

Constant Propagation on SSA form

Advanced Compiler Techniques
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Constant Propagation

Safety

- ◆ Proves that name always has known value
- ◆ Specializes code around that value
 - ◆ Moves some computations to compile time \Rightarrow *code motion*
 - ◆ Exposes some unreachable blocks \Rightarrow *dead code*

Opportunity

- ◆ Value $\neq \perp$ signifies an opportunity

Profitability

- ◆ Compile-time evaluation is cheaper than run-time evaluation
- ◆ Branch removal may lead to block coalescing
 - ◆ If not, it still avoids the test & makes branch predictable

Sparse Constant Propagation Using SSA

```

 $\forall$  expression,  $e$       {       $\text{TOP}$  if its value is unknown (or set by  $\Phi$ -node)
     $\text{Value}(e) \leftarrow$        $c_i$  if its value is known (the constant  $c_i$ )
 $\text{WorkList} \leftarrow \emptyset$        $\text{BOT}$  if its value is known to vary
 $\forall$  SSA edge  $s = \langle u, v \rangle$ 
  if  $\text{Value}(u) \neq \text{TOP}$  then
    add  $s$  to  $\text{WorkList}$ 

while ( $\text{WorkList} \neq \emptyset$ )
  remove  $s = \langle u, v \rangle$  from  $\text{WorkList}$ 
  let  $o$  be the operation that uses  $v$ 
  if  $\text{Value}(o) \neq \text{BOT}$  then
     $t \leftarrow$  result of evaluating  $o$ 
    if  $t \neq \text{Value}(o)$  then
       $\forall$  SSA edge  $\langle o, x \rangle$ 
        add  $\langle o, x \rangle$  to  $\text{WorkList}$ 

```

Same result, fewer \wedge operations
Performs \wedge only at Φ nodes

i.e., o is “ $a \leftarrow b \text{ op } v$ ” or “ $a \leftarrow v \text{ op } b$ ”

Evaluating a Φ -node:

$\Phi(x_1, x_2, x_3, \dots, x_n)$ is
 $\text{Value}(x_1) \wedge \text{Value}(x_2) \wedge \dots \wedge \text{Value}(x_n)$

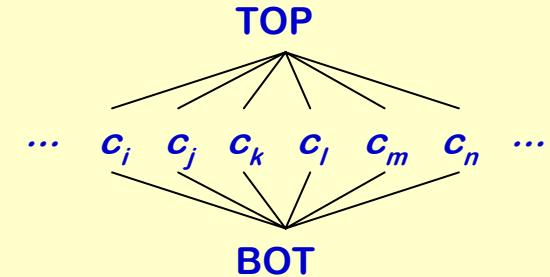
Where

$\text{TOP} \wedge x = x$	$\forall x$
$c_i \wedge c_j = c_i$	if $c_i = c_j$
$c_i \wedge c_j = \text{BOT}$	if $c_i \neq c_j$
$\text{BOT} \wedge x = \text{BOT}$	$\forall x$

Sparse Constant Propagation Using SSA

How long does this algorithm take to halt?

- ◆ Initialization is two passes
 - ◆ $|ops| + 2 \times |ops|$ edges
- ◆ Value(x) can take on 3 values
 - ◆ **TOP**, c_i , **BOT**
 - ◆ Each use can be on **WorkList** twice
 - ◆ $2 \times |args| \Rightarrow 4 \times |ops|$ evaluations, **WorkList** pushes & pops



This is an optimistic algorithm:

- ◆ Initialize all values to **TOP**, unless they are known constants
- ◆ Every value becomes **BOT** or c_i , unless its use is uninitialized

Sparse Constant Propagation

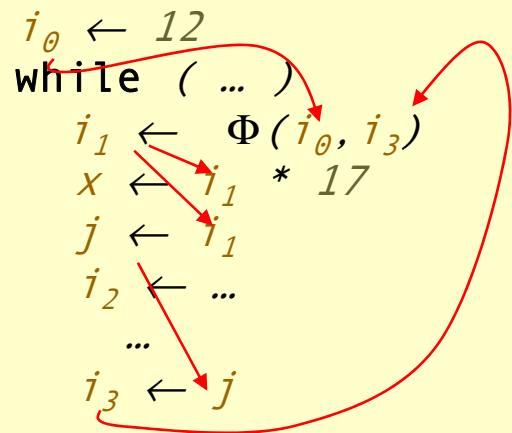
Optimism

```
i0 ← 12
while ( ... )
    i1 ← Φ(i0, i3)
    x ← i1 * 17
    j ← i1
    i2 ← ...
    ...
    i3 ← j
```

- This version of the algorithm is an *optimistic* formulation
- Initializes values to **TOP**
- Prior version used \perp (*implicit*)

Sparse Constant Propagation

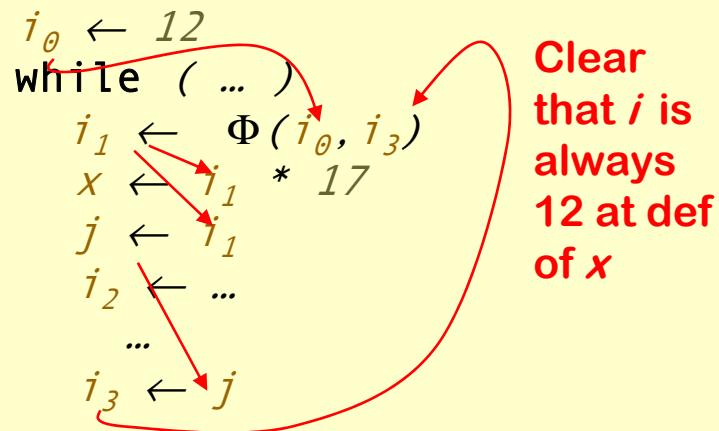
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Sparse Constant Propagation

Optimism



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Sparse Constant Propagation

Optimism

```
12    $i_0 \leftarrow 12$ 
    while ( ... )
    ⊥  $i_1 \leftarrow \Phi(i_0, i_3)$ 
    ⊥  $x \leftarrow i_1 * 17$ 
    ⊥  $j \leftarrow i_1$ 
    ⊥  $i_2 \leftarrow \dots$ 
    ...
    ⊥  $i_3 \leftarrow j$ 
```

Pessimistic
initializations

Leads to:

$$\begin{aligned} i_1 &\equiv 12 \wedge \perp \equiv \perp \\ x &\equiv \perp * 17 \equiv \perp \\ j &\equiv \perp \\ i_3 &\equiv \perp \end{aligned}$$

- This version of the algorithm is an *optimistic* formulation
- Initializes values to **TOP**
- Prior version used \perp (*implicit*)

Sparse Constant Propagation

Optimism

```

12    $i_0 \leftarrow 12$ 
    while ( ... )
      TOP  $i_1 \leftarrow \Phi(i_0, i_3)$ 
      TOP  $x \leftarrow i_1 * 17$ 
      TOP  $j \leftarrow i_1$ 
      TOP  $i_2 \leftarrow \dots$ 
      ...
      TOP  $i_3 \leftarrow j$ 

```

Optimistic initializations
 Leads to:
 $i_1 \equiv 12 \wedge \text{TOP} \equiv 12$
 $x \equiv 12 * 17 \equiv 204$
 $j \equiv 12$
 $i_3 \equiv 12$
 $i_1 \equiv 12 \wedge 12 \equiv 12$

- This version of the algorithm is an *optimistic* formulation
- Initializes values to **TOP**
- Prior version used \perp (*implicit*)

In general, optimism helps inside loops.

M.N. Wegman & F.K. Zadeck, Constant propagation with conditional branches, ACM TOPLAS, 13(2), April 1991, pages 181–210.

Sparse Conditional Constant Propagation

What happens when it propagates a value into a branch?

- ◆ TOP \Rightarrow we gain no knowledge.
- ◆ BOT \Rightarrow either path can execute.
- ◆ TRUE or FALSE \Rightarrow only one path can execute.

} But, the algorithm
does not use this ...

Working this into the algorithm.

- ◆ Use two worklists: **SSAWorkList** & **CFGWorkList**:
 - ◆ **SSAWorkList** determines values.
 - ◆ **CFGWorkList** governs reachability.
- ◆ Don't propagate into operation until its block is reachable.

Sparse Conditional Constant Propagation

```

SSAWorkList  $\leftarrow \emptyset$ 
CFGWorkList  $\leftarrow n_0$ 
 $\forall$  block b
    clear b's mark
     $\forall$  expression e in b
        Value(e)  $\leftarrow$  TOP

```

Initialization Step

To evaluate a branch

```

if arg is BOT then
    put both targets on CFGWorklist
else if arg is TRUE then
    put TRUE target on CFGWorkList
else if arg is FALSE then
    put FALSE target on CFGWorkList

```

To evaluate a jump
place its target on CFGWorkList

```

while ((CFGWorkList  $\cup$  SSAWorkList)  $\neq \emptyset$ )
    while(CFGWorkList  $\neq \emptyset$ )
        remove b from CFGWorkList
        mark b
        evaluate each  $\Phi$ -function in b
        evaluate each op in b, in order

    while(SSAWorkList  $\neq \emptyset$ )
        remove s =  $\langle u, v \rangle$  from SSAWorkList
        let o be the operation that contains v
        t  $\leftarrow$  result of evaluating o
        if t  $\neq$  Value(o) then
            Value(o)  $\leftarrow$  t
             $\forall$  SSA edge  $\langle o, x \rangle$ 
                if x is marked, then
                    add  $\langle o, x \rangle$  to SSAWorkList

```

Propagation Step

Sparse Conditional Constant Propagation

There are some subtle points:

- ◆ Branch conditions should not be **TOP** when evaluated.
 - ◆ Indicates an upwards-exposed use. (*no initial value - undefined*)
 - ◆ Hard to envision compiler producing such code.
- ◆ Initialize all operations to **TOP**.
 - ◆ Block processing will fill in the non-top initial values.
 - ◆ Unreachable paths contribute **TOP** to Φ -functions.
- ◆ Code shows CFG edges first, then SSA edges.
 - ◆ Can intermix them in arbitrary order. (*correctness*)
 - ◆ Taking CFG edges first may help with speed. (*minor effect*)

Sparse Conditional Constant Propagation

More subtle points:

- ◆ $\text{TOP} * \text{BOT} \rightarrow \text{TOP}$
 - ◆ If TOP becomes 0 , then $0 * \text{BOT} \rightarrow 0$.
 - ◆ This prevents non-monotonic behavior for the result value.
 - ◆ Uses of the result value might go irretrievably to 0 .
 - ◆ Similar effects with any operation that has a “zero”.
- ◆ Some values reveal simplifications, rather than constants
 - ◆ $\text{BOT} * c_i \rightarrow \text{BOT}$, but might turn into shifts & adds ($c_i = 2, \text{BOT} \geq 0$)
 - ◆ $\text{BOT}^{**2} \rightarrow \text{BOT} * \text{BOT}$.
(vs. series or call to library)
- ◆ $\text{cbr } \text{TRUE} \rightarrow L_1, L_2$ becomes $\text{br} \rightarrow L_1$
 - ◆ Method discovers this; it must rewrite the code, too!

Sparse Conditional Constant Propagation

Unreachable Code

```
i1←17
if (i1>0) then
    j1←10
else
    j2←20
j3←Φ(j1, j2)
k←j3*17
```

Optimism

- Initialization to **TOP** is still important.
- Unreachable code keeps **TOP**.
- \wedge with **TOP** has desired result.

Sparse Conditional Constant Propagation

Unreachable Code

```
17  i1←17
    if (i1>0) then
10    j1←10
    else
20    j2←20
⊥   j3←Φ(j1, j2)
⊥   k←j3*17
```

All paths execute

Optimism

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Sparse Conditional Constant Propagation

Unreachable Code

```
17  i←17
    if (i>0) then
TOP   j1←10
    else
TOP   j2←20
TOP   j3←Φ(j1, j2)
170  k←j3*17
```

With SCC
marking
blocks

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Sparse Conditional Constant Propagation

Unreachable Code

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    if (i>0) then
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```

With SCC
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Optimism

- Initialization to **TOP** is still important.
- Unreachable code keeps **TOP**.
- \wedge with **TOP** has desired result.

Cannot get this any other way:

- DEAD code cannot test (**i** > 0).
- DEAD marks **j₂** as useful.

Sparse Conditional Constant Propagation

Unreachable Code

```

17  i←17
    if (i>0) then
10   j1←10
    else
TOP  j2←20
10   j3←Φ(j1, j2)
170  k←j3*17

```

With SCC
marking
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Optimism

- Initialization to **TOP** is still important.
- Unreachable code keeps **TOP**.
- \wedge with **TOP** has desired result.

In general, combining two optimizations can lead to answers that cannot be produced by any combination of running them separately.

This algorithm is one example of that general principle.

Combining register allocation & instruction scheduling is another ...

Using SSA Form for Optimizations

In general, using SSA conversion leads to:

- ◆ Cleaner formulations.
- ◆ Better results.
- ◆ Faster algorithms.

We've seen two SSA-based algorithms.

- ◆ Dead-code elimination.
- ◆ Sparse conditional constant propagation.