

- precedence: unary binds tighter than binary

$$\begin{aligned}(\nu a) P \mid Q &= ((\nu a) P) \mid Q \\ a.P + M &= (a.P) + M\end{aligned}$$

$$[a/b]M_1 + M_2 = ([a/b]M_1) + M_2$$

- what about:

$$\begin{aligned}P \mid Q + R &\stackrel{?}{=} (P \mid Q) + R \\ P \mid Q + R &\stackrel{?}{=} P \mid (Q + R)\end{aligned}$$

# Bound and Free Names

- $(\nu a) P$  **binds**  $a$  in  $P$
- $a$  occurs **bound** in  $P$ ,  
if it occurs in a subterm  $(\nu a) Q$  of  $P$
- $a$  occurs **free** in  $P$ ,  
if it occurs without enclosing  $(\nu a) Q$  in  $P$
- Define  $\text{fn}(P)$  and  $\text{bn}(P)$  inductively on  $\mathcal{P}$   
(sets of free/bound names of  $P$ ):

$$\text{fn}(P_1 | P_2) \stackrel{\text{def}}{=} \text{fn}(P_1) \cup \text{fn}(P_2)$$

$$\text{bn}(P_1 | P_2) \stackrel{\text{def}}{=} \text{bn}(P_1) \cup \text{bn}(P_2)$$

...

$$\text{fn}((\nu a) P) \stackrel{\text{def}}{=} \text{fn}(P) \setminus \{a\}$$

$$\text{bn}((\nu a) P) \stackrel{\text{def}}{=} \text{bn}(P) \cup \{a\}$$

# $\alpha$ -Conversion & Substitution

- **substitution**  $[\vec{b}/\vec{a}]P$  (for matching  $\vec{b}$  and  $\vec{a}$ )  
replaces *all free* occurrences of  $a_i$  in  $P$  by  $b_i$ .

$$[b/a](\nu b) b.a = ?$$

- $\alpha$ -**conversion**, written  $=_\alpha$ :  
conflict-free **renaming of bound names**  
(no new name-bindings shall be generated)
- **substitution**  $[\vec{b}/\vec{a}]P$  (for matching  $\vec{b}$  and  $\vec{a}$ , where  $\vec{a}$  p.w.d.)  
replaces *all free* occurrences of  $a_i$  in  $P$  by  $b_i$ ,  
possibly enforcing  $\alpha$ -conversion.

# Examples

$$\begin{aligned}(\nu a) (\bar{a}.0 | b.0) &=_{\alpha} (\nu c) (\bar{c}.0 | b.0) \\ &=_{\alpha} (\nu b) (\bar{b}.0 | b.0)\end{aligned}$$

$$\begin{aligned}[a/b] ( (\nu b) \bar{b}.0 | b.0 ) &=_{\alpha} ( (\nu b) \bar{a}.0 | a.0 ) \\ &=_{\alpha} ( (\nu b) \bar{b}.0 | a.0 )\end{aligned}$$

$$\begin{aligned}[a/b] ( (\nu a) \bar{b}.a.0 | b.0 ) &=_{\alpha} ( (\nu a) \bar{a}.a.0 | a.0 ) \\ &=_{\alpha} ( (\nu c) \bar{a}.c.0 | a.0 )\end{aligned}$$

# LTS — Concurrent Expressions

...

$$\text{PAR}_1: \frac{P_1 \xrightarrow{\mu} P'_1}{P_1|P_2 \xrightarrow{\mu} P'_1|P_2} \qquad \text{PAR}_2: \frac{P_2 \xrightarrow{\mu} P'_2}{P_1|P_2 \xrightarrow{\mu} P_1|P'_2}$$

$$\text{REACT: } \frac{P \xrightarrow{\lambda} P' \quad Q \xrightarrow{\bar{\lambda}} Q'}{P|Q \xrightarrow{\tau} P'|Q'}$$

$$\text{RES: } \frac{P \xrightarrow{\mu} P'}{(\nu a) P \xrightarrow{\mu} (\nu a) P'} \quad \text{IF } \mu \notin \{a, \bar{a}\}$$

$$\text{ALPHA: } \frac{Q \xrightarrow{\mu} Q'}{P \xrightarrow{\mu} P'} \quad \text{IF } P =_{\alpha} Q \text{ AND } P' =_{\alpha} Q'$$

# Buffers, revisited ...

$$\begin{aligned}\mathcal{N} &:= \{ \text{in}_i, \text{out}_i, \mathbf{x}_i \mid i \in \{0, 1\} \} \\ \vec{a} &:= \text{in}_0, \text{in}_1, \text{out}_0, \text{out}_1 \\ \text{Bluff}^{(2)}(\vec{a}) &\stackrel{\text{def}}{=} (\nu \mathbf{x}_0, \mathbf{x}_1) ( \text{Buff}^{(1)} \langle \text{in}_0, \text{in}_1, \mathbf{x}_0, \mathbf{x}_1 \rangle \\ &\quad | \text{Buff}^{(1)} \langle \mathbf{x}_0, \mathbf{x}_1, \text{out}_0, \text{out}_1 \rangle )\end{aligned}$$

- compare the behavior (= LTSs) of  $\text{Buff}^{(2)}$  and  $\text{Bluff}^{(2)}$
- regard both as black boxes with “buttons”  $\vec{a}$  ...