

# Dead Code Elimination & Constant Propagation on SSA form

This lecture is primarily based on Konstantinos Sagonas set of slides  
(Advanced Compiler Techniques, (2AD518)  
at Uppsala University, January–February 2004).

Used with kind permission.  
(In turn based on Keith Cooper's slides)

# Dead Code Elimination Using SSA

## Dead code elimination

- ◆ Conceptually similar to mark-sweep garbage collection:
  - ◆ Mark *useful* operations.
  - ◆ Everything not marked is useless.
- ◆ Need an efficient way to find and to mark useful operations.
  - ◆ Start with critical operations.
  - ◆ Work back up SSA edges to find their antecedents.
- ◆ Operations defined as critical:
  - ◆ I/O statements,
  - ◆ linkage code (*entry & exit blocks*),
  - ◆ return values,
  - ◆ calls to other procedures.

Algorithm will use post-dominators & reverse dominance frontiers.

# Dead Code Elimination Using SSA

## Mark

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  if i is critical then
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while (Worklist ≠ Ø)
  remove i from WorkList
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for each b ∈ RDF(block(i))
  mark the block-ending
  branch in b
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```

## Sweep

```

for each op i
  if i is not marked then
    if i is a branch then
      rewrite with a jump to
      i's nearest useful
      post-dominator
    if i is not a jump then
      delete i

```

## Notes:

- Eliminates some branches.
- Reconnects dead branches to the remaining live code.
- Find useful post-dominator by walking post-dominator tree.
  - > Entry & exit nodes are useful

# Dead Code Elimination Using SSA

## Handling Branches

- ◆ When is a branch useful?
  - ◆ When another useful operation depends on its existence

In the CFG,  $j$  is control dependent on  $i$  if

1.  $\exists$  a non-null path  $p$  from  $i$  to  $j$  such that  $j$  post-dominates every node on  $p$  after  $i$
2.  $j$  does not strictly post-dominate  $i$

- ◆  $j$  control dependent on  $i \Rightarrow$  one path from  $i$  leads to  $j$ , one doesn't
- ◆ This is the reverse dominance frontier of  $j$  ( $RDF(j)$ )

Algorithm uses  $RDF(n)$  to mark branches as live

# Dead Code Elimination Using SSA

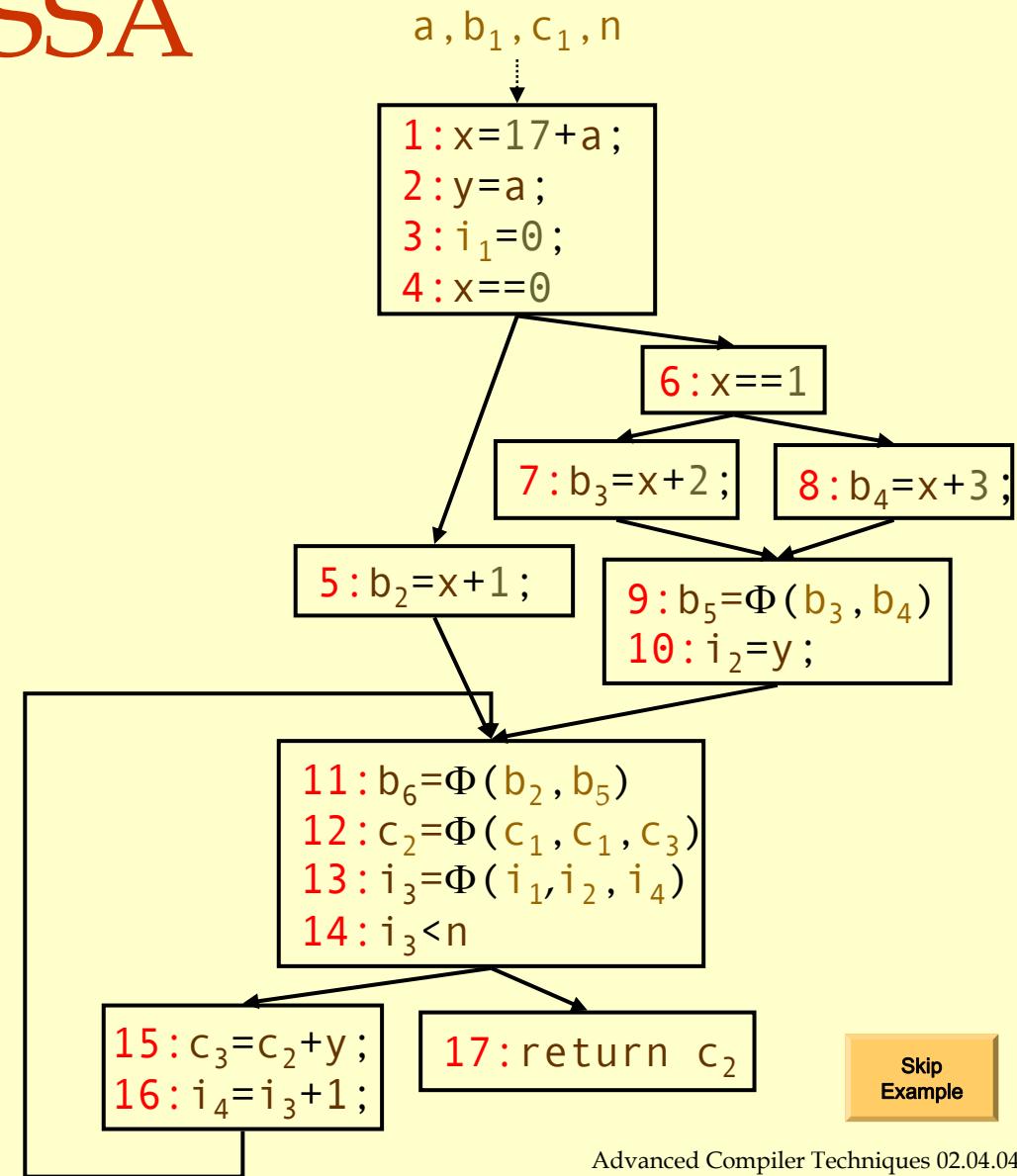
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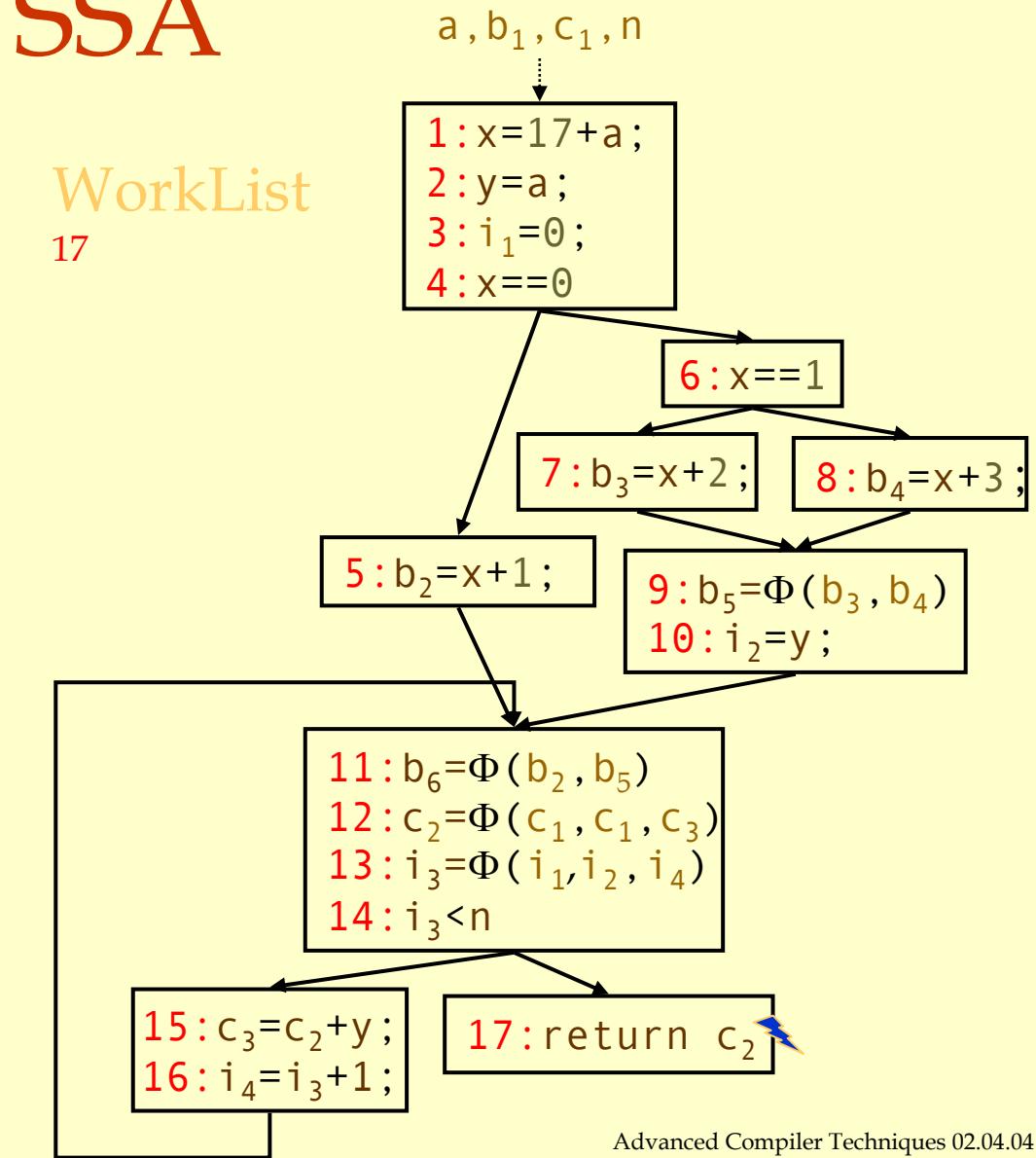
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## WorkList

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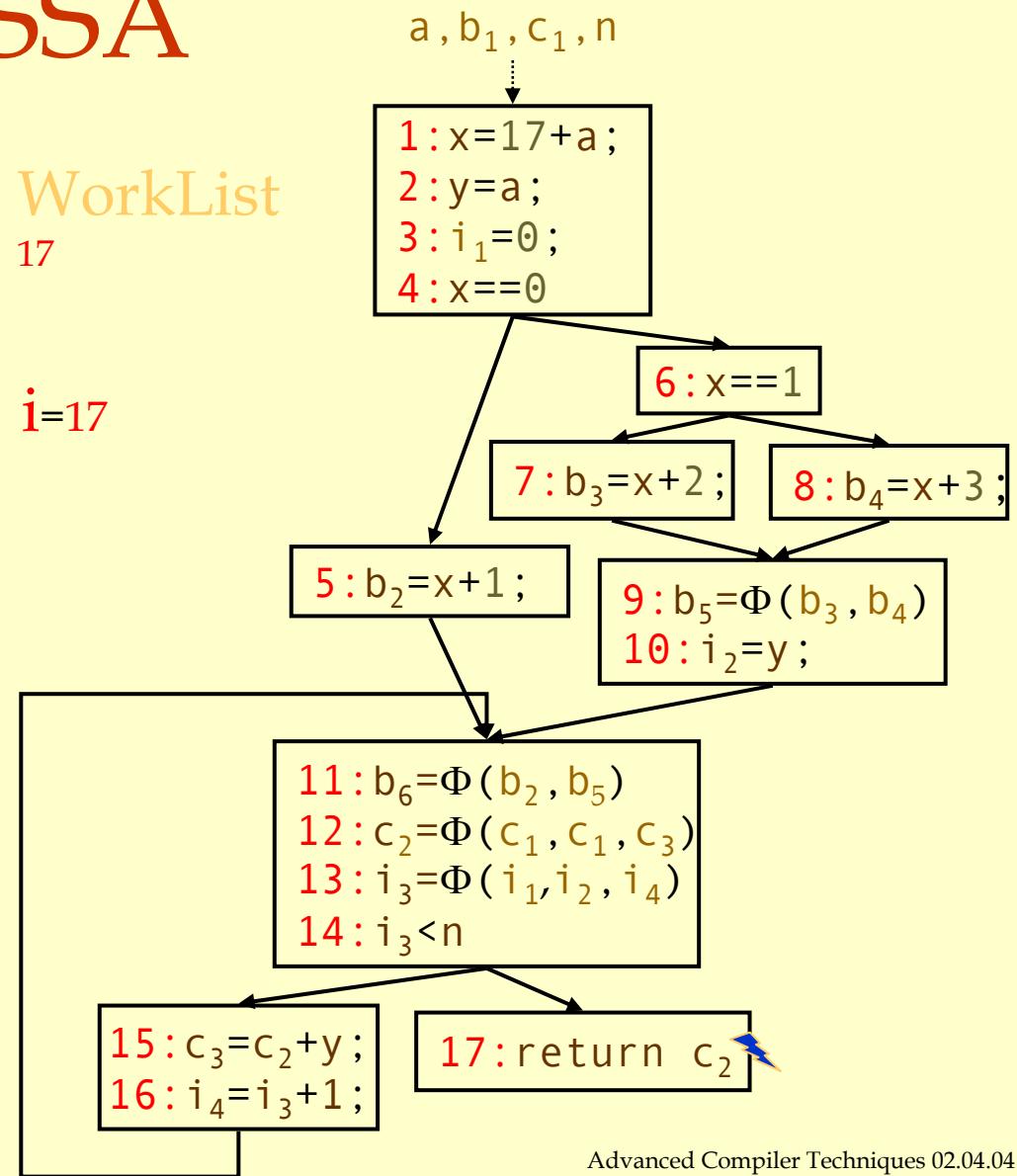
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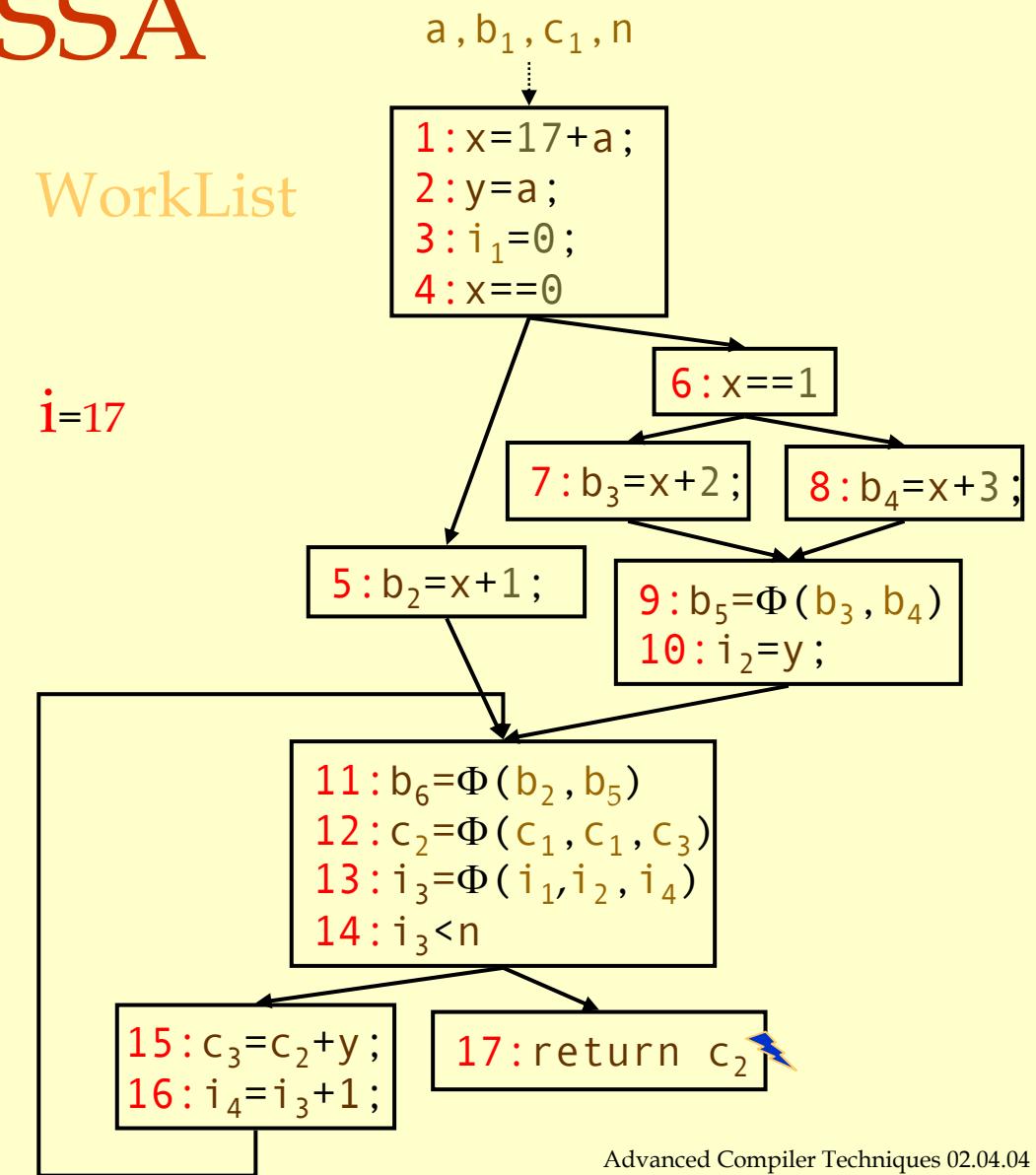


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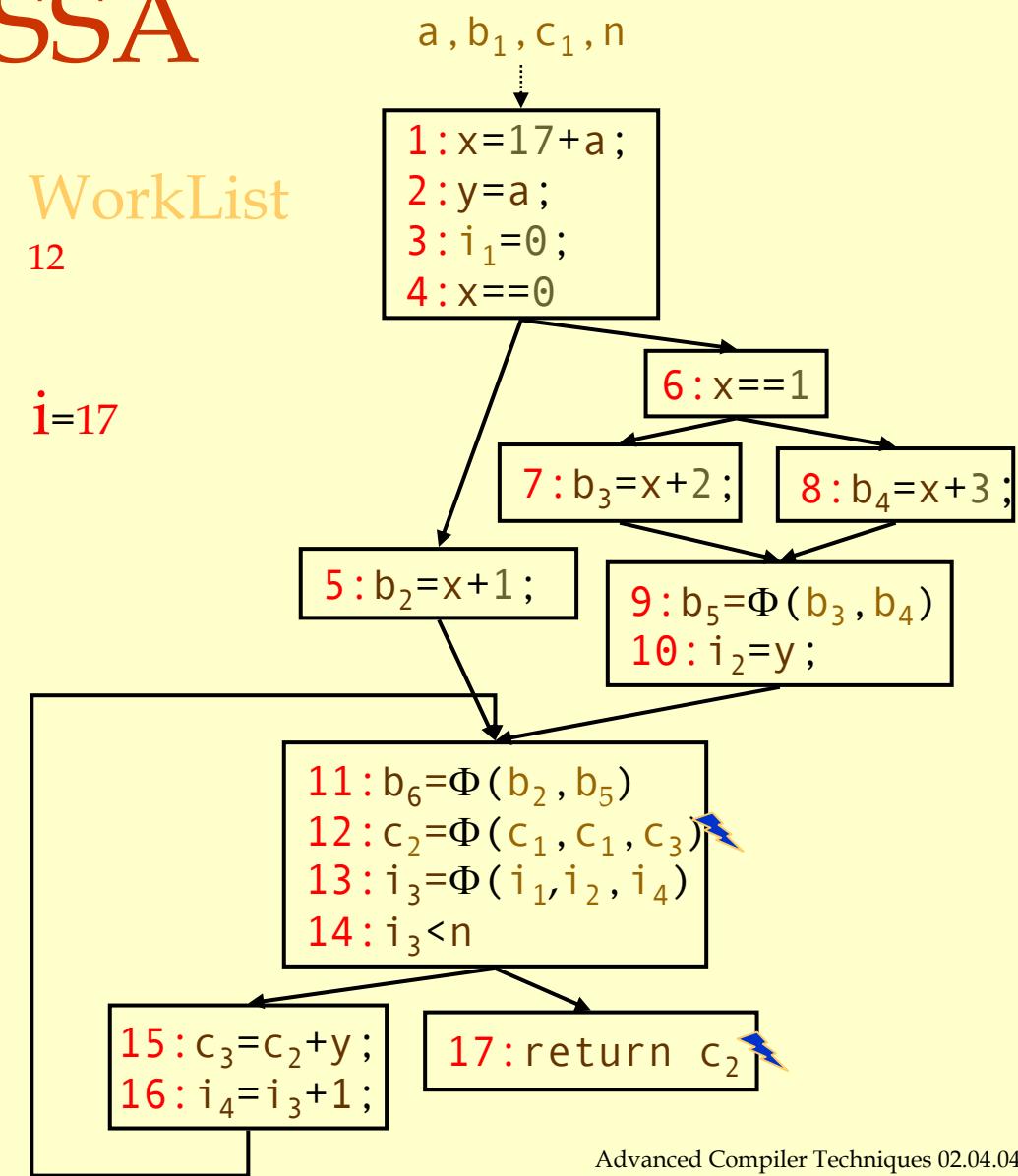


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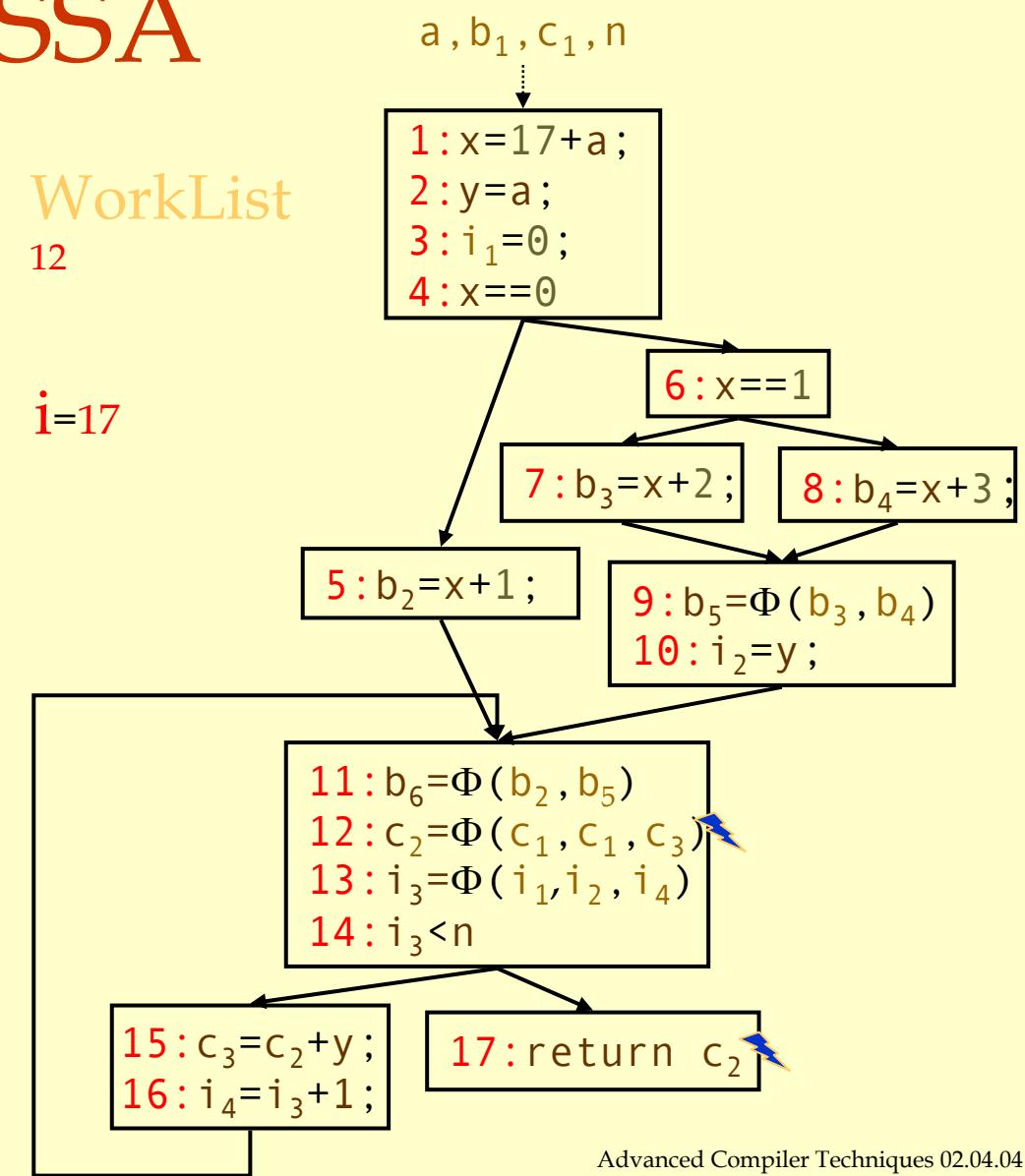


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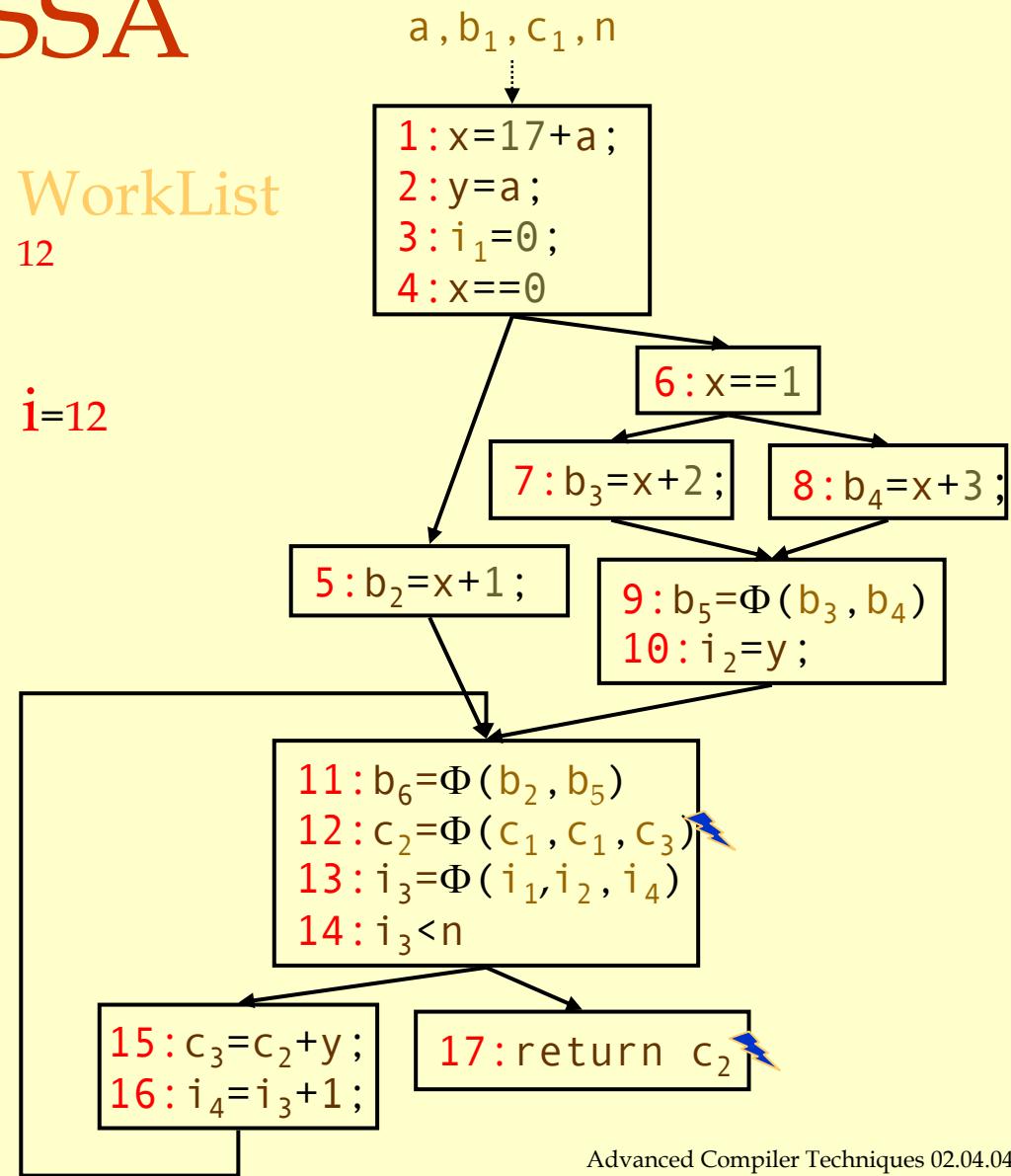


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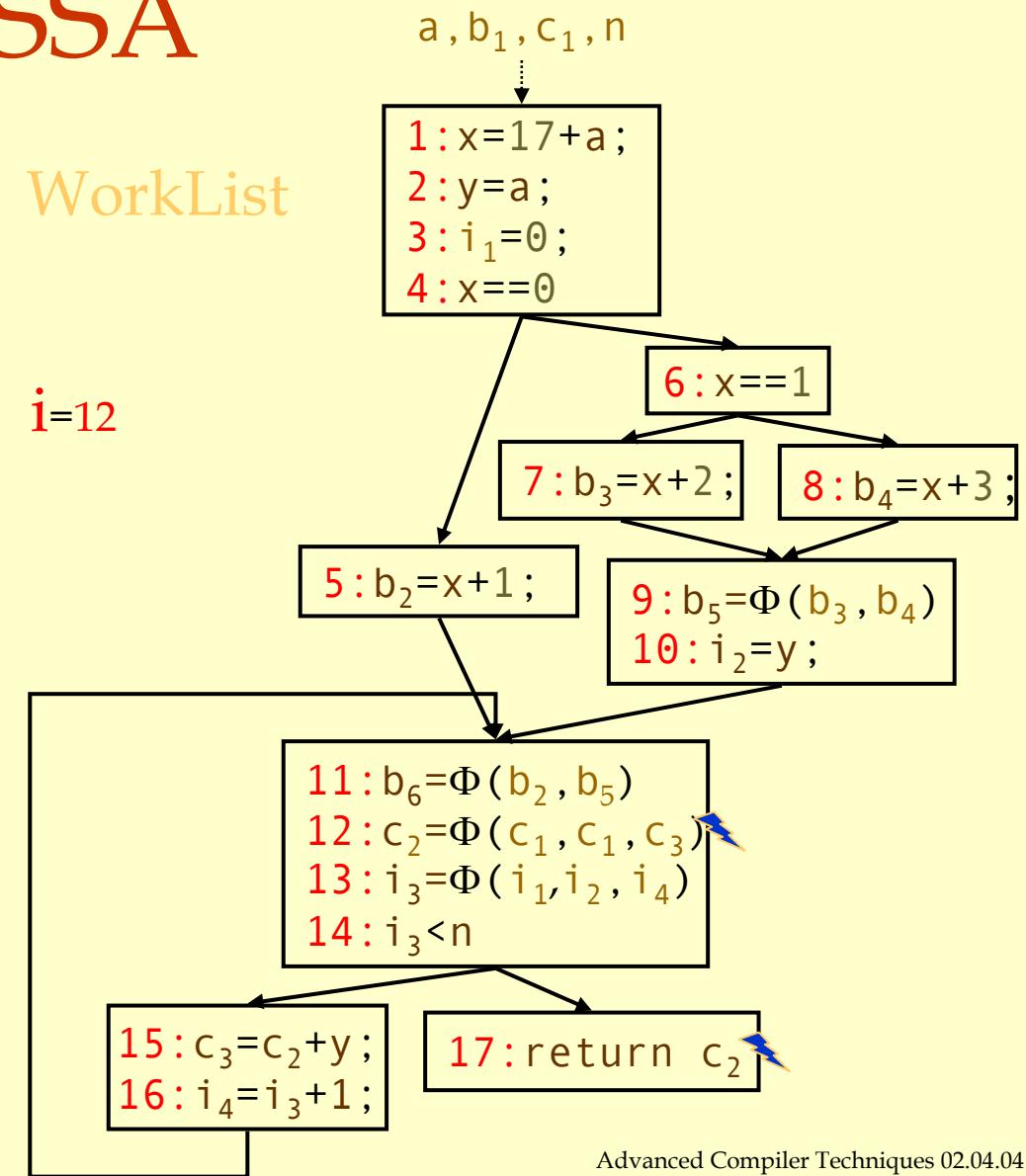


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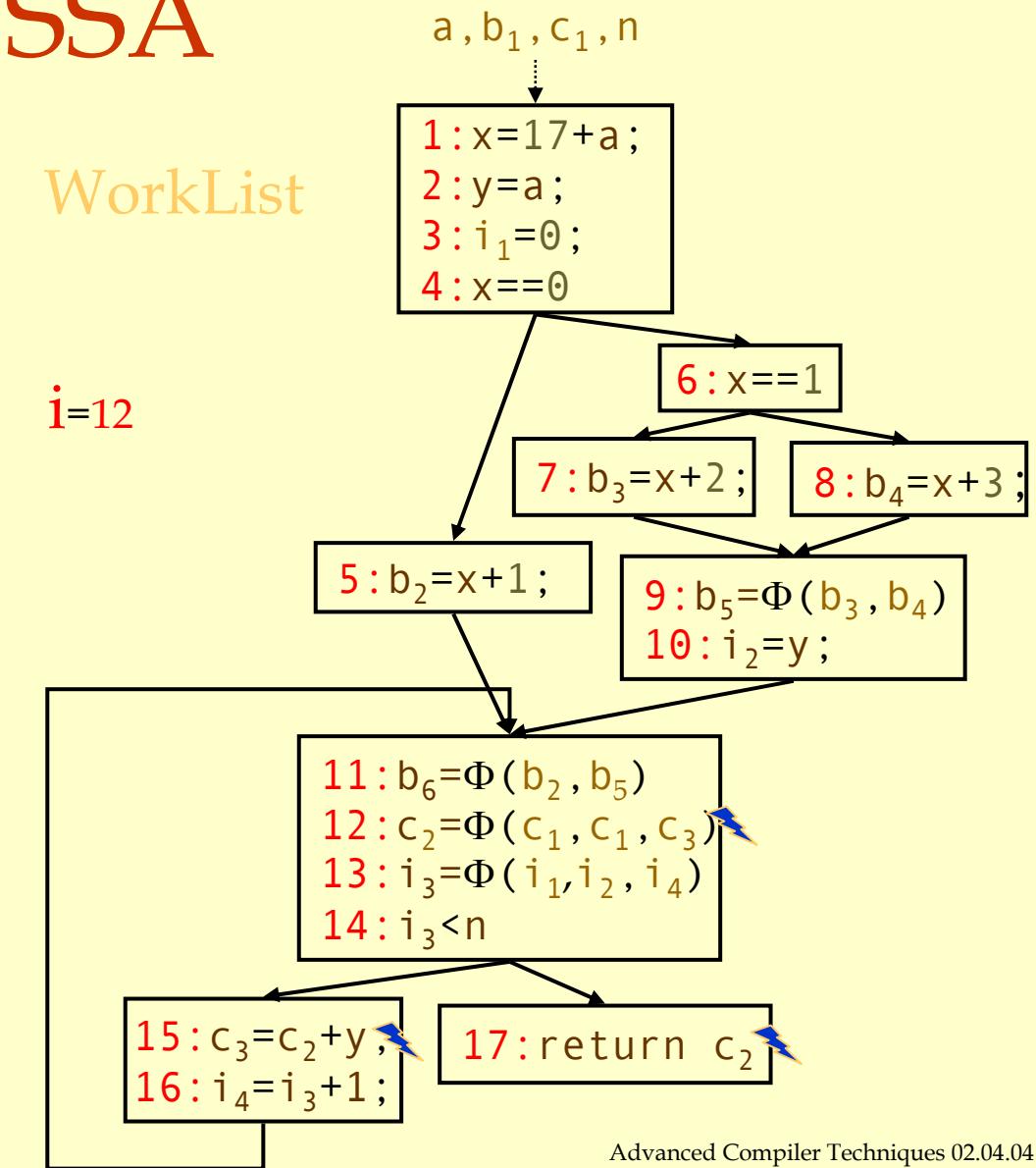


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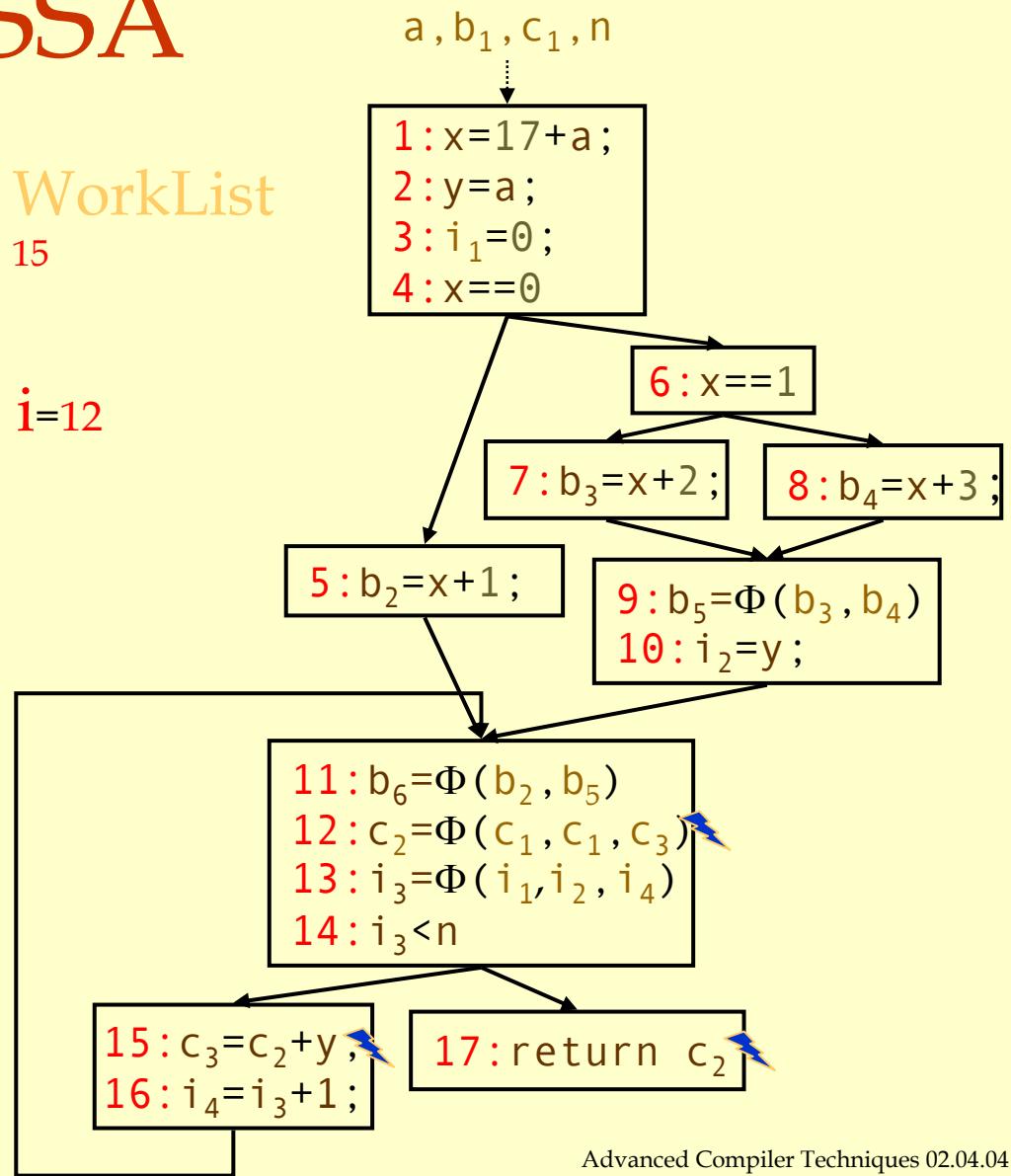
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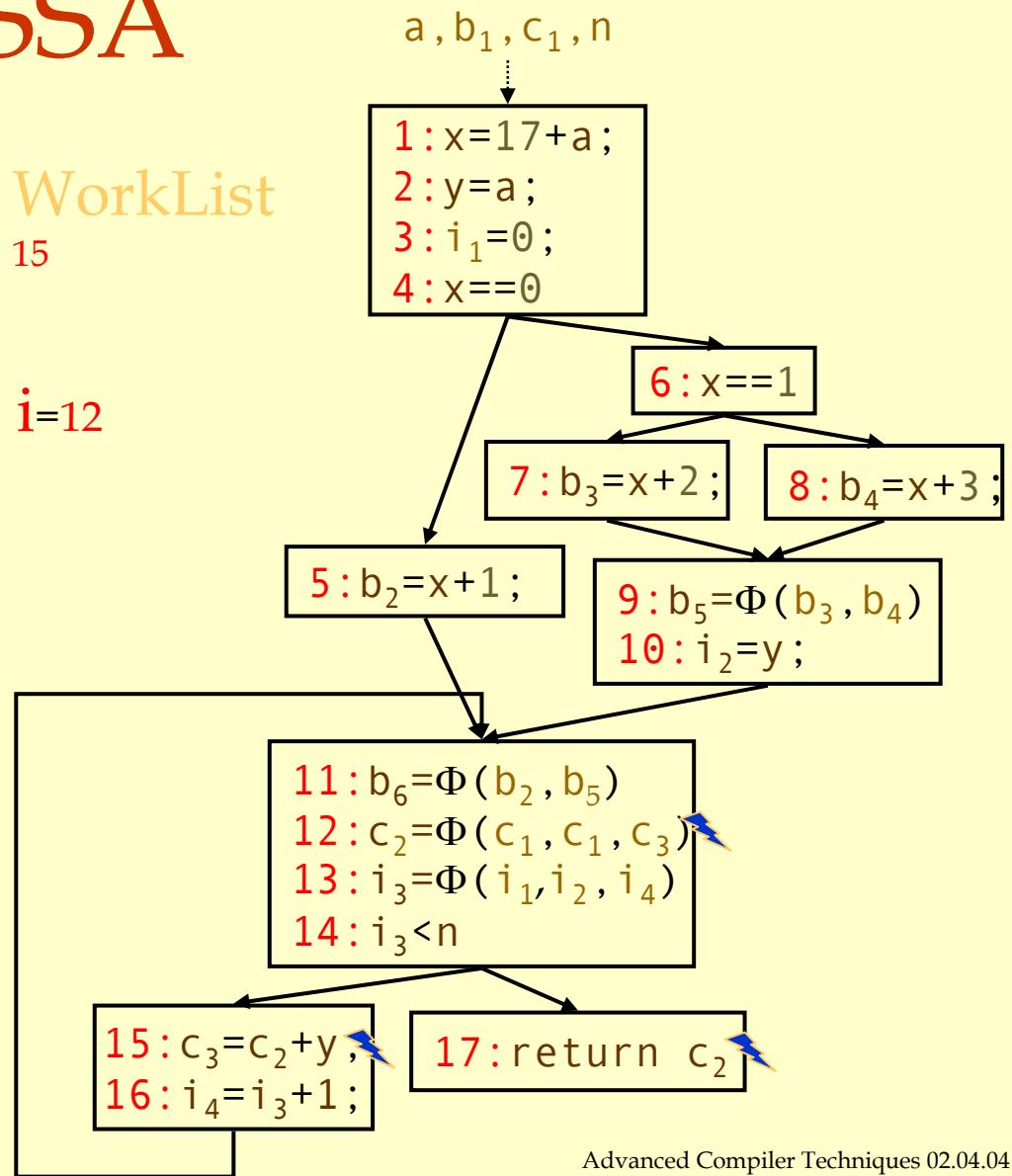
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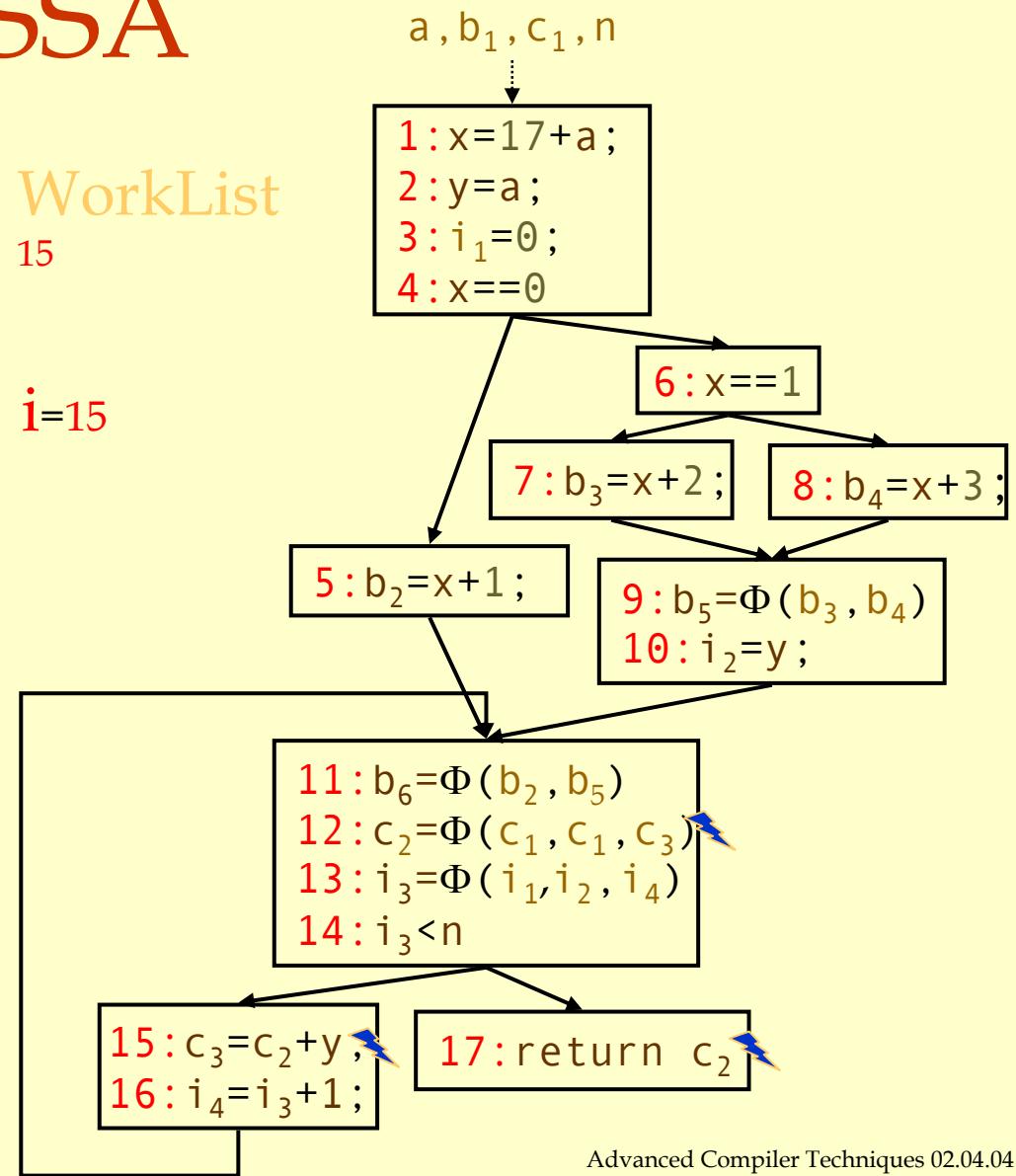
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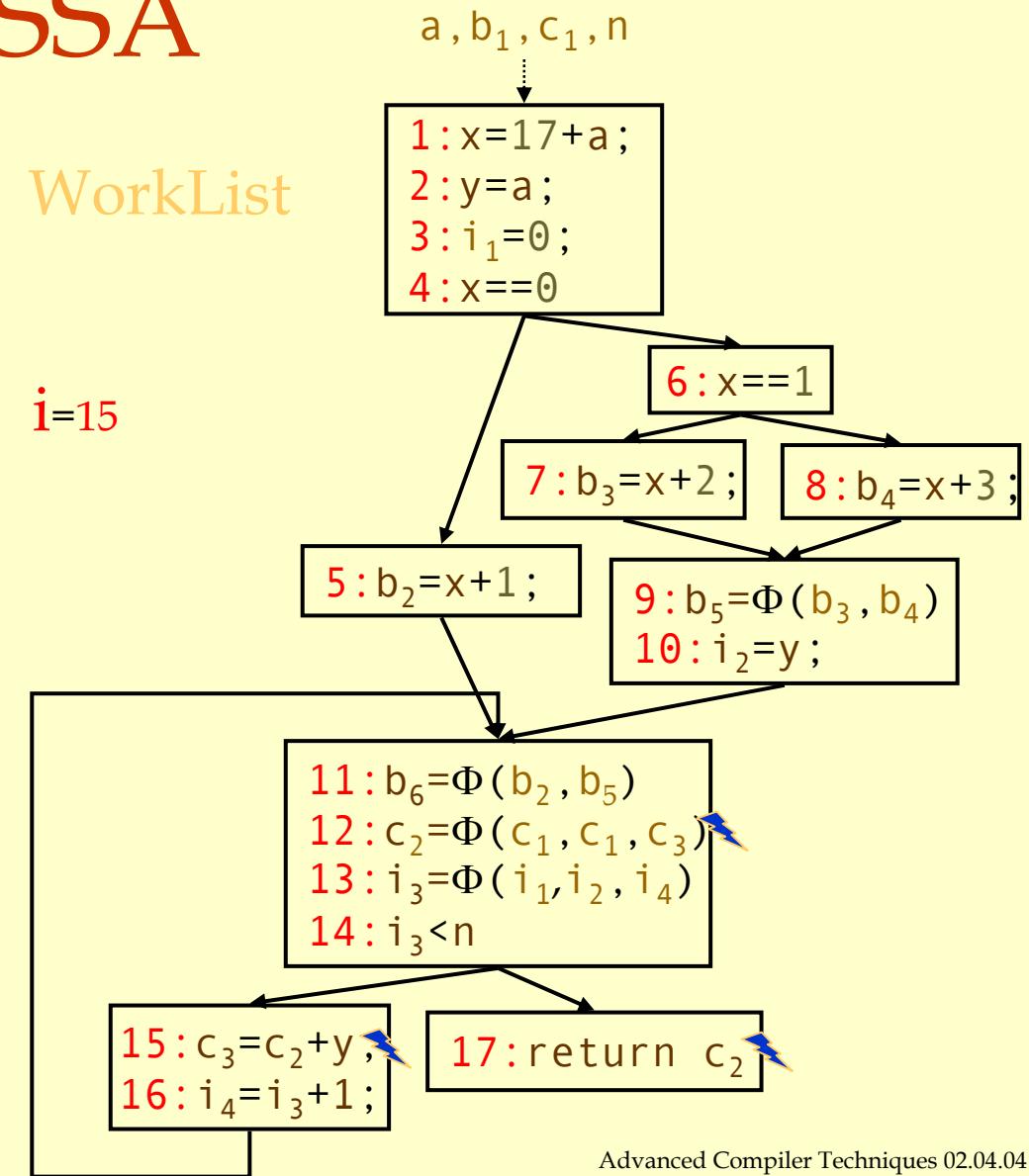


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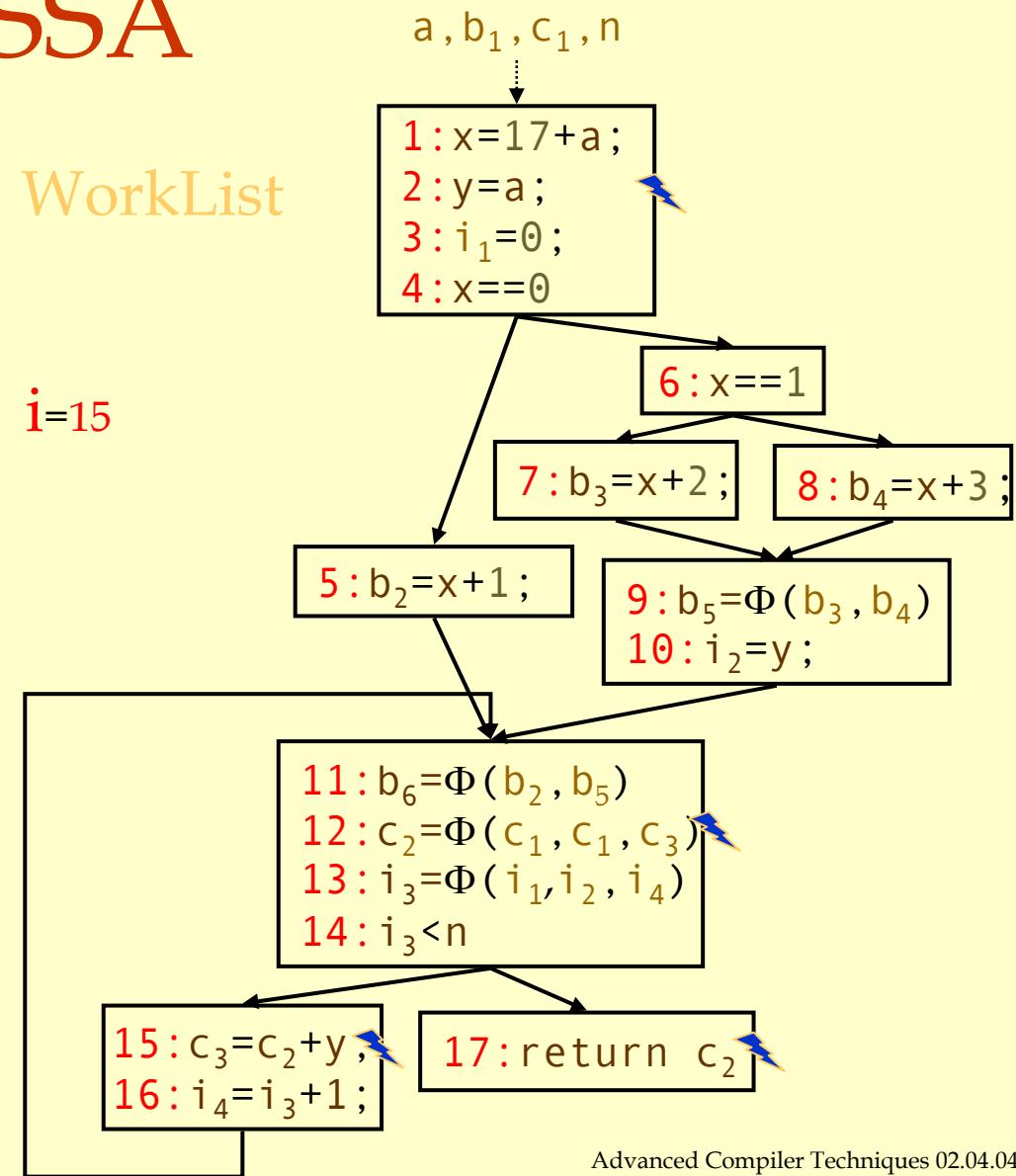


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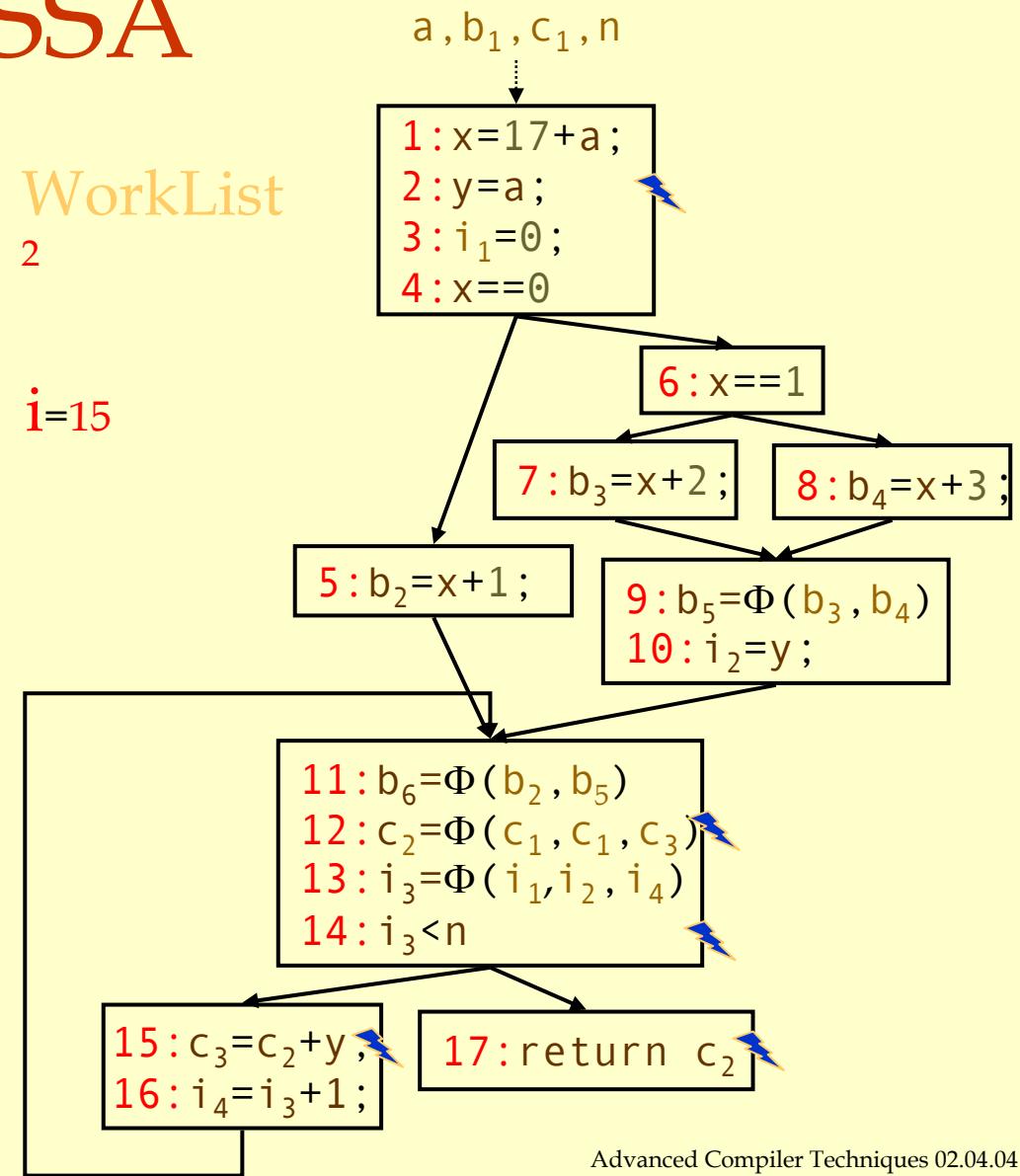
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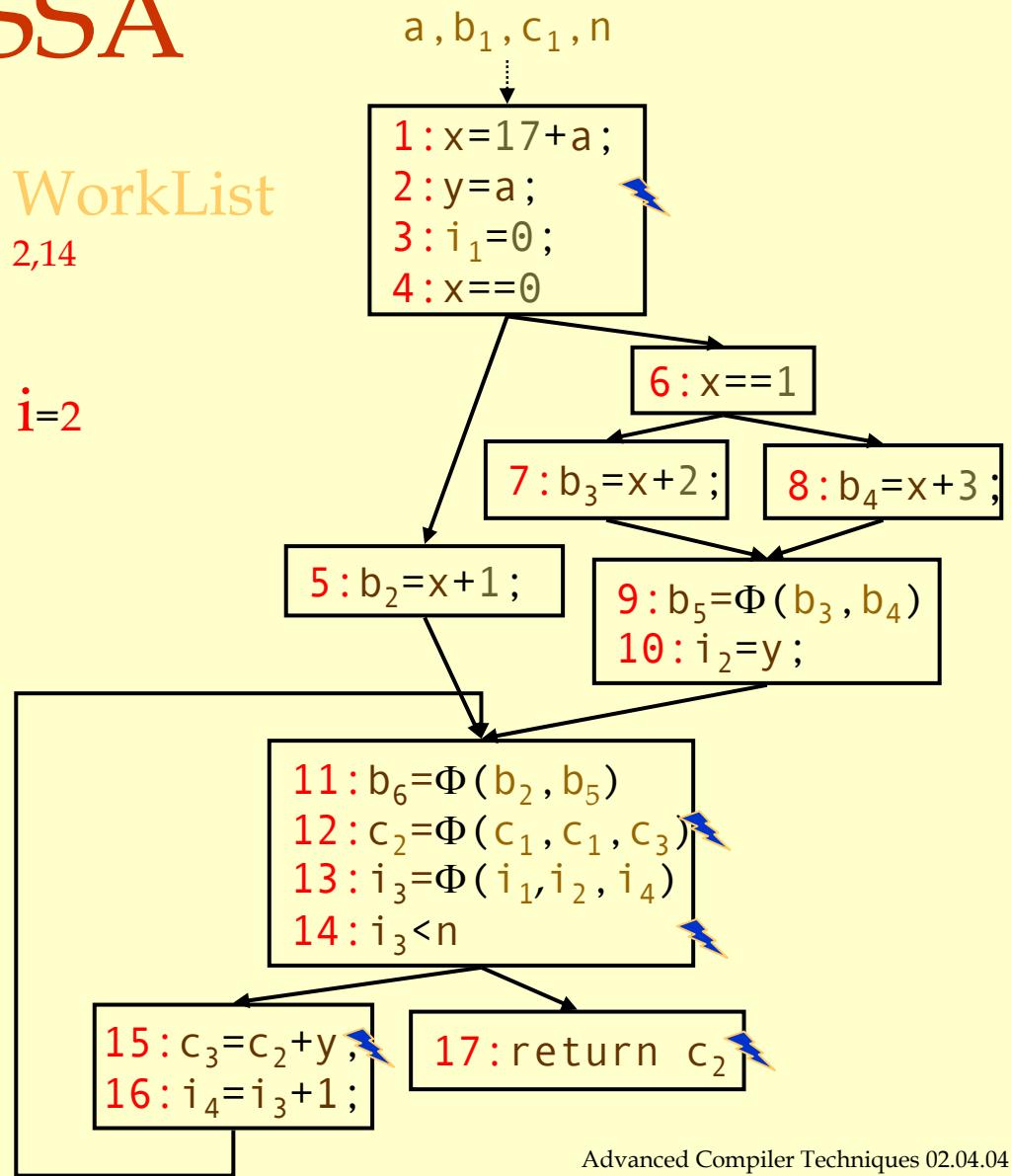


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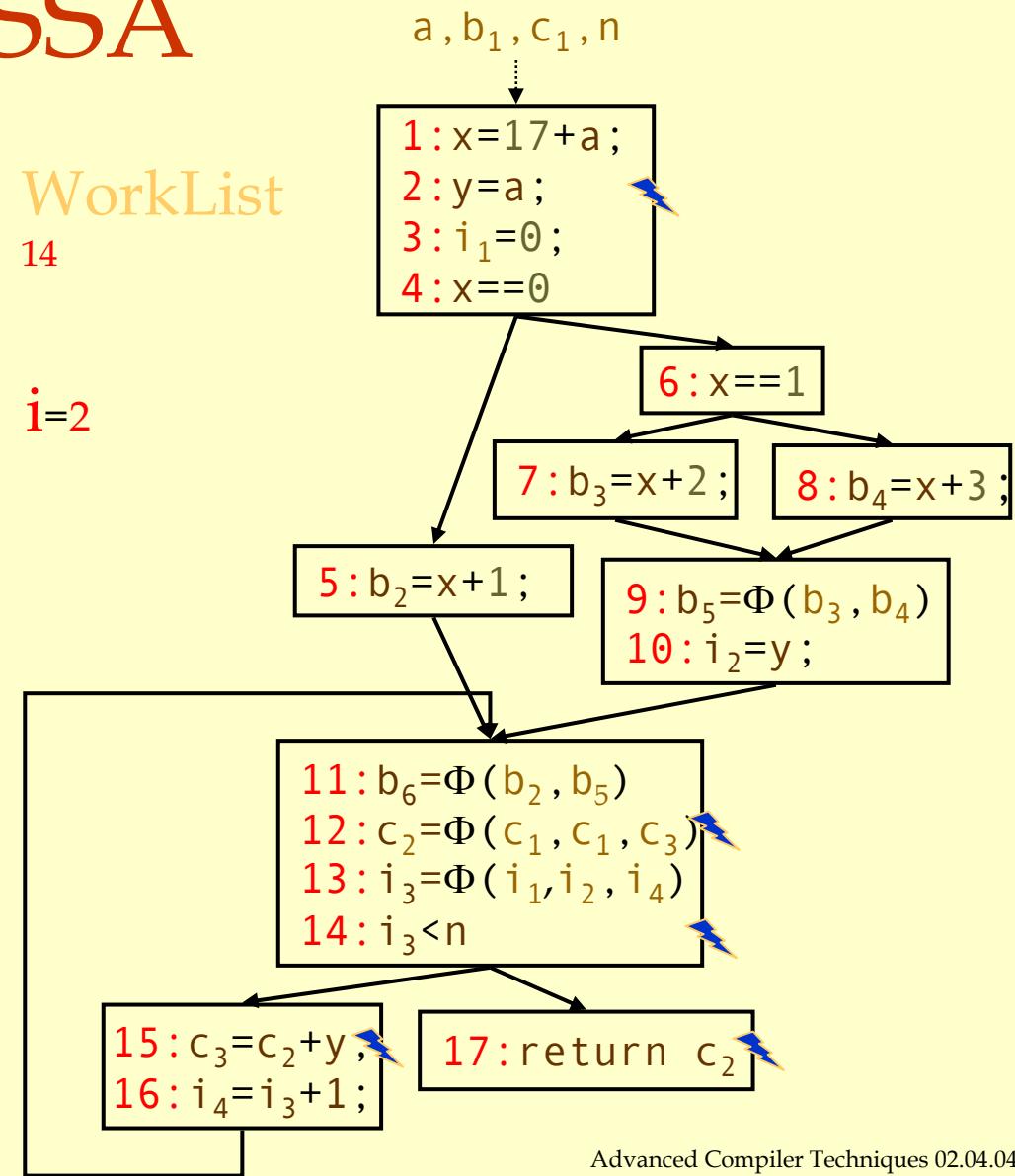


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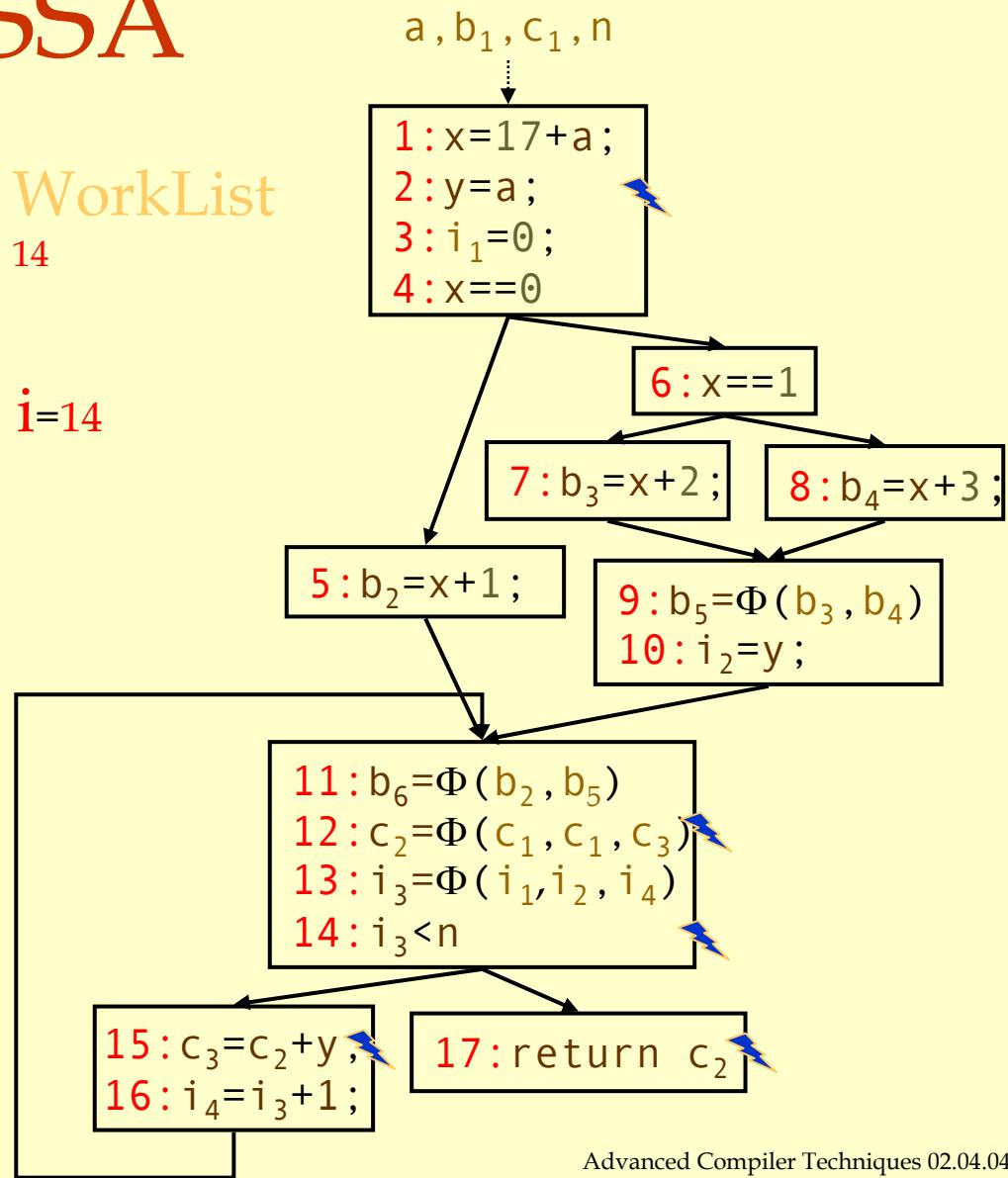


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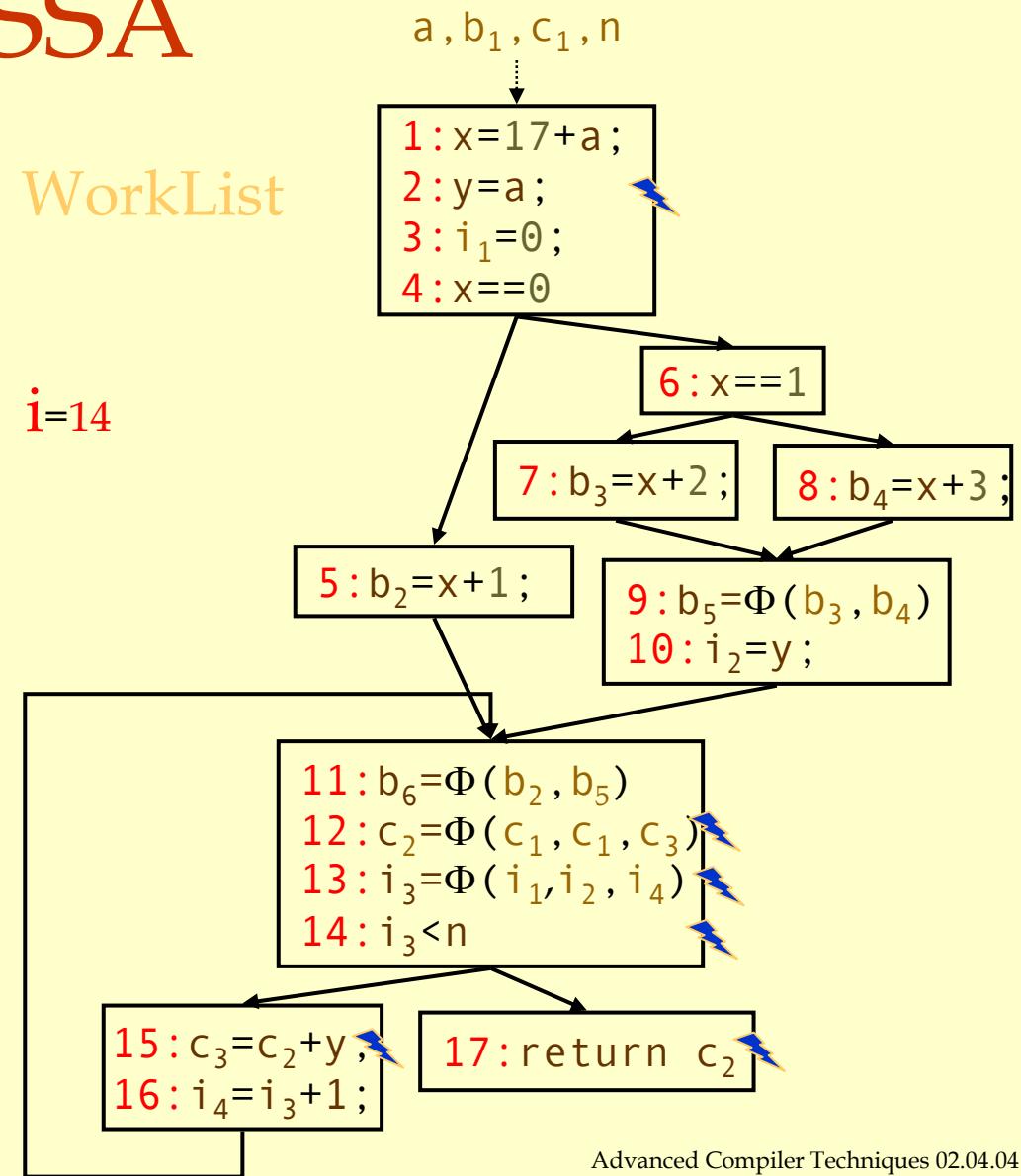


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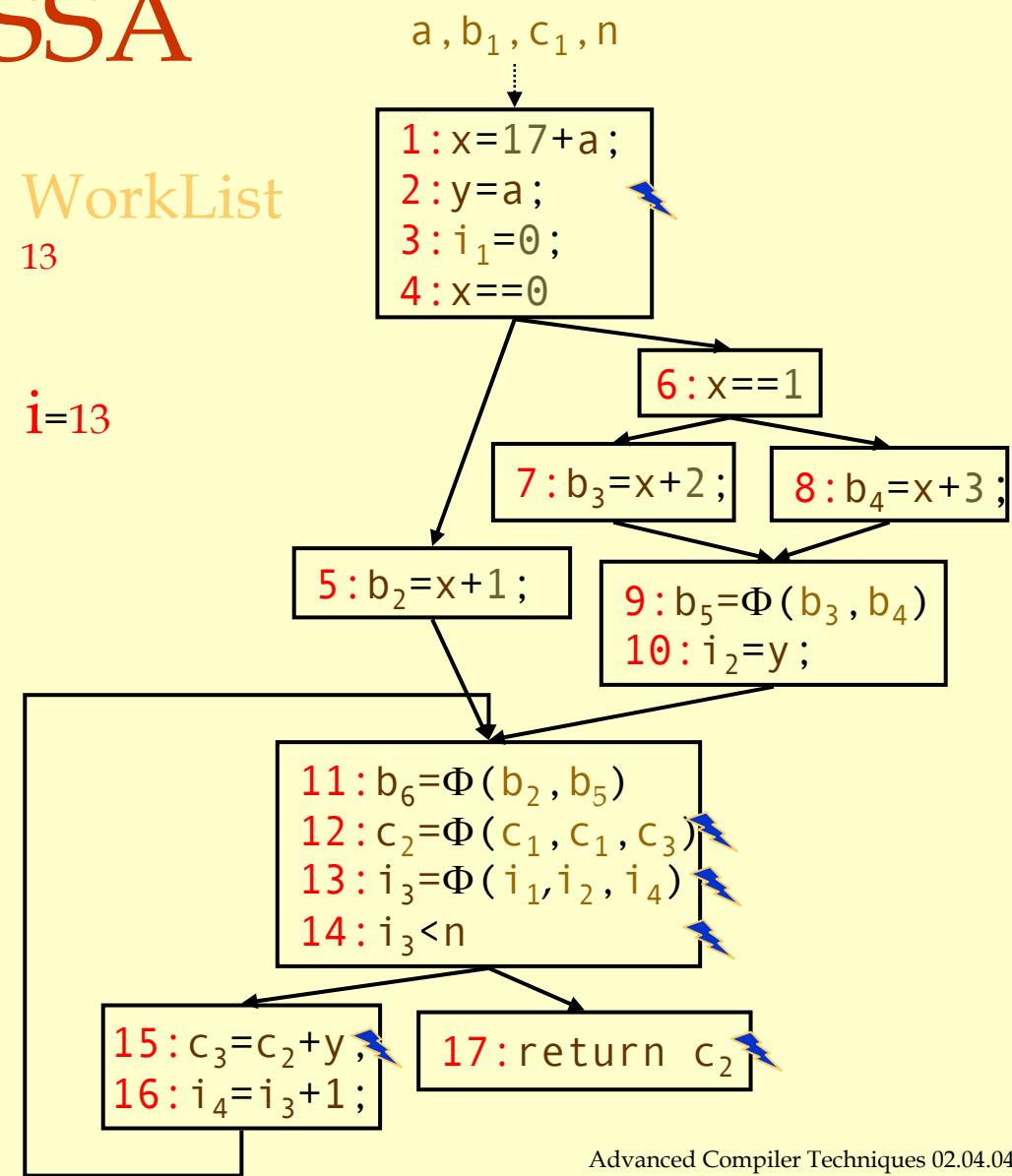


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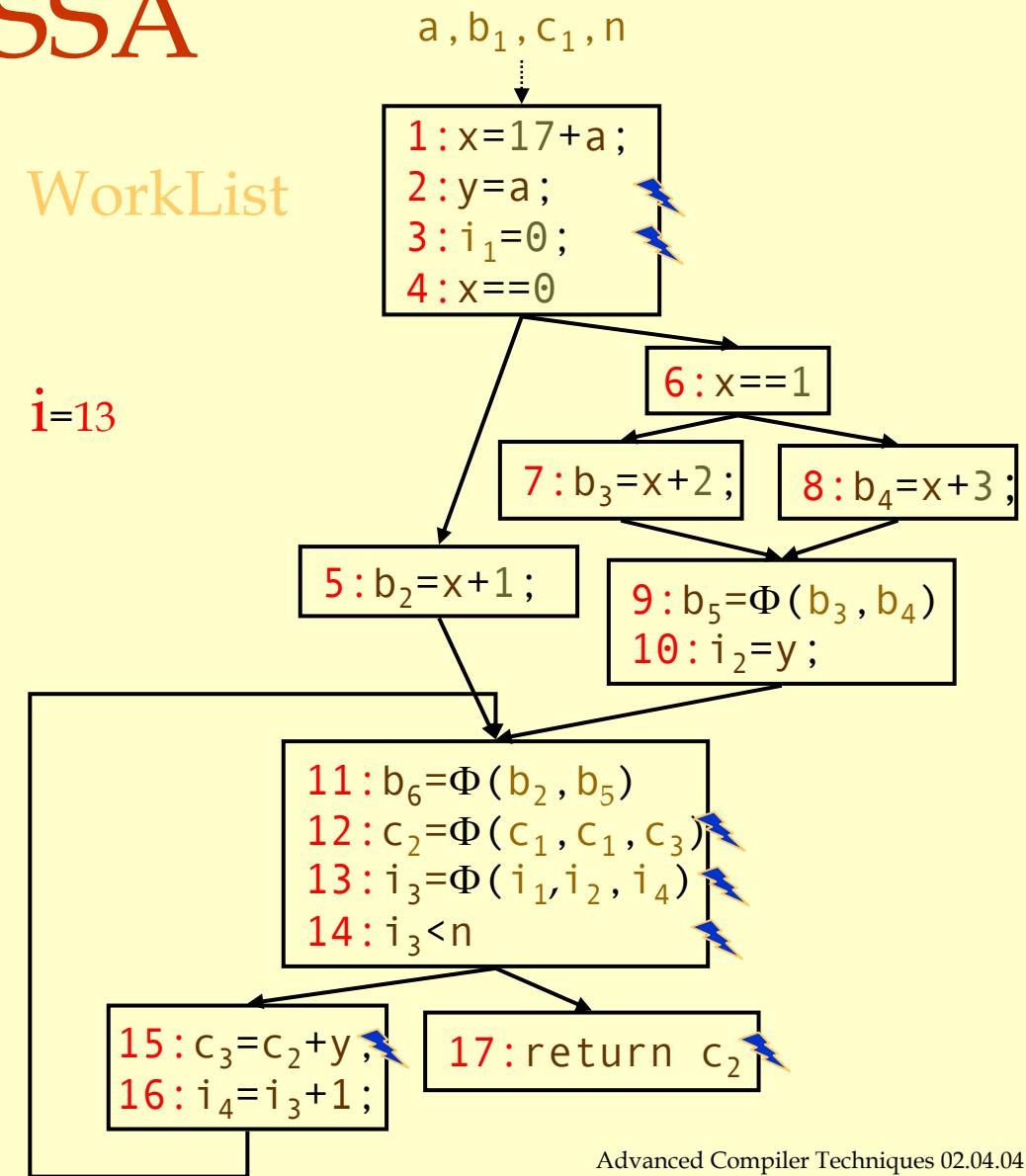


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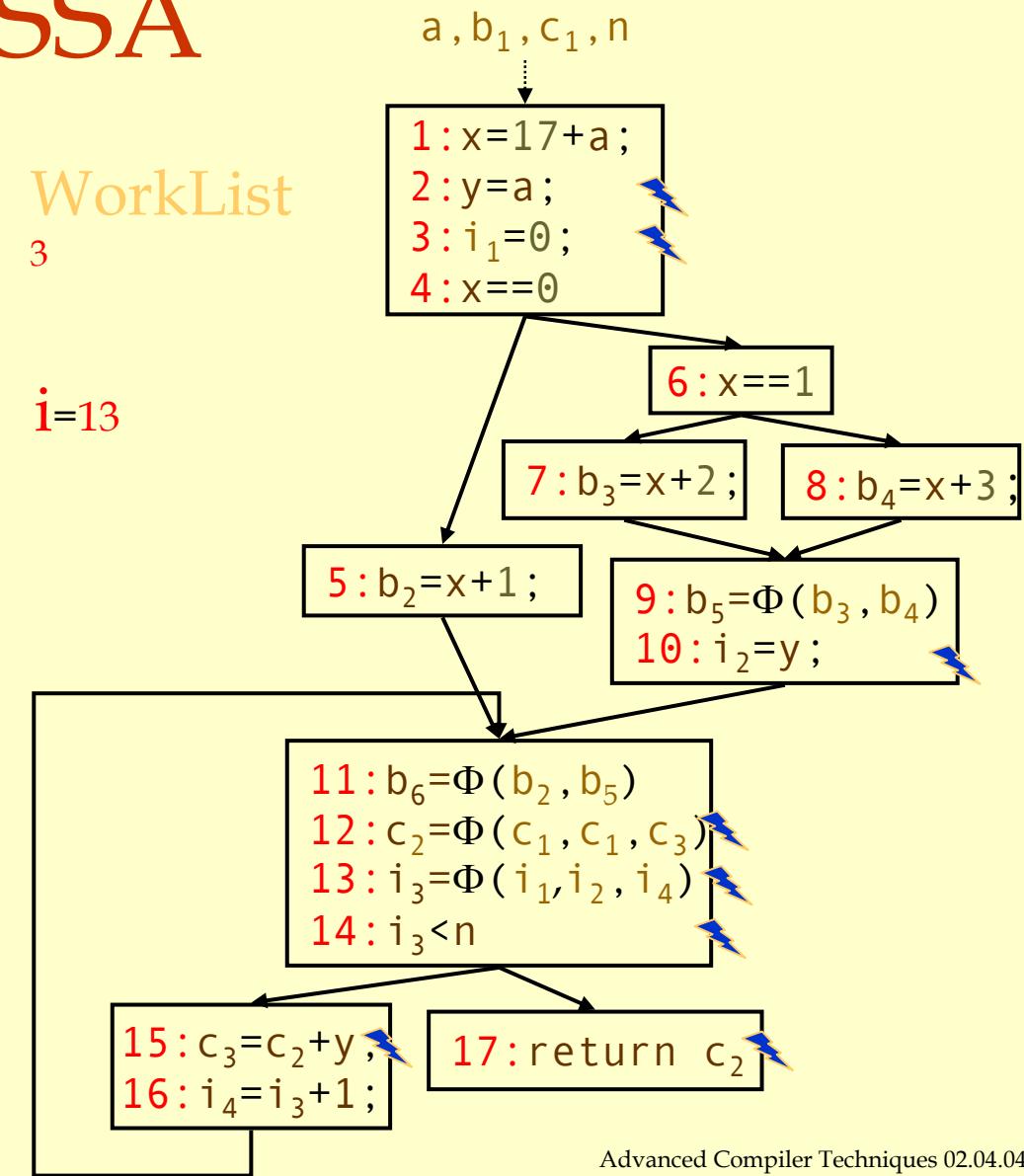


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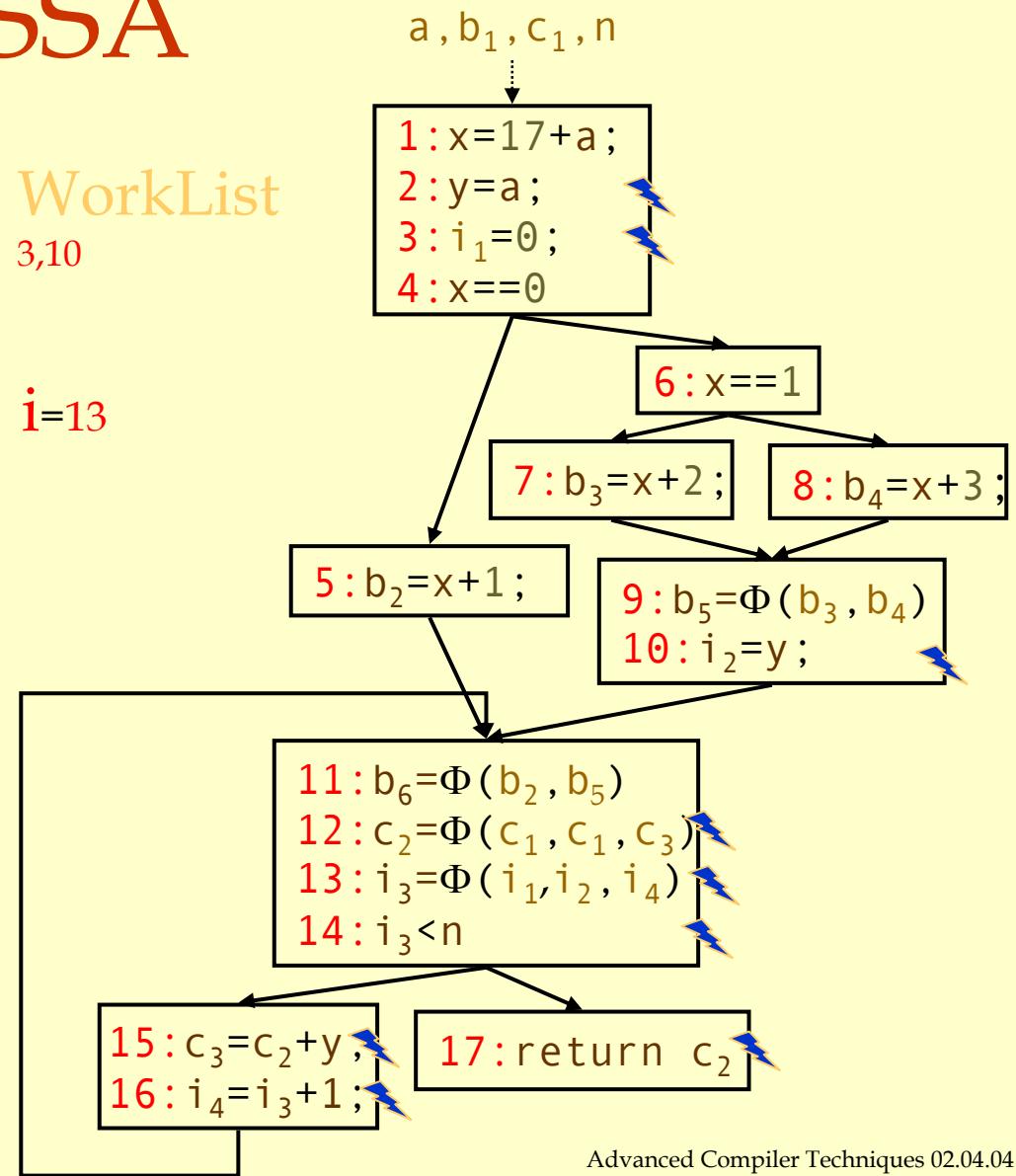


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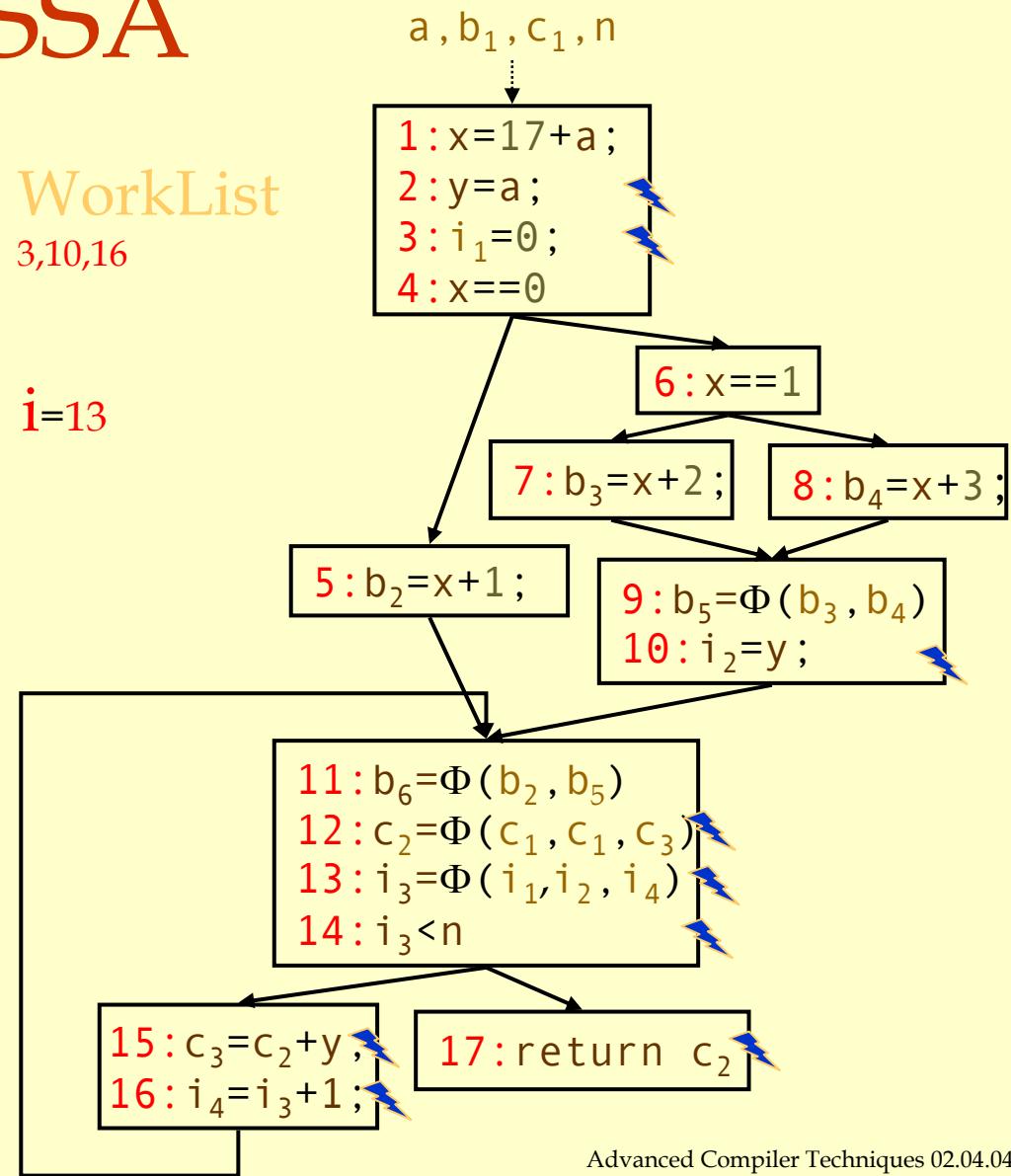


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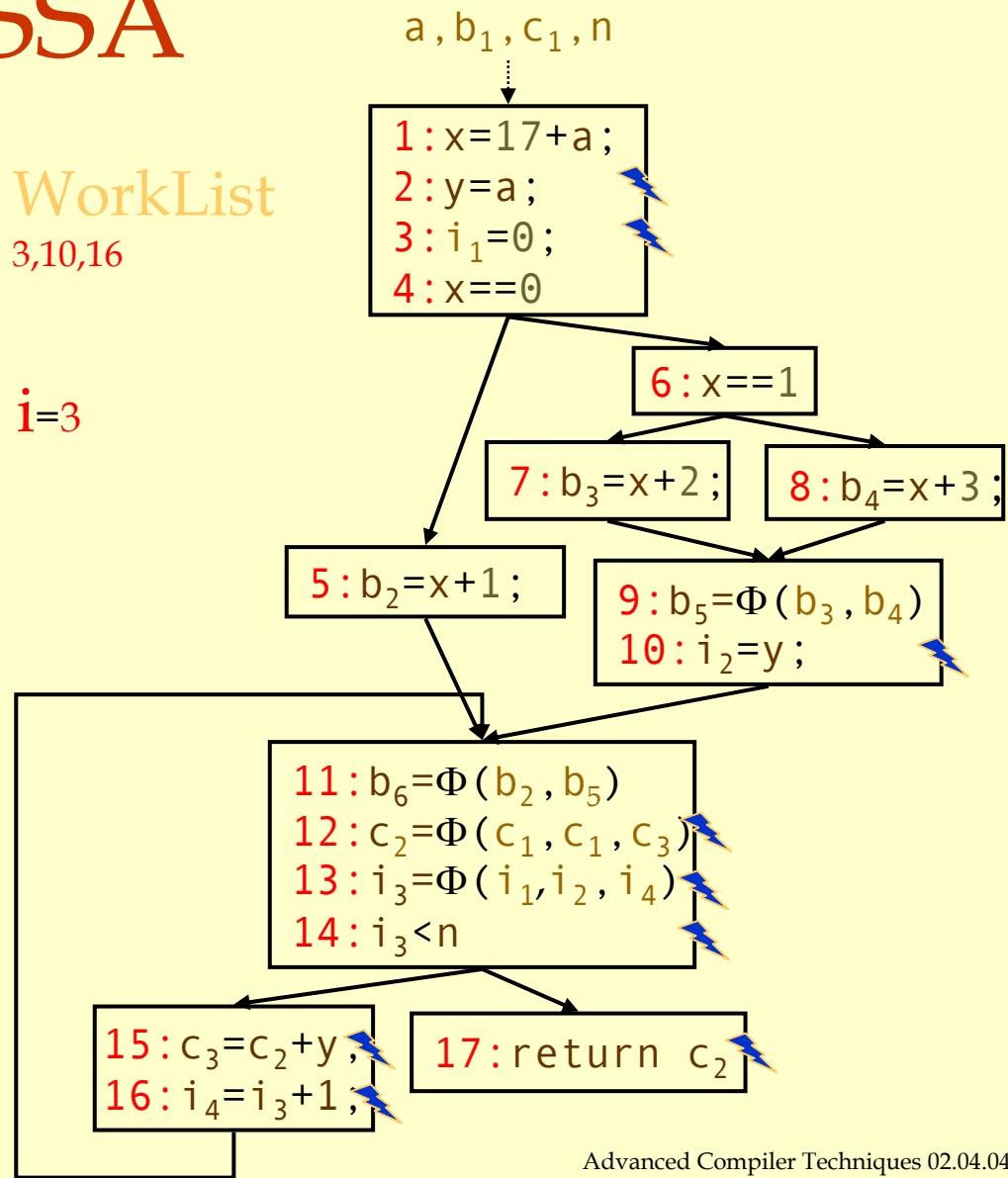


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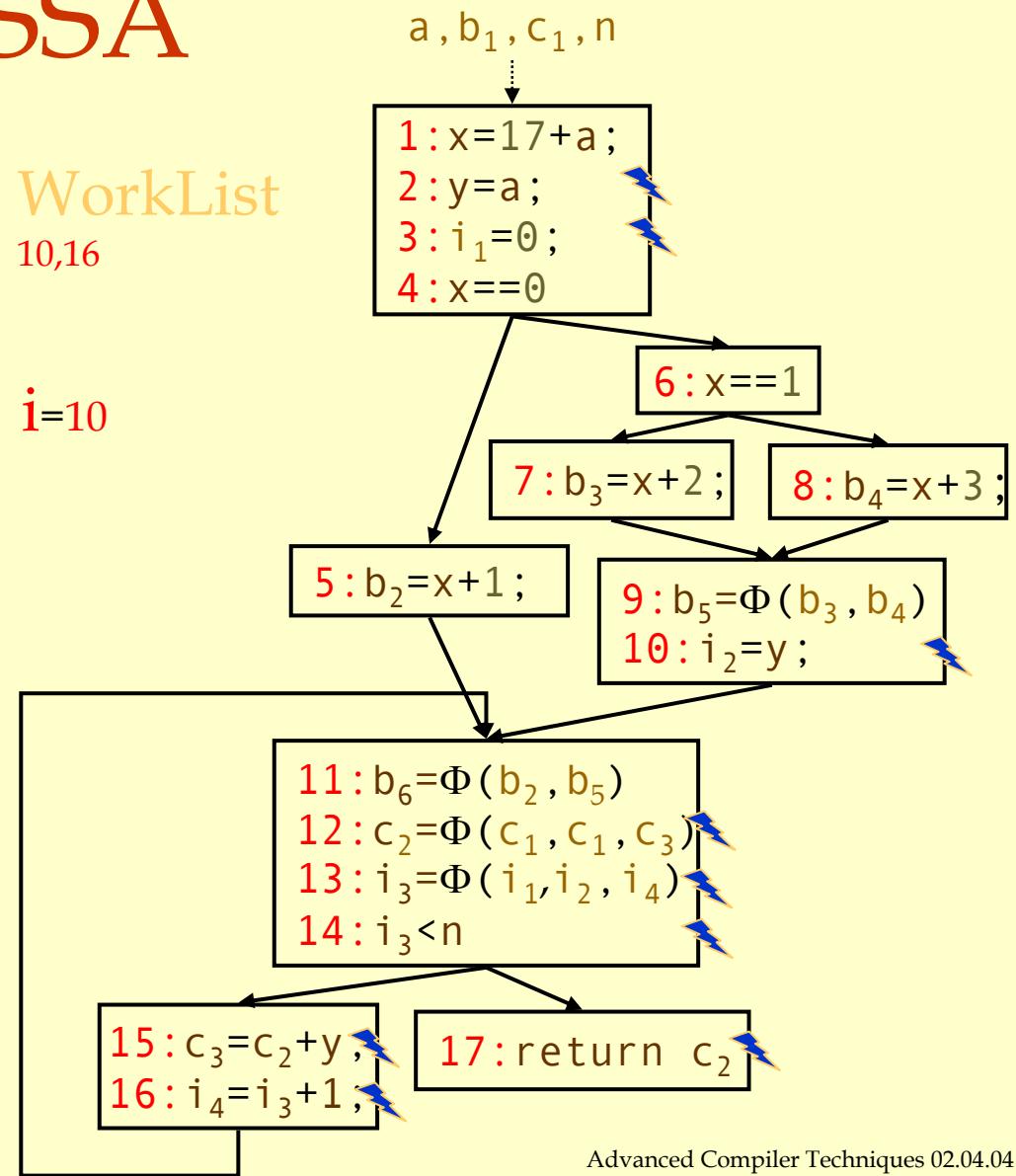


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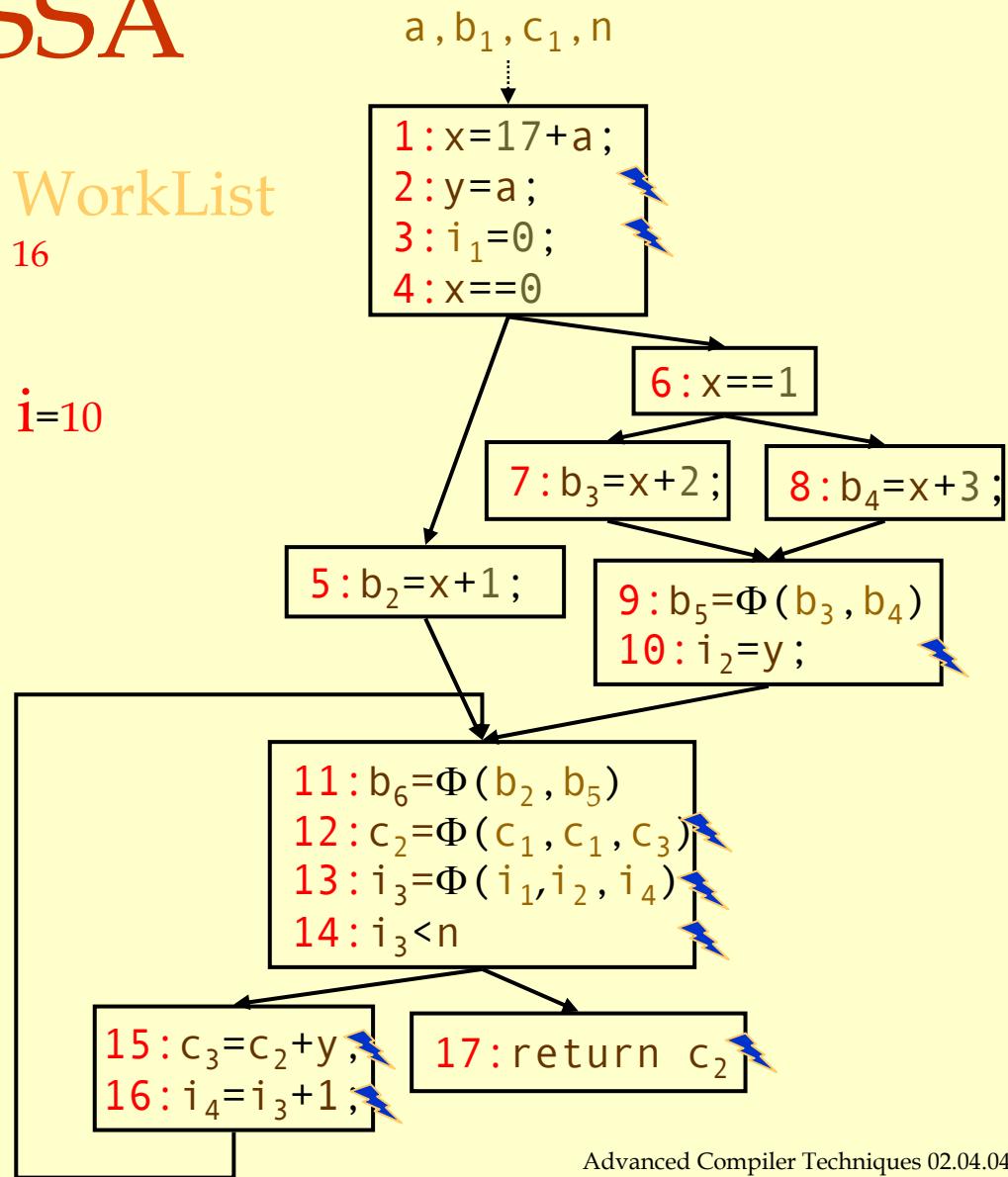
# Dead Code Elimination Using SSA

## Mark

```
for each op i
  clear i's mark
  if i is critical then
    mark i
    add i to WorkList
```

```
while (Worklist ≠ Ø)
  remove i from WorkList
  (i has form " $x \leftarrow y \text{ op } z$ ")
  if def(y) is not marked then
    mark def(y)
    add def(y) to WorkList
  if def(z) is not marked then
    mark def(z)
    add def(z) to WorkList

  for each b ∈ RDF(block(i))
    mark the block-ending
    branch in b
    add it to WorkList
```



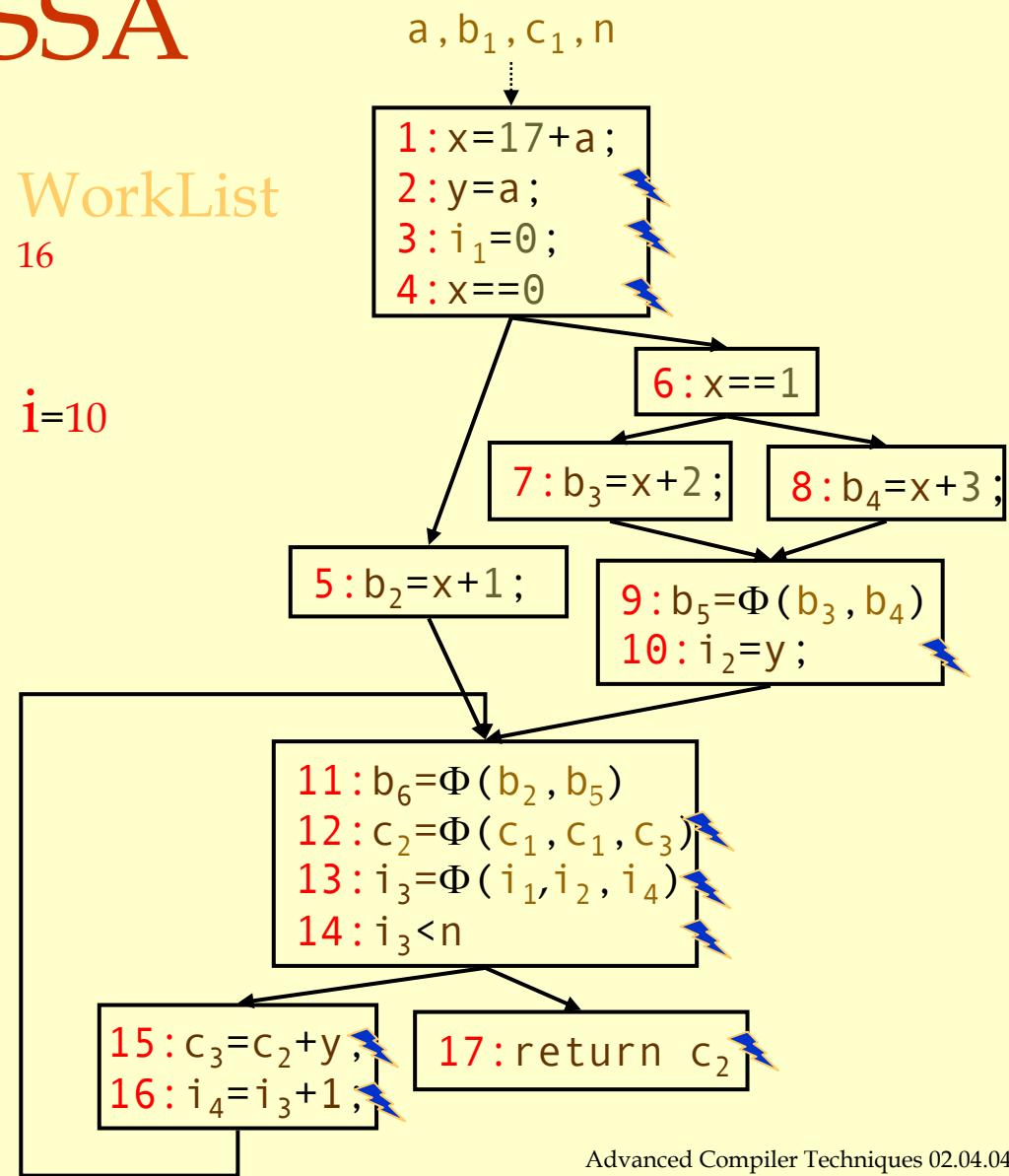
# Dead Code Elimination Using SSA

## Mark

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for each op i
  clear i's mark
  if i is critical then
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    add i to WorkList
```

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while (Worklist ≠ Ø)
  remove i from WorkList
    (i has form " $x \leftarrow y \text{ op } z$ ")
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    add def(y) to WorkList
  if def(z) is not marked then
    mark def(z)
    add def(z) to WorkList

  for each b ∈ RDF(block(i))
    mark the block-ending
    branch in b
    add it to WorkList
```



# Dead Code Elimination Using SSA

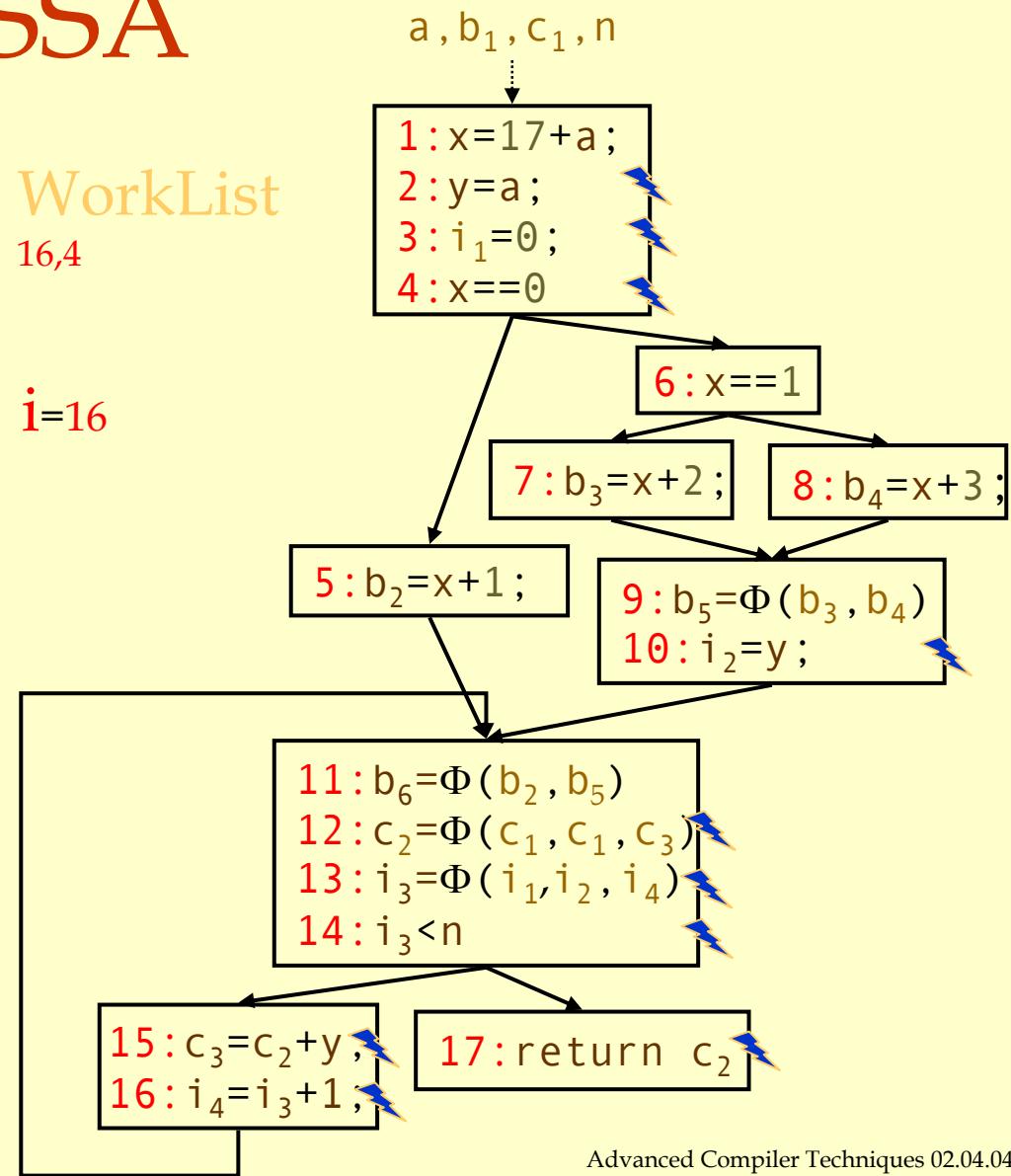
## Mark

```

for each op i
  clear i's mark
  if i is critical then
    mark i
    add i to WorkList
  
```

```

while (Worklist ≠ Ø)
  remove i from WorkList
    (i has form "x←y op z")
  if def(y) is not marked then
    mark def(y)
    add def(y) to WorkList
  if def(z) is not marked then
    mark def(z)
    add def(z) to WorkList
  for each b ∈ RDF(block(i))
    mark the block-ending
      branch in b
    add it to WorkList
  
```



# Dead Code Elimination Using SSA

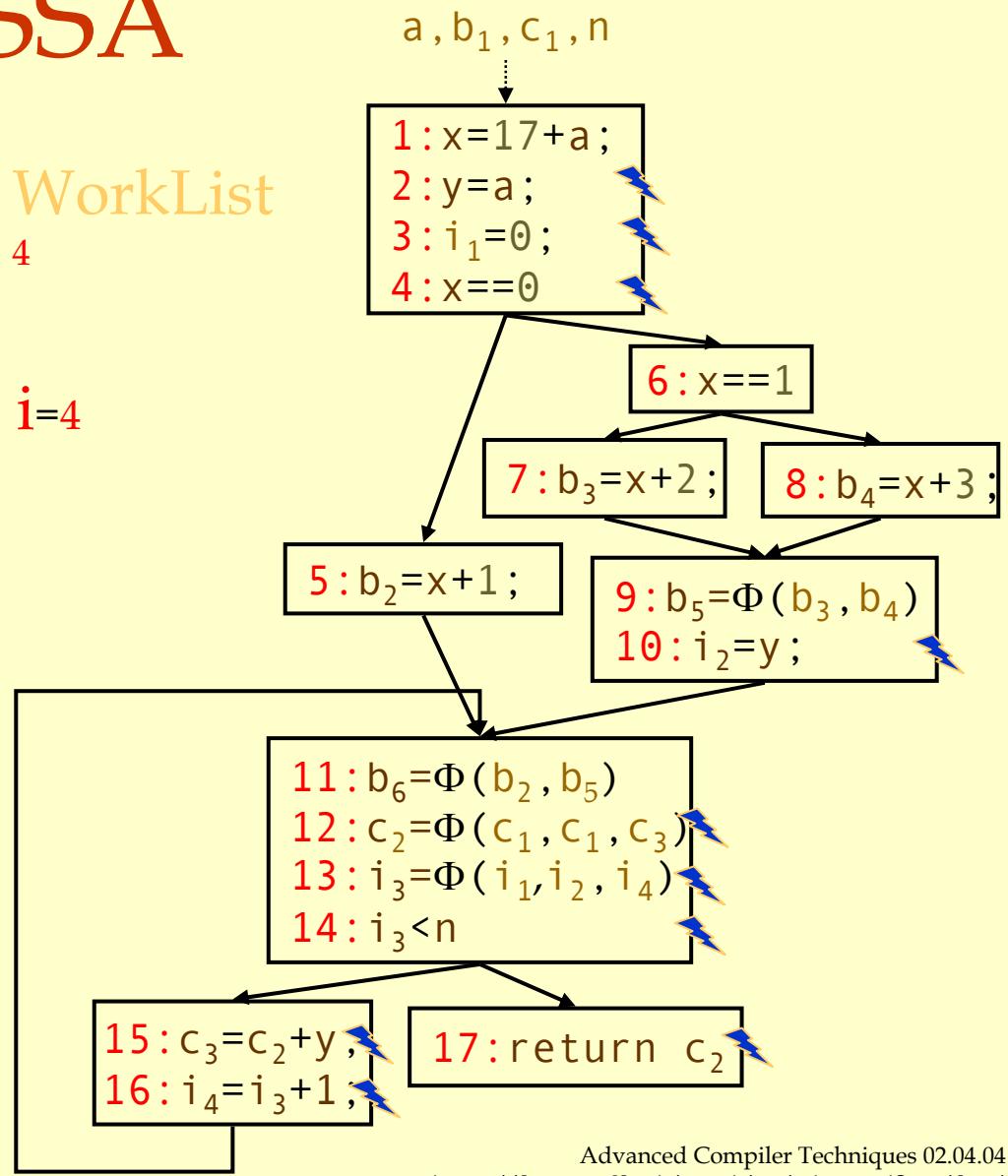
## Mark

```

for each op i
  clear i's mark
  if i is critical then
    mark i
    add i to WorkList
  
```

```

while (Worklist ≠ Ø)
  remove i from WorkList
    (i has form "x←y op z")
  if def(y) is not marked then
    mark def(y)
    add def(y) to WorkList
  if def(z) is not marked then
    mark def(z)
    add def(z) to WorkList
  for each b ∈ RDF(block(i))
    mark the block-ending
      branch in b
    add it to WorkList
  
```



# Dead Code Elimination Using SSA

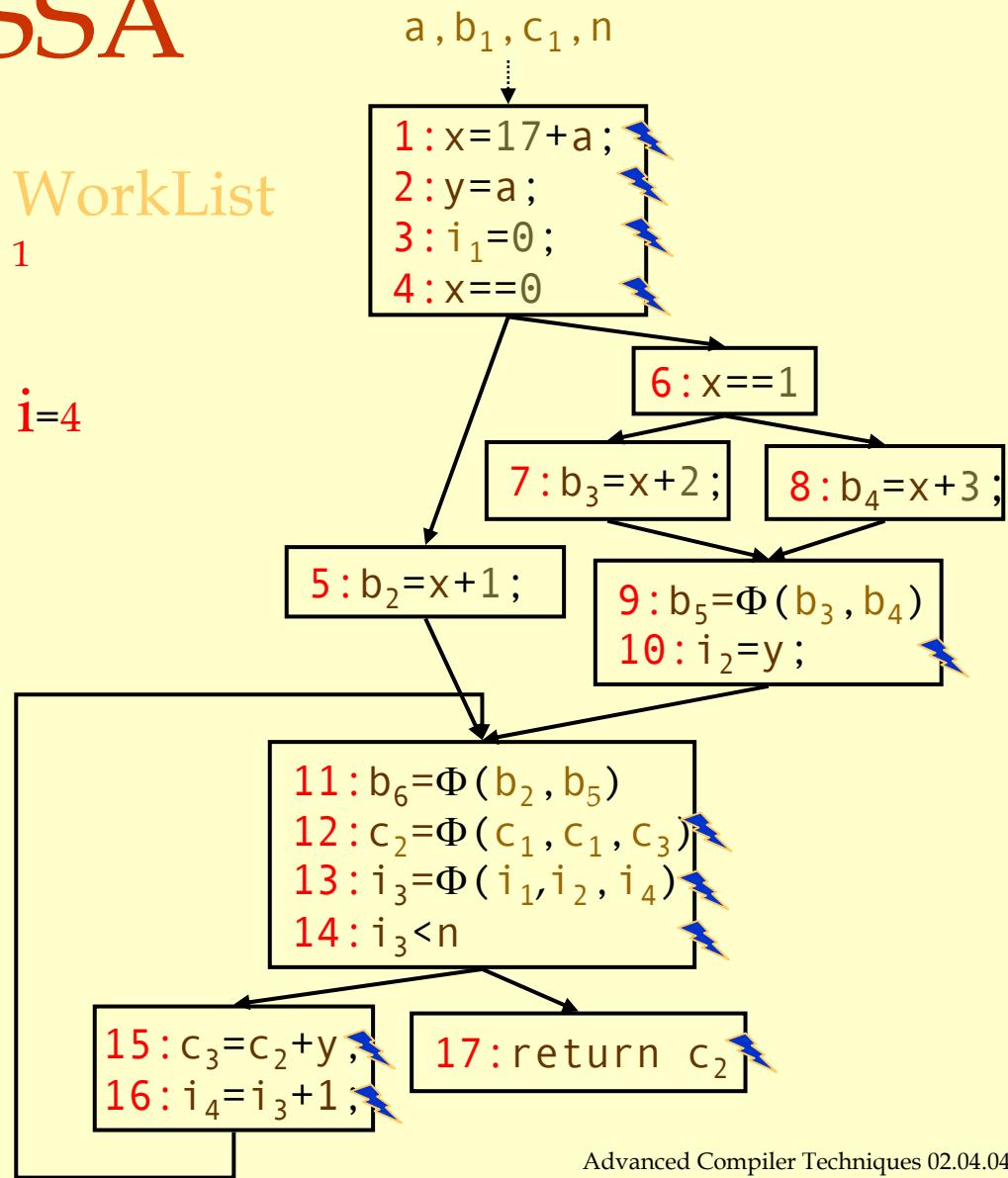
## Mark

```

for each op i
  clear i's mark
  if i is critical then
    mark i
    add i to WorkList
  
```

```

while (Worklist ≠ Ø)
  remove i from WorkList
  (i has form " $x \leftarrow y \text{ op } z$ ")
  if def(y) is not marked then
    mark def(y)
    add def(y) to WorkList
  if def(z) is not marked then
    mark def(z)
    add def(z) to WorkList
  for each b ∈ RDF(block(i))
    mark the block-ending
      branch in b
    add it to WorkList
  
```



# Dead Code Elimination Using SSA

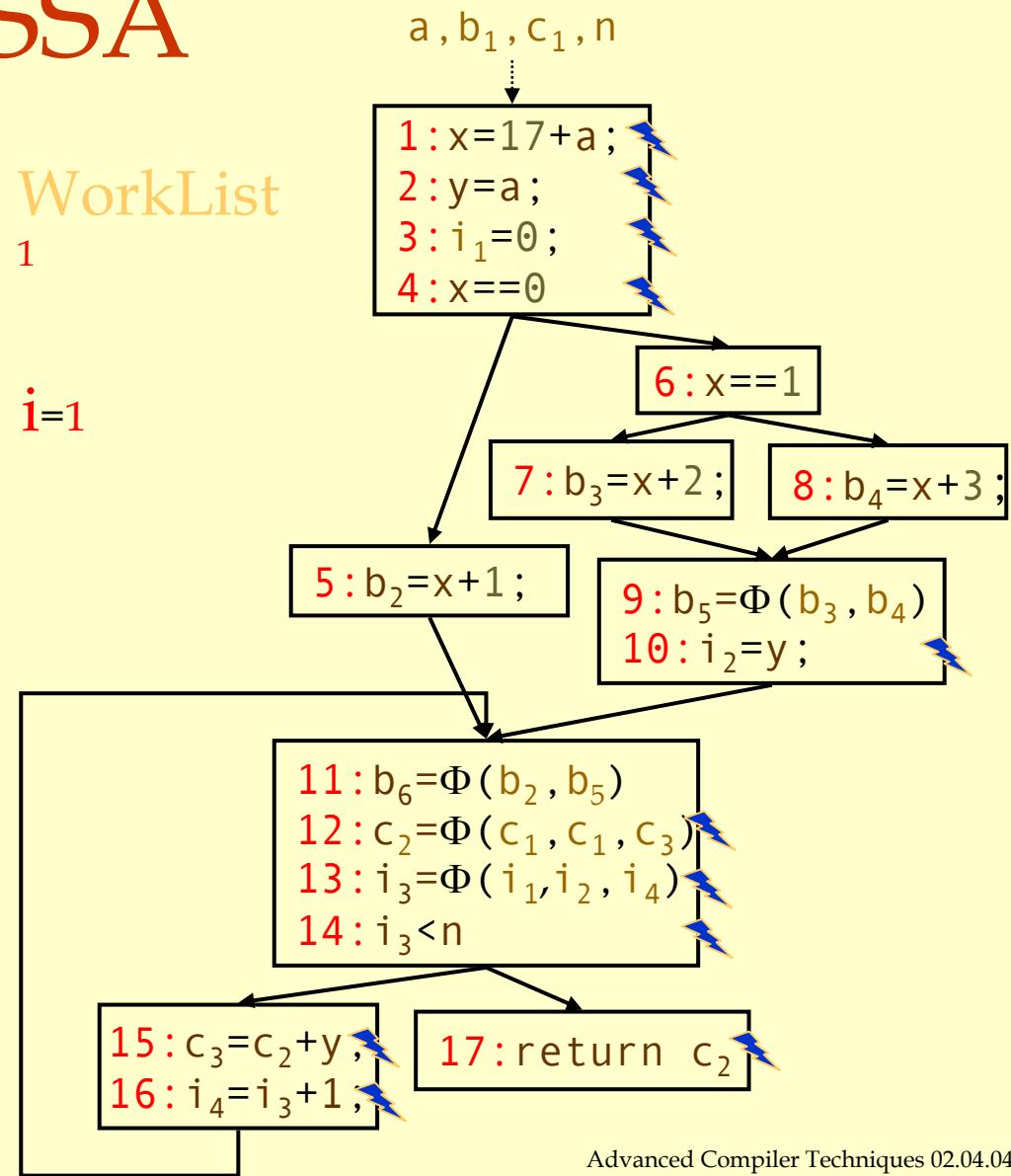
## Mark

```

for each op i
  clear i's mark
  if i is critical then
    mark i
    add i to WorkList
  
```

```

while (Worklist ≠ Ø)
  remove i from WorkList
    (i has form "x ← y op z")
  if def(y) is not marked then
    mark def(y)
    add def(y) to WorkList
  if def(z) is not marked then
    mark def(z)
    add def(z) to WorkList
  for each b ∈ RDF(block(i))
    mark the block-ending
      branch in b
    add it to WorkList
  
```

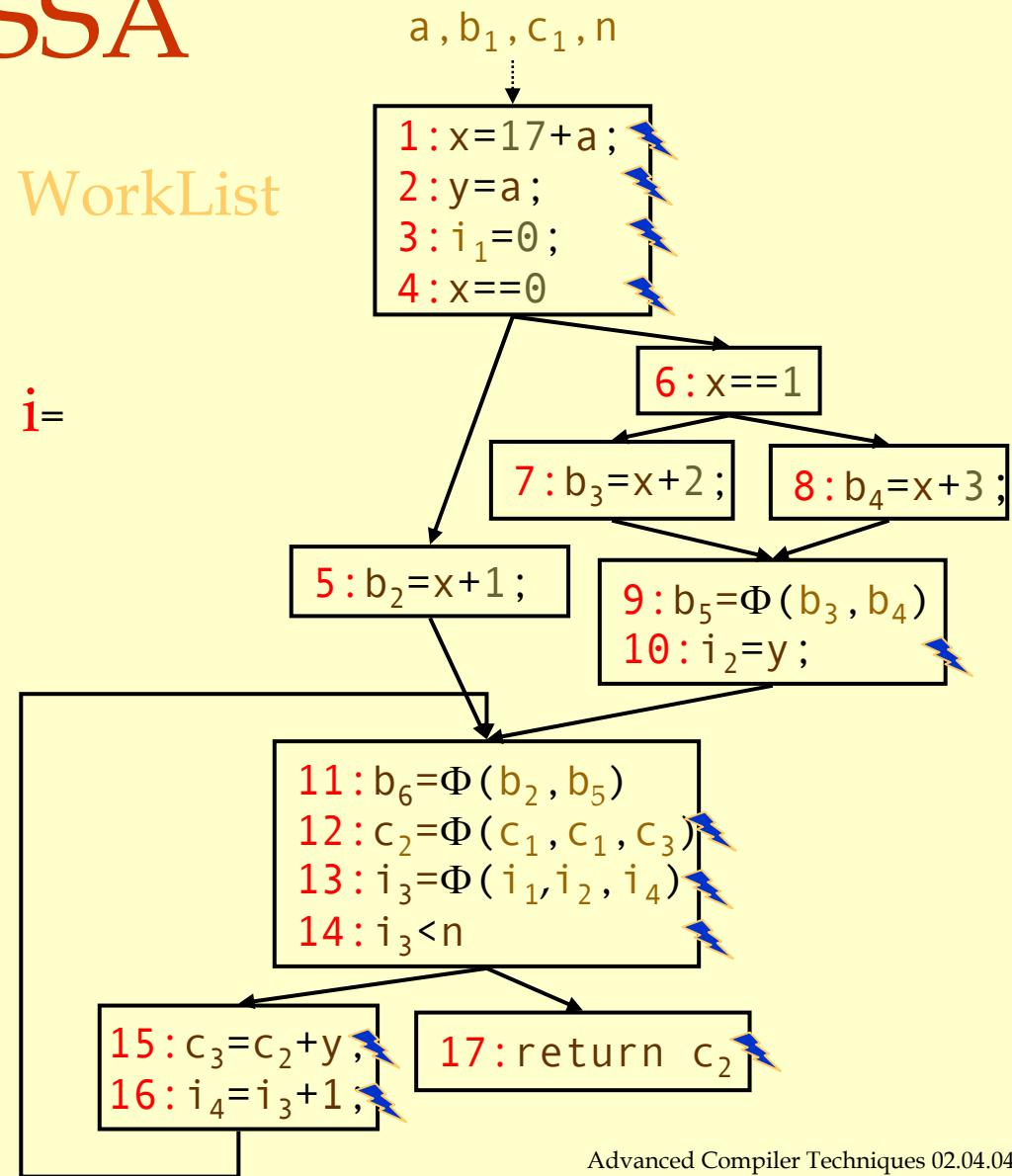


# Dead Code Elimination Using SSA

## Mark

```
for each op i
  clear i's mark
  if i is critical then
    mark i
    add i to WorkList
```

```
while (Worklist ≠ Ø)
  remove i from WorkList
  (i has form " $x \leftarrow y \text{ op } z$ ")
  if def(y) is not marked then
    mark def(y)
    add def(y) to WorkList
  if def(z) is not marked then
    mark def(z)
    add def(z) to WorkList
  for each b ∈ RDF(block(i))
    mark the block-ending
    branch in b
    add it to WorkList
```



# Dead Code Elimination Using SSA

Dead Code Elimination

**Sweep**

for each op **i**

if **i** is not marked then

    if **i** is a branch then

        rewrite with a jump to

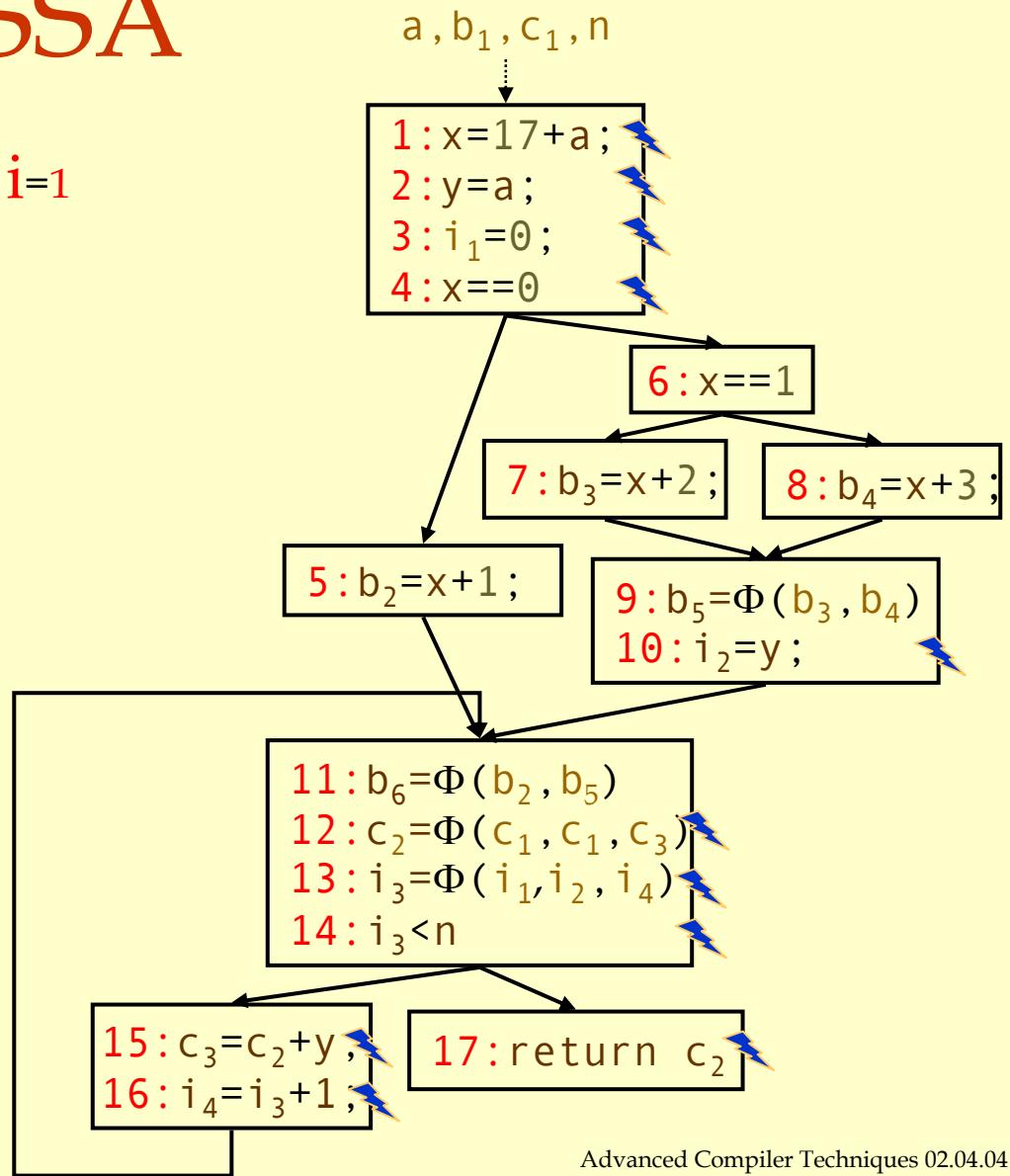
**i**'s nearest useful

            post-dominator

    if **i** is not a jump then

        delete **i**

i=1



# Dead Code Elimination Using SSA

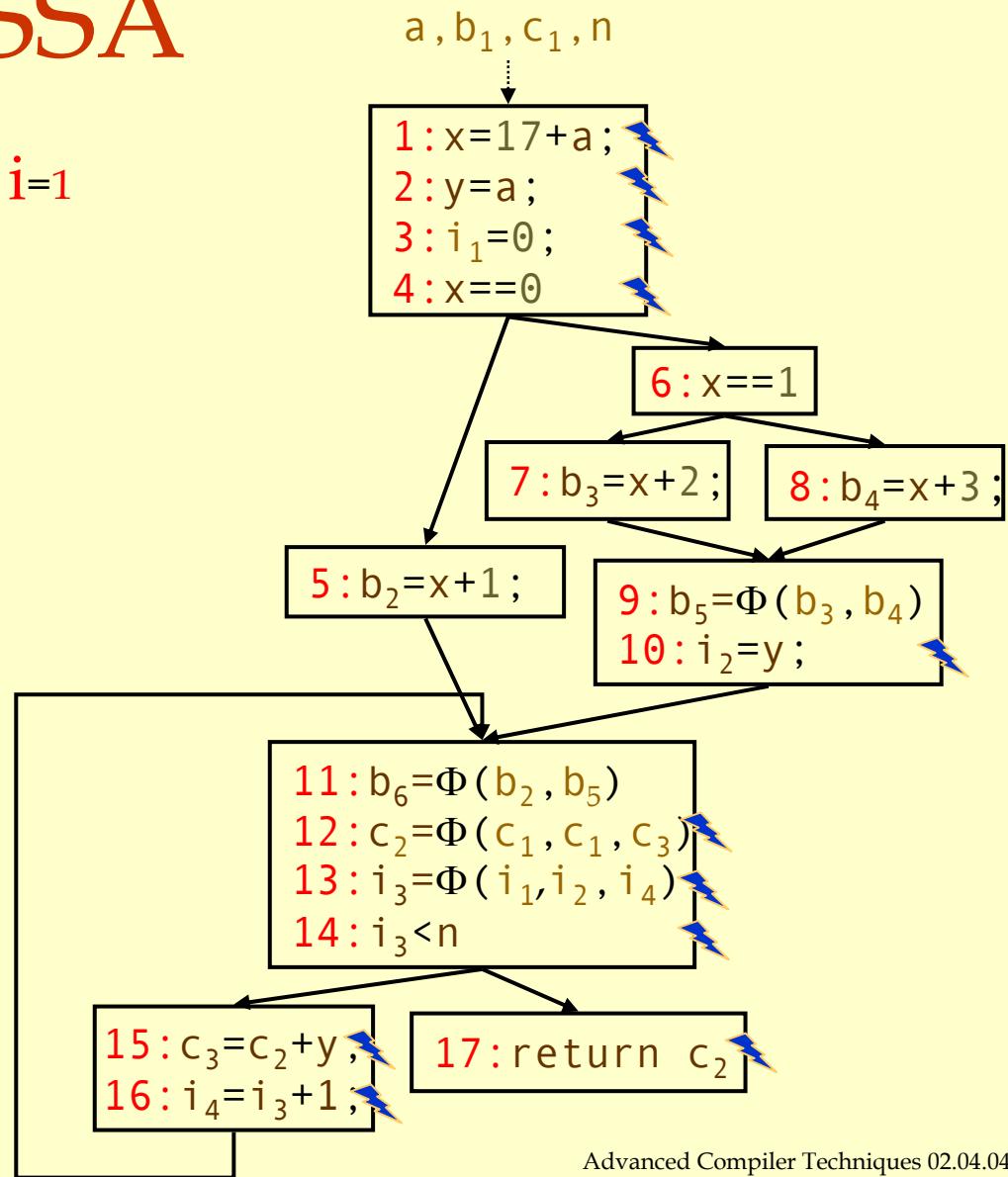
## Sweep

for each op  $i$   
 if  $i$  is not marked then

if  $i$  is a branch then  
 rewrite with a jump to  
 $i$ 's nearest useful  
 post-dominator  
 if  $i$  is not a jump then  
 delete  $i$

$i=1$

SSA



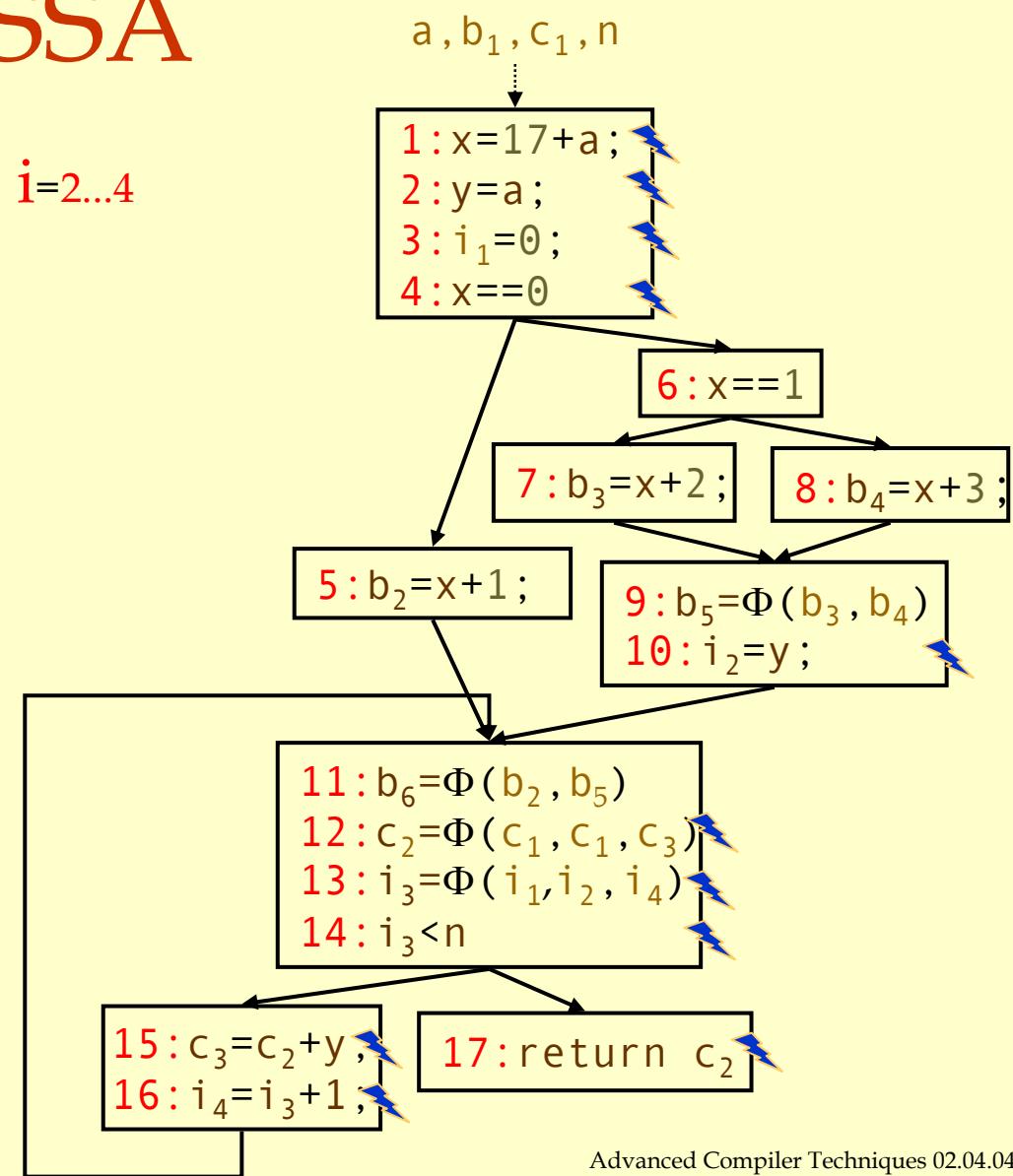
# Dead Code Elimination Using SSA

## Sweep

for each op  $i$   
 if  $i$  is not marked then

if  $i$  is a branch then  
 rewrite with a jump to  
 $i$ 's nearest useful  
 post-dominator  
 if  $i$  is not a jump then  
 delete  $i$

$i=2..4$



# Dead Code Elimination Using SSA

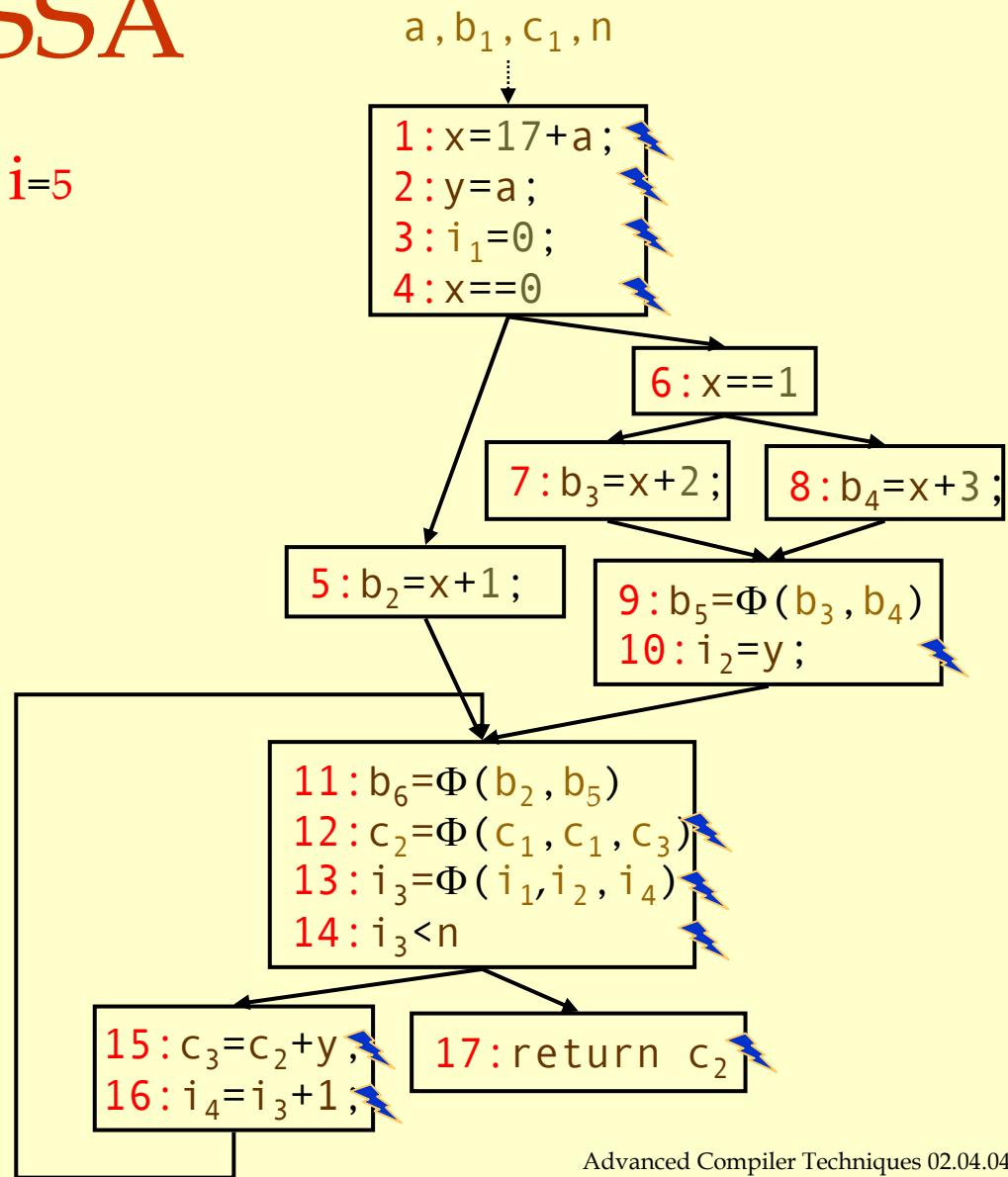
## Sweep

for each op  $i$   
 if  $i$  is not marked then

if  $i$  is a branch then  
 rewrite with a jump to  
 $i$ 's nearest useful  
 post-dominator  
 if  $i$  is not a jump then  
 delete  $i$

$i=5$

SSA



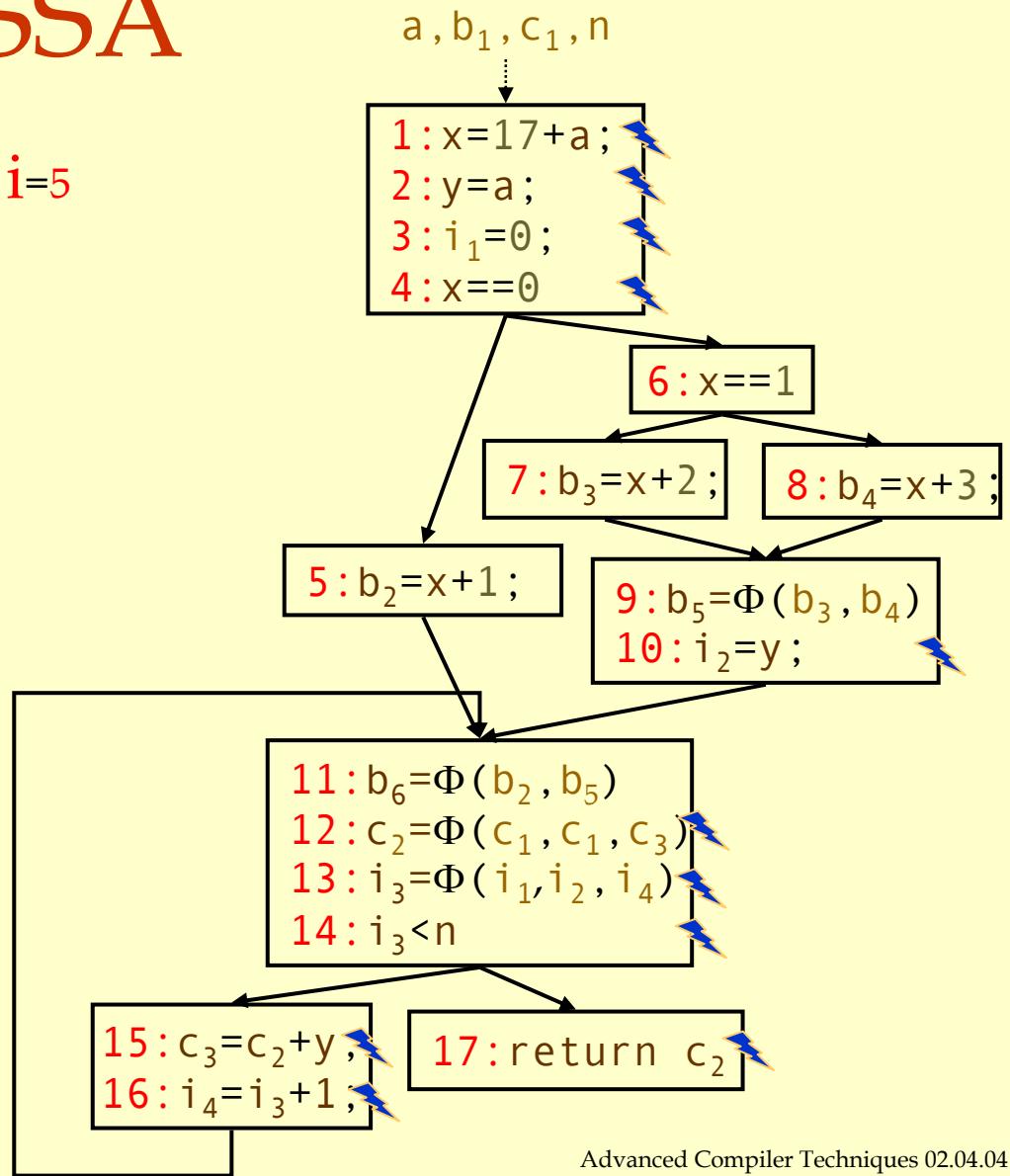
# Dead Code Elimination Using SSA

Dead Code Elimination

**Sweep**

for each op  $i$   
if  $i$  is not marked then  
    if  $i$  is a branch then  
        rewrite with a jump to  
             $i$ 's nearest useful  
            post-dominator  
    if  $i$  is not a jump then  
        delete  $i$

i=5

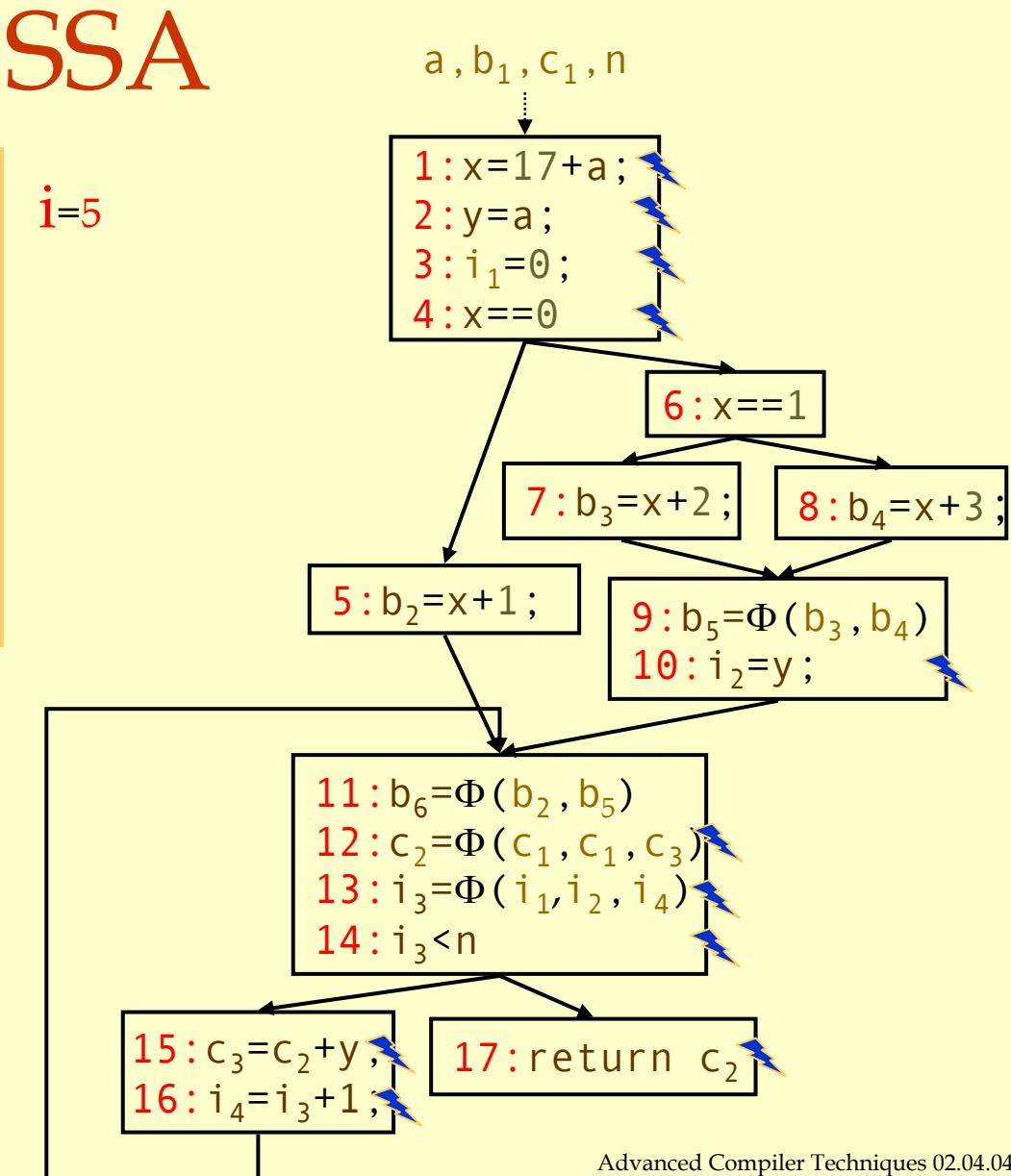


# Dead Code Elimination Using SSA

## Sweep

```

for each op i
  if i is not marked then
    if i is a branch then
      rewrite with a jump to
      i's nearest useful
      post-dominator
    if i is not a jump then
      delete i
  
```

 $i=5$ 

# Dead Code Elimination Using SSA

## Sweep

for each op  $i$

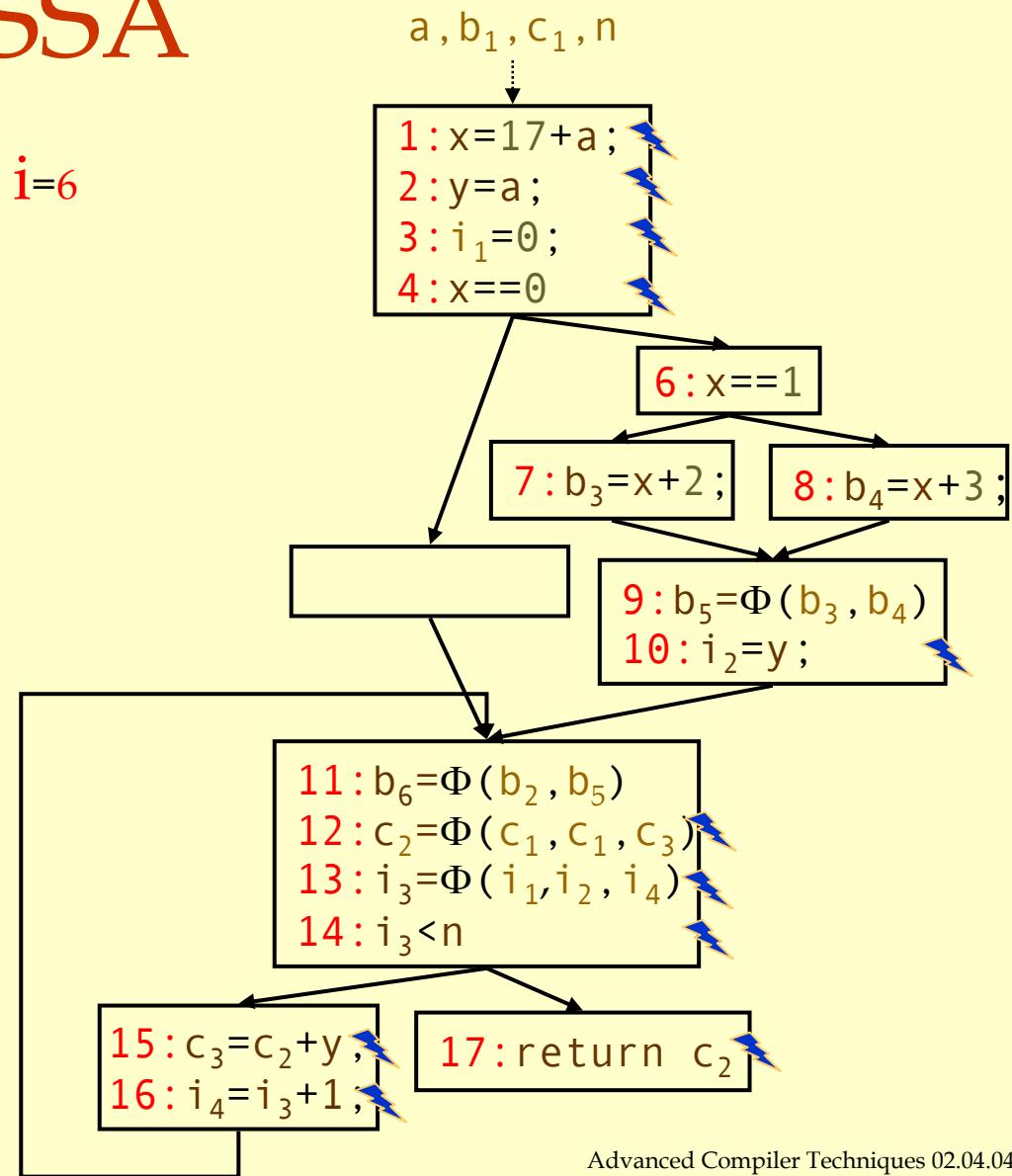
if  $i$  is not marked then

if  $i$  is a branch then  
rewrite with a jump to  
 $i$ 's nearest useful  
post-dominator

if  $i$  is not a jump then  
delete  $i$

$i=6$

SSA

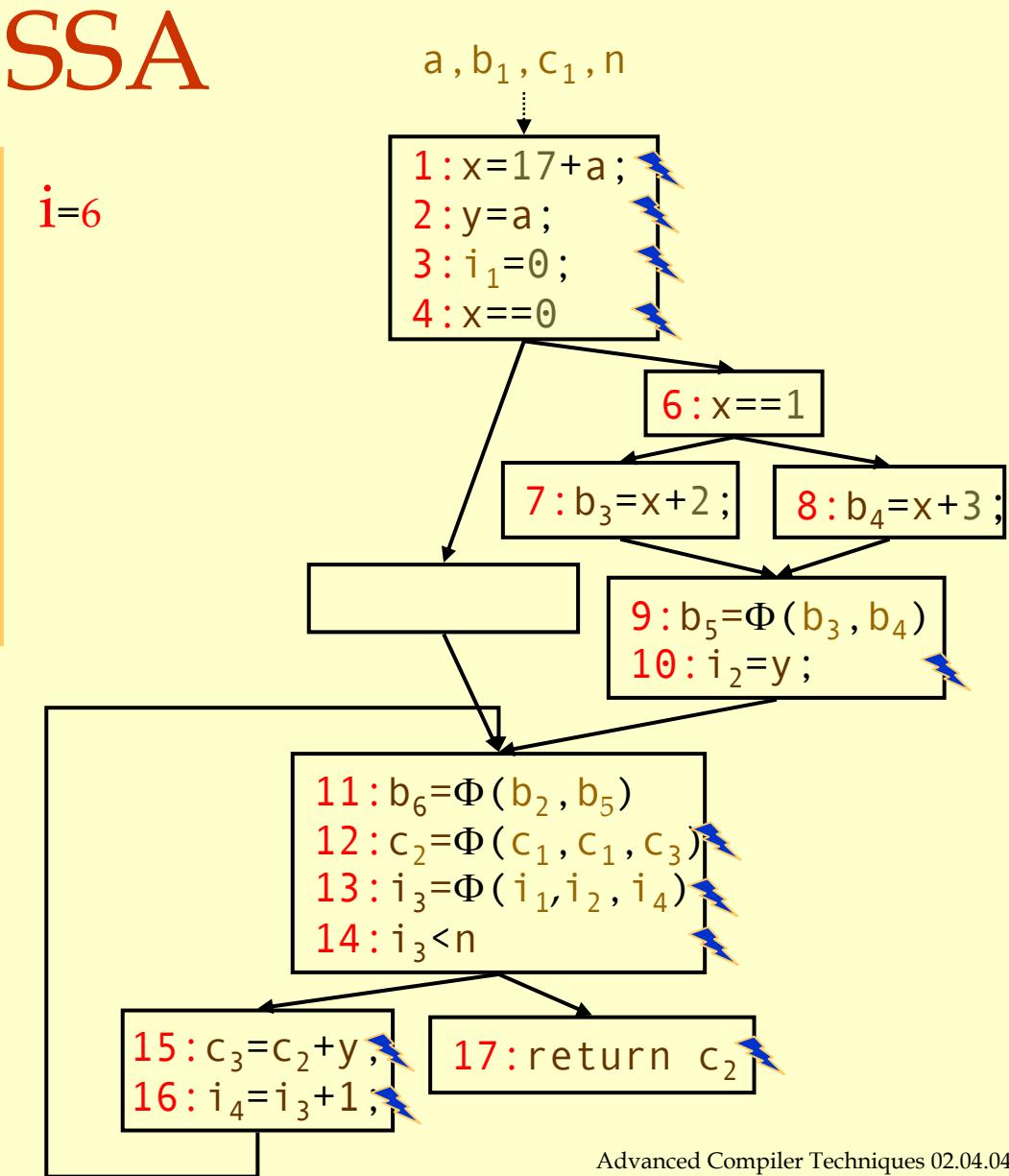


# Dead Code Elimination Using SSA

## Sweep

```

for each op i
  if i is not marked then
    if i is a branch then
      rewrite with a jump to
      i's nearest useful
      post-dominator
    if i is not a jump then
      delete i
  
```

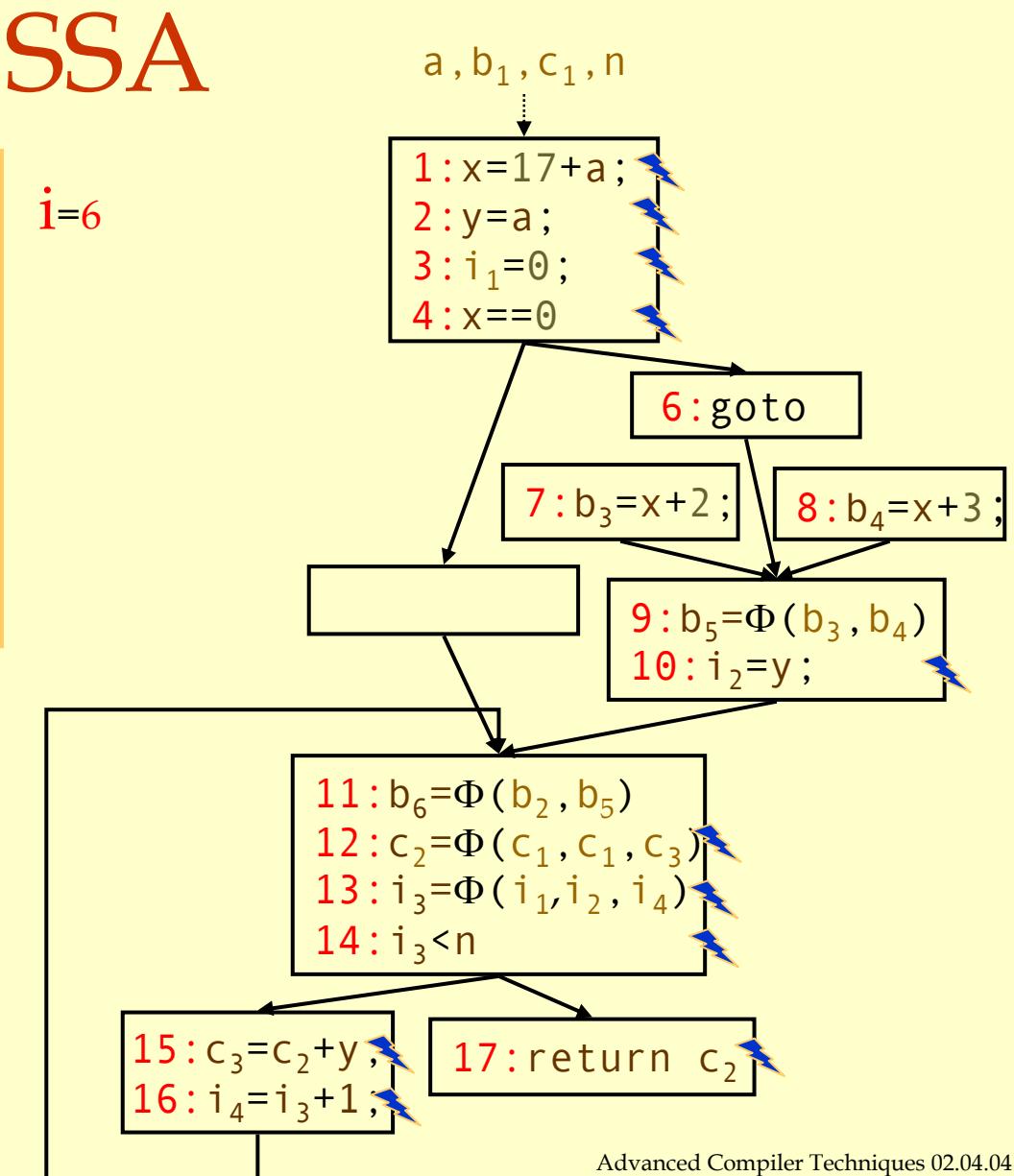
 $i=6$ 

# Dead Code Elimination Using SSA

## Sweep

```

for each op i
  if i is not marked then
    if i is a branch then
      rewrite with a jump to
      i's nearest useful
      post-dominator
    if i is not a jump then
      delete i
  
```

 $i=6$ 

# Dead Code Elimination Using SSA

## Sweep

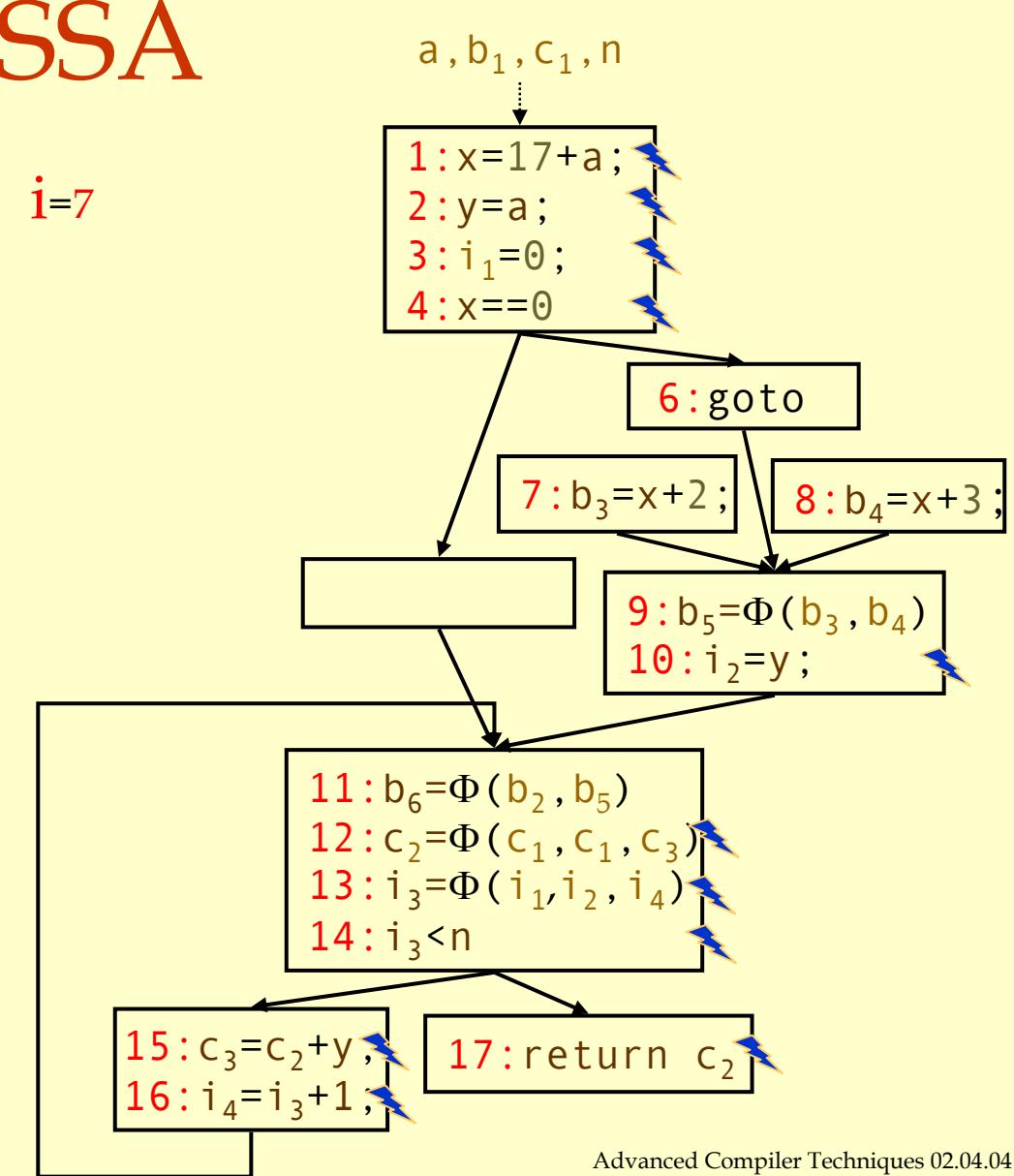
for each op  $i$

if  $i$  is not marked then

if  $i$  is a branch then  
rewrite with a jump to  
 $i$ 's nearest useful  
post-dominator

if  $i$  is not a jump then  
delete  $i$

$i=7$



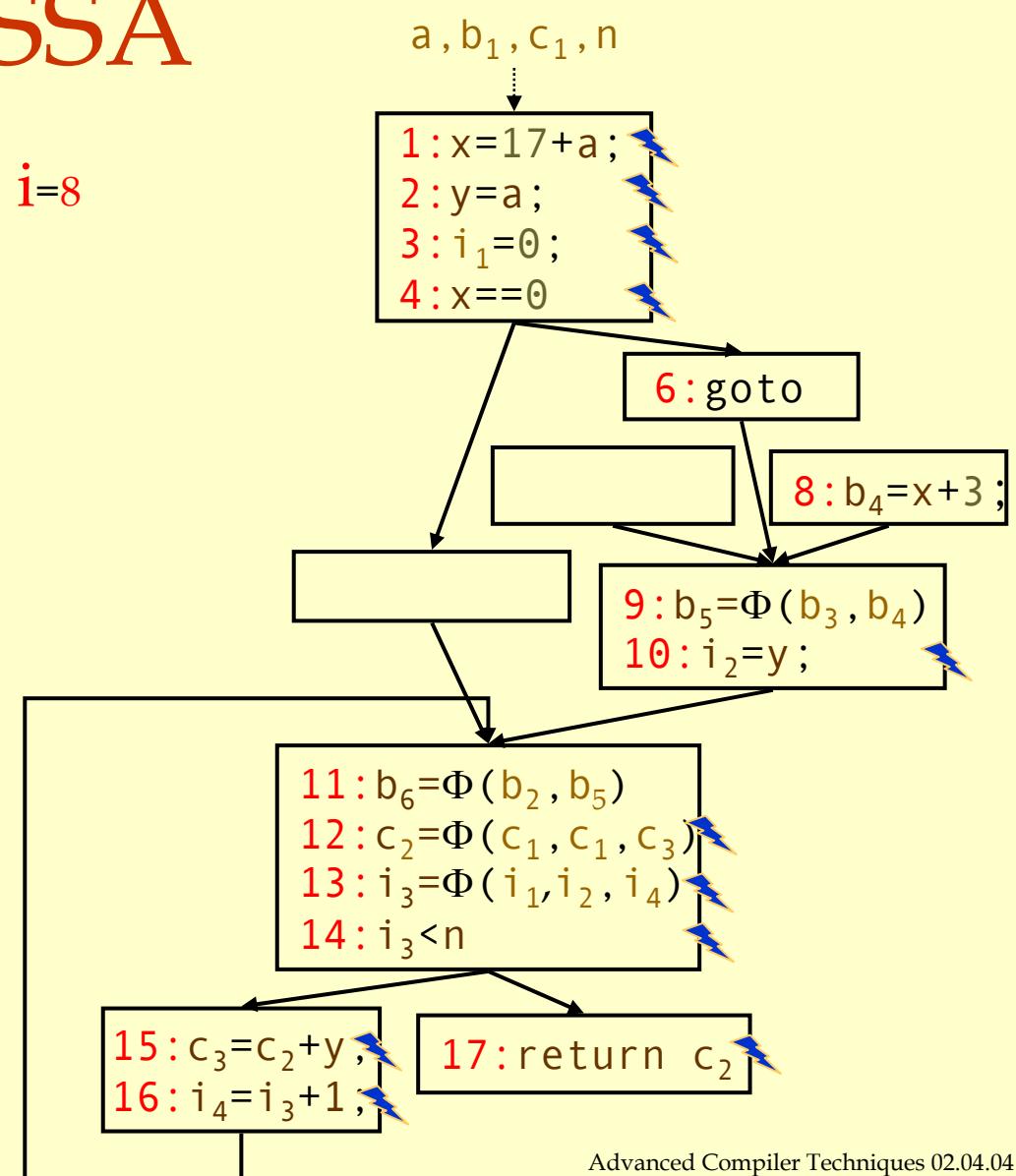
# Dead Code Elimination Using SSA

## Sweep

for each op  $i$

- if  $i$  is not marked then
- if  $i$  is a branch then  
rewrite with a jump to  
 $i$ 's nearest useful  
post-dominator
- if  $i$  is not a jump then  
delete  $i$

$i=8$



# Dead Code Elimination Using SSA

## Sweep

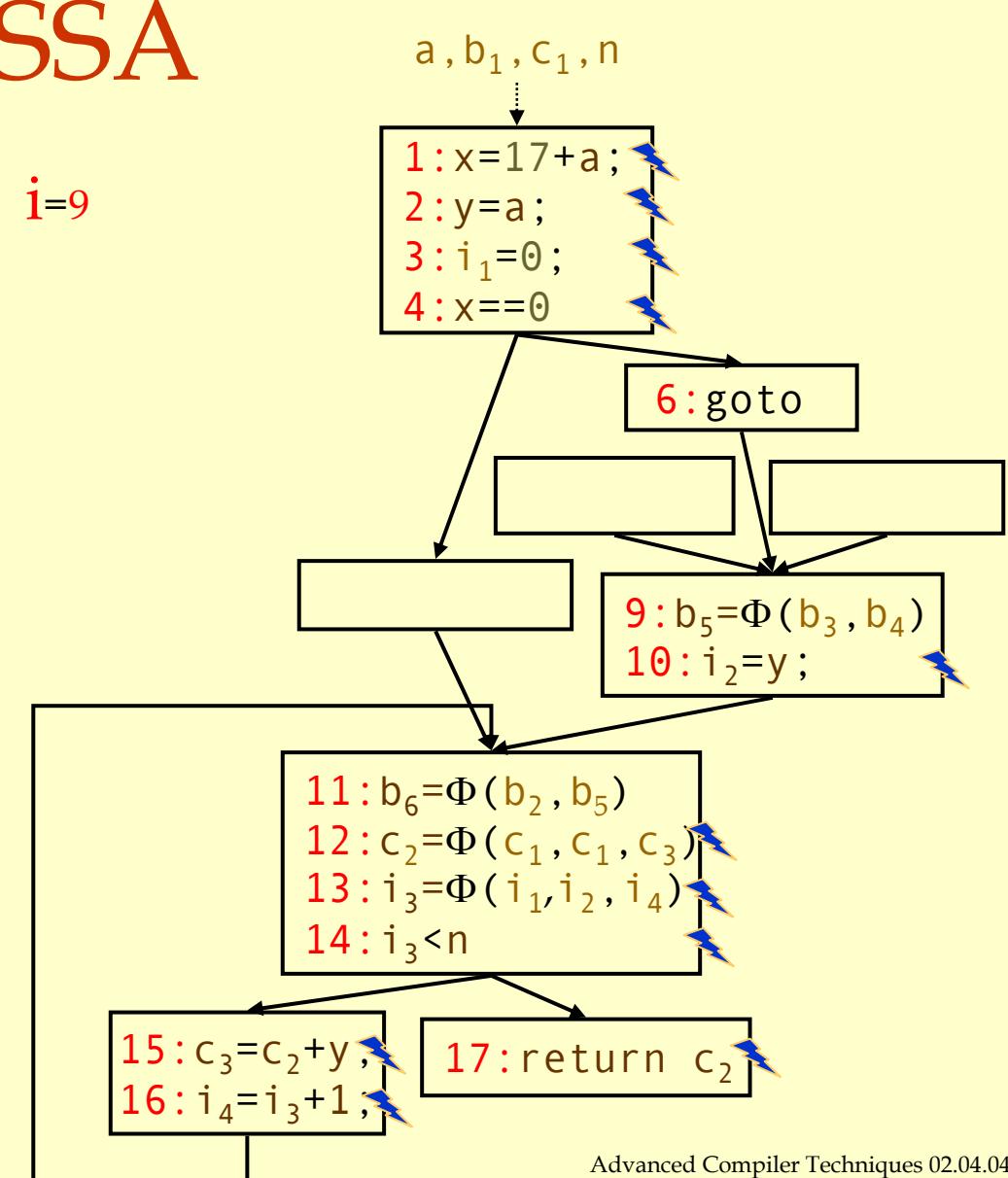
for each op  $i$

if  $i$  is not marked then

if  $i$  is a branch then  
rewrite with a jump to  
 $i$ 's nearest useful  
post-dominator

if  $i$  is not a jump then  
delete  $i$

$i=9$



# Dead Code Elimination Using SSA

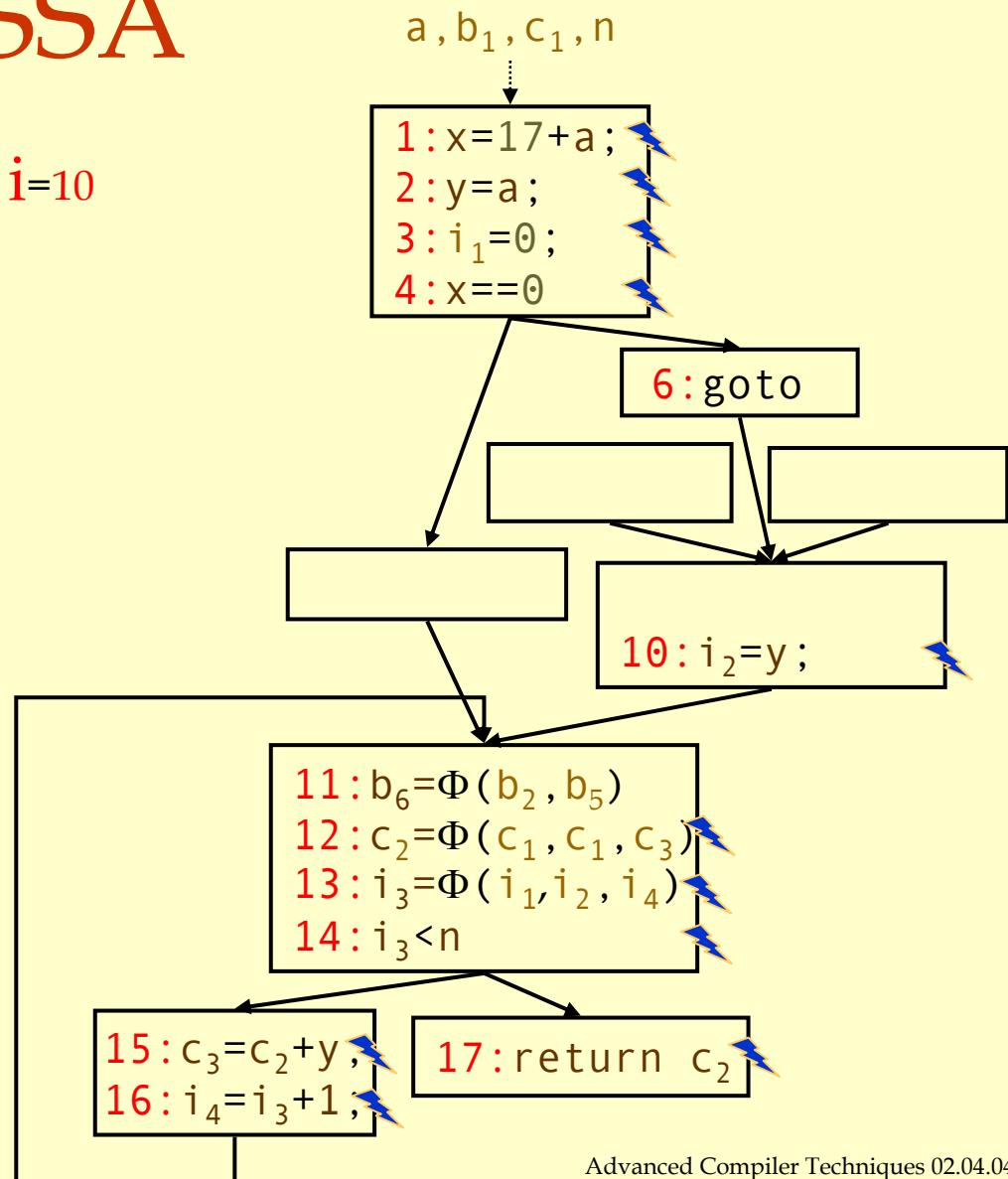
## Sweep

for each op  $i$   
 if  $i$  is not marked then

if  $i$  is a branch then  
 rewrite with a jump to  
 $i$ 's nearest useful  
 post-dominator  
 if  $i$  is not a jump then  
 delete  $i$

$i=10$

SSA



# Dead Code Elimination Using SSA

## Sweep

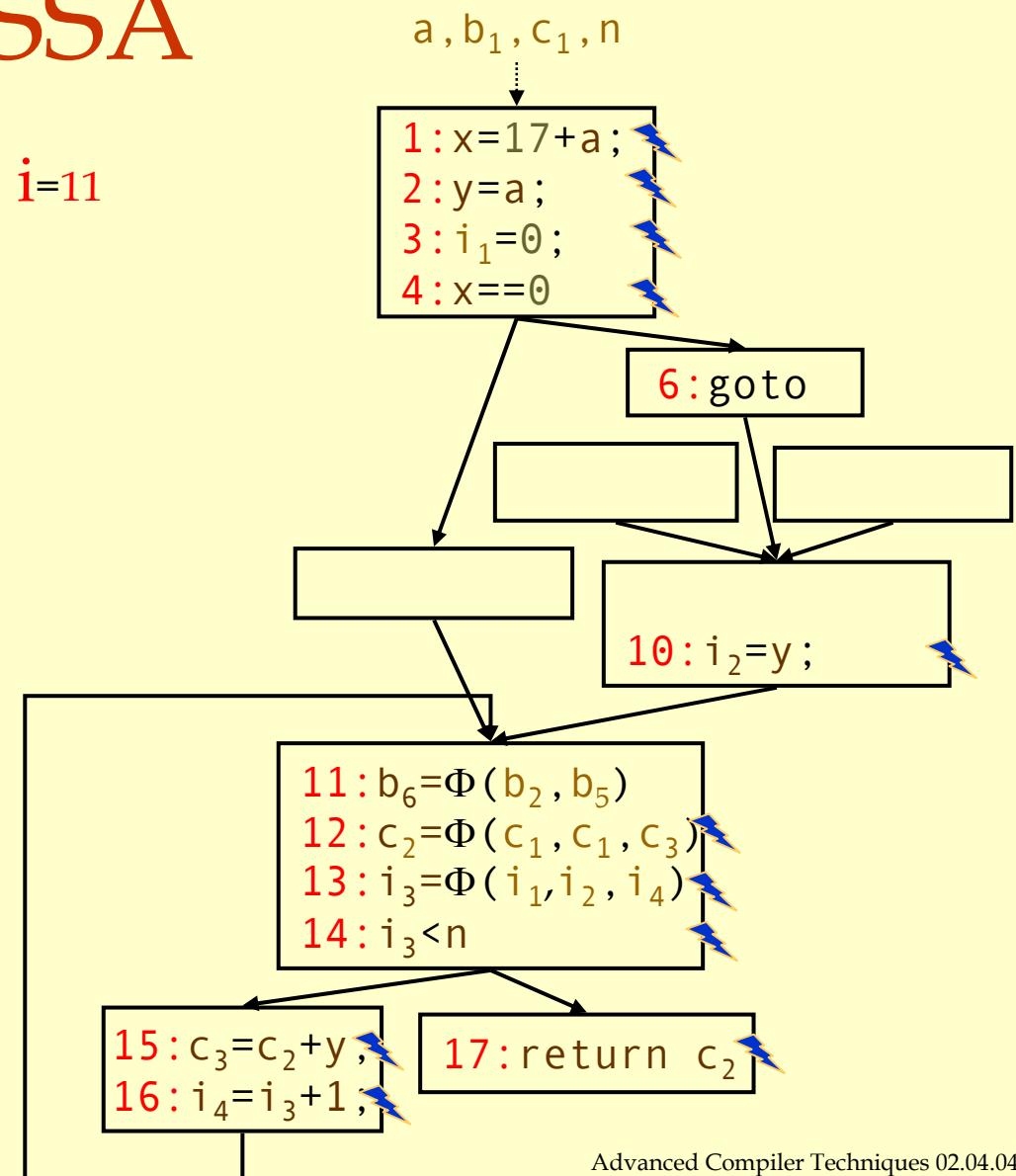
for each op  $i$

if  $i$  is not marked then

if  $i$  is a branch then  
rewrite with a jump to  
 $i$ 's nearest useful  
post-dominator

if  $i$  is not a jump then  
delete  $i$

$i=11$



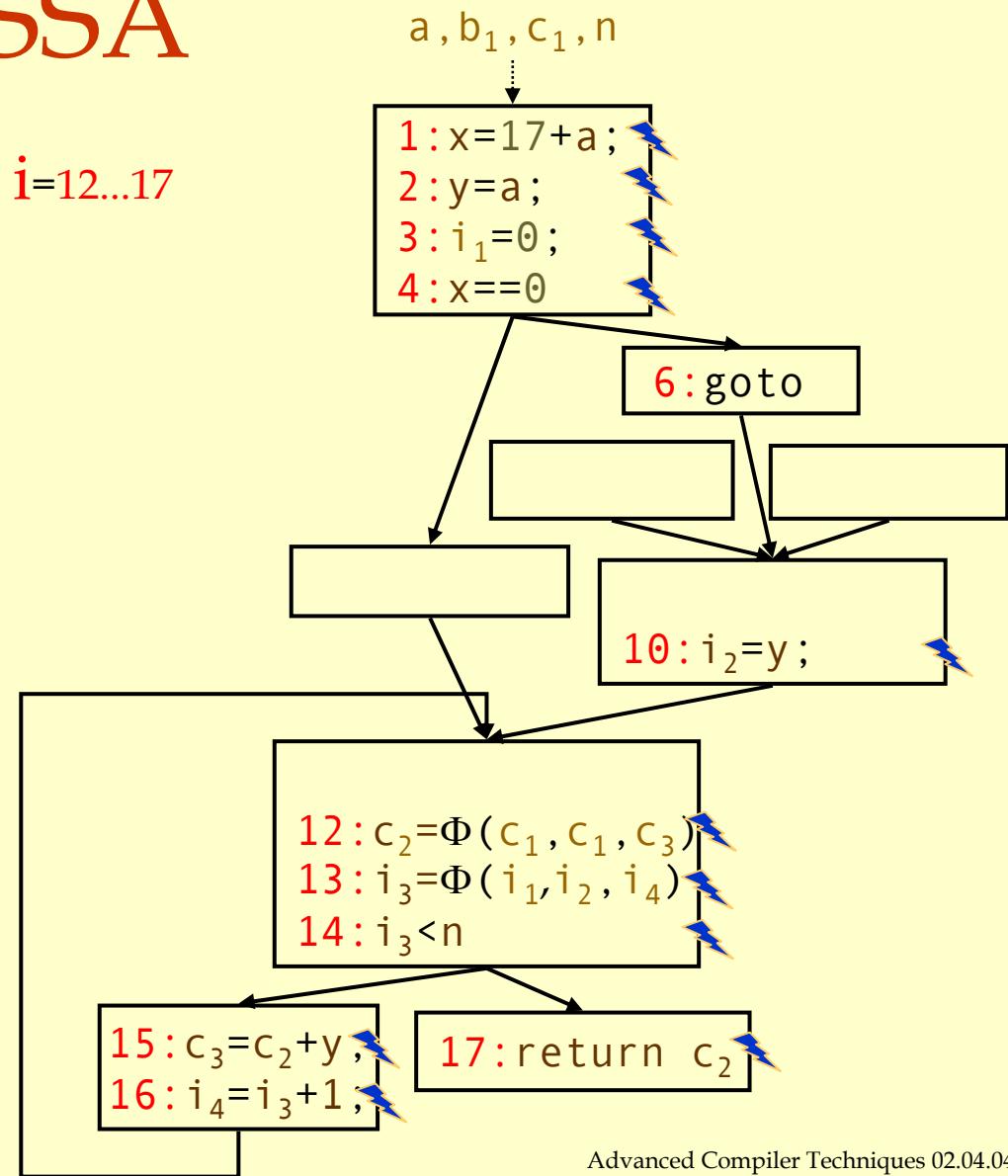
# Dead Code Elimination Using SSA

## Sweep

for each op  $i$   
 if  $i$  is not marked then

if  $i$  is a branch then  
 rewrite with a jump to  
 $i$ 's nearest useful  
 post-dominator  
 if  $i$  is not a jump then  
 delete  $i$

$i=12\ldots 17$



# Dead Code Elimination Using SSA

What's left?

- ◆ Algorithm eliminates useless definitions & some useless branches
- ◆ Algorithm leaves behind empty blocks & extraneous control-flow

Algorithm from: Cytron, Ferrante, Rosen, Wegman, & Zadeck, *Efficiently Computing Static Single Assignment Form and the Control Dependence Graph*, ACM TOPLAS 13(4), October 1991

with a correction due to Rob Shillner

Two more issues

- ◆ Simplifying control-flow
- ◆ Eliminating unreachable blocks

Both are CFG transformations (no need for SSA)

# Constant Propagation

## Safety

- ◆ Proves that name always has known value
- ◆ Specializes code around that value
  - ◆ Moves some computations to compile time  $(\Rightarrow \text{code motion})$
  - ◆ Exposes some unreachable blocks  $(\Rightarrow \text{dead code})$

## Opportunity

- ◆ Value  $\neq \perp$  signifies an opportunity

## Profitability

- ◆ Compile-time evaluation is cheaper than run-time evaluation
- ◆ Branch removal may lead to block coalescing
  - ◆ If not, it still avoids the test & makes branch predictable

# Sparse Constant Propagation Using SSA

```

 $\forall$  expression,  $e$       {       $\text{TOP}$  if its value is unknown
     $\text{Value}(e) \leftarrow \text{TOP}$        $c_i$  if its value is known (the constant  $c_i$ )
 $\text{WorkList} \leftarrow \emptyset$        $\text{BOT}$  if its value is known to vary
 $\forall$  SSA edge  $s = \langle u, v \rangle$ 
  if  $\text{Value}(u) \neq \text{TOP}$  then
    add  $s$  to  $\text{WorkList}$ 

while ( $\text{WorkList} \neq \emptyset$ )
  remove  $s = \langle u, v \rangle$  from  $\text{WorkList}$ 
  let  $o$  be the operation that uses  $v$ 
  if  $\text{Value}(o) \neq \text{BOT}$  then
     $t \leftarrow$  result of evaluating  $o$ 
    if  $t \neq \text{Value}(o)$  then
       $\forall$  SSA edge  $\langle o, x \rangle$ 
        add  $\langle o, x \rangle$  to  $\text{WorkList}$ 

```

Same result, fewer  $\wedge$  operations  
Performs  $\wedge$  only at  $\Phi$  nodes

i.e.,  $o$  is “ $a \leftarrow b \text{ op } v$ ” or “ $a \leftarrow v \text{ op } b$ ”

Evaluating a  $\Phi$ -node:

$\Phi(x_1, x_2, x_3, \dots, x_n)$  is  
 $\text{Value}(x_1) \wedge \text{Value}(x_2) \wedge \text{Value}(x_3)$   
 $\wedge \dots \wedge \text{Value}(x_n)$

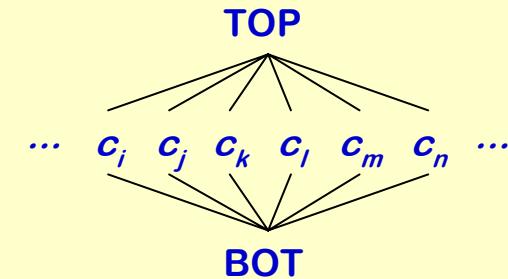
Where

$\text{TOP} \wedge x = x$	$\forall x$
$c_i \wedge c_j = c_i$	if $c_i = c_j$
$c_i \wedge c_j = \text{BOT}$	if $c_i \neq c_j$
$\text{BOT} \wedge x = \text{BOT}$	$\forall x$

# Sparse Constant Propagation Using SSA

How long does this algorithm take to halt?

- ◆ Initialization is two passes
  - ◆  $|ops| + 2 \times |ops|$  edges
- ◆ Value( $x$ ) can take on 3 values
  - ◆ **TOP**,  $c_i$ , **BOT**
  - ◆ Each use can be on **WorkList** twice
  - ◆  $2 \times |args| = 4 \times |ops|$  evaluations, **WorkList** pushes & pops



This is an optimistic algorithm:

- ◆ Initialize all values to **TOP**, unless they are known constants
- ◆ Every value becomes **BOT** or  $c_i$ , unless its use is uninitialized

# Sparse Conditional Constant Propagation

## Optimism

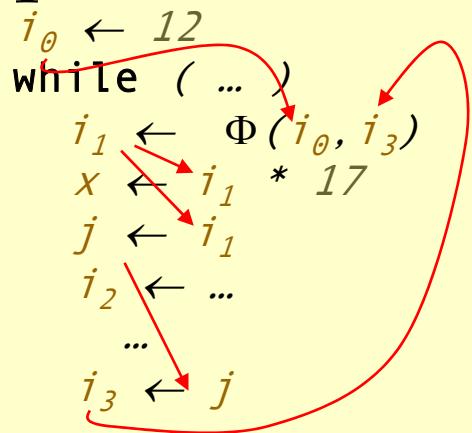
```
i0 ← 12
while ( ... )
    i1 ← Φ(i0, i3)
    x ← i1 * 17
    j ← i1
    i2 ← ...
    ...
    i3 ← j
```

## Optimism

- This version of the algorithm is an *optimistic* formulation
- Initializes values to **TOP**
- Prior version used  $\perp$  (*implicit*)

# Sparse Conditional Constant Propagation

## Optimism

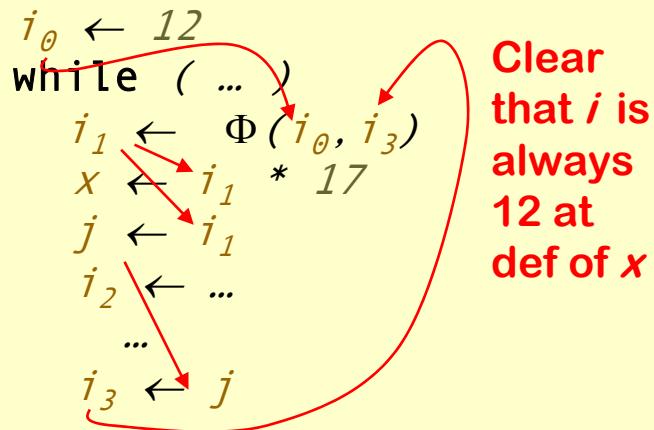


## Optimism

- This version of the algorithm is an optimistic formulation
- Initializes values to **TOP**
- Prior version used  $\perp$  (*implicit*)

# Sparse Conditional Constant Propagation

## Optimism



## Optimism

- This version of the algorithm is an optimistic formulation
- Initializes values to **TOP**
- Prior version used  $\perp$  (*implicit*)

## Optimism

```
12   $i_0 \leftarrow 12$ 
    while ( ... )
    ⊥  $i_1 \leftarrow \Phi(i_0, i_3)$ 
    ⊥  $x \leftarrow i_1 * 17$ 
    ⊥  $j \leftarrow i_1$ 
    ⊥  $i_2 \leftarrow \dots$ 
    ...
    ⊥  $i_3 \leftarrow j$ 
```

Pessimistic  
initializations

Leads to:

$$\begin{aligned} i_1 &\equiv 12 \wedge \perp \equiv \perp \\ x &\equiv \perp * 17 \equiv \perp \\ j &\equiv \perp \\ i_3 &\equiv \perp \end{aligned}$$

## Optimism

- This version of the algorithm is an *optimistic* formulation
- Initializes values to **TOP**
- Prior version used  $\perp$  (*implicit*)

# Sparse Conditional Constant Propagation

## Optimism

```

12    $i_0 \leftarrow 12$            Optimistic
      while ( ... )           initializations
      TOP  $i_1 \leftarrow \Phi(i_0, i_3)$ 
      TOP  $x \leftarrow i_1 * 17$     Leads to:
      TOP  $j \leftarrow i_1$          $i_1 \equiv 12 \wedge \text{TOP} \equiv 12$ 
      TOP  $i_2 \leftarrow \dots$       $x \equiv 12 * 17 \equiv 204$ 
      ...
      TOP  $i_3 \leftarrow j$          $j \equiv 12$ 
                                 $i_3 \equiv 12$ 
                                 $i_1 \equiv 12 \wedge 12 \equiv 12$ 
  
```

## Optimism

- This version of the algorithm is an optimistic formulation
- Initializes values to **TOP**
- Prior version used  $\perp$  (*implicit*)

In general, optimism helps inside loops.

M.N. Wegman & F.K. Zadeck, Constant propagation with conditional branches, ACM TOPLAS, 13(2), April 1991, pages 181–210.

# Sparse Conditional Constant Propagation

What happens when it propagates a value into a branch?

- ◆ **TOP**  $\Rightarrow$  we gain no knowledge.
- ◆ **BOT**  $\Rightarrow$  either path can execute.
- ◆ **TRUE** or **FALSE**  $\Rightarrow$  only one path can execute.

} But, the algorithm  
does not use this ...

Working this into the algorithm.

- ◆ Use two worklists: **SSAWorkList** & **CFGWorkList**:
  - ◆ **SSAWorkList** determines values.
  - ◆ **CFGWorkList** governs reachability.
- ◆ Don't propagate into operation until its block is reachable.

# Sparse Conditional Constant Propagation

$\text{SSAWorkList} \leftarrow \emptyset$

$\text{CFGWorkList} \leftarrow n_0$

$\forall$  block  $b$

clear  $b$ 's mark

$\forall$  expression  $e$  in  $b$

$\text{Value}(e) \leftarrow \text{TOP}$

## Initialization Step

To evaluate a branch

```

if arg is BOT then
    put both targets on CFGWorklist
else if arg is TRUE then
    put TRUE target on CFGWorkList
else if arg is FALSE then
    put FALSE target on CFGWorkList

```

To evaluate a jump

place its target on **CFGWorkList**

while  $((\text{CFGWorkList} \cup \text{SSAWorkList}) \neq \emptyset)$

while( $\text{CFGWorkList} \neq \emptyset$ )

remove  $b$  from **CFGWorkList**

mark  $b$

evaluate each  $\Phi$ -function in  $b$

evaluate each op in  $b$ , *in order*

while( $\text{SSAWorkList} \neq \emptyset$ )

remove  $s = \langle u, v \rangle$  from **SSAWorkList**

let  $o$  be the operation that contains  $v$

$t \leftarrow$  result of evaluating  $o$

if  $t \neq \text{Value}(o)$  then

$\text{Value}(o) \leftarrow t$

$\forall$  SSA edge  $\langle o, x \rangle$

if  $x$  is marked, then

add  $\langle o, x \rangle$  to **SSAWorkList**

## Propagation Step

# Sparse Conditional Constant Propagation

There are some subtle points:

- ◆ Branch conditions should not be **TOP** when evaluated.
  - ◆ Indicates an upwards-exposed use. *(no initial value - undefined)*
  - ◆ Hard to envision compiler producing such code.
- ◆ Initialize all operations to **TOP**.
  - ◆ Block processing will fill in the non-top initial values.
  - ◆ Unreachable paths contribute **TOP** to  $\Phi$ -functions.
- ◆ Code shows CFG edges first, then SSA edges.
  - ◆ Can intermix them in arbitrary order. *(correctness)*
  - ◆ Taking CFG edges first may help with speed. *(minor effect)*

# Sparse Conditional Constant Propagation

More subtle points:

- ◆  $\text{TOP} * \text{BOT} \rightarrow \text{TOP}$ 
  - ◆ If  $\text{TOP}$  becomes  $0$ , then  $0 * \text{BOT} \rightarrow 0$ .
  - ◆ This prevents non-monotonic behavior for the result value.
  - ◆ Uses of the result value might go irretrievably to  $0$ .
  - ◆ Similar effects with any operation that has a “zero”.
- ◆ Some values reveal simplifications, rather than constants
  - ◆  $\text{BOT} * c_i \rightarrow \text{BOT}$ , but might turn into shifts & adds ( $c_i = 2$ ,  $\text{BOT} \geq 0$ )
  - ◆ Removes commutativity. *(reassociation)*
  - ◆  $\text{BOT}^{**2} \rightarrow \text{BOT} * \text{BOT}$ . *(vs. series or call to library)*
- ◆  $\text{cbr } \text{TRUE} \rightarrow L_1, L_2$  becomes  $\text{br} \rightarrow L_1$ 
  - ◆ Method discovers this; it must rewrite the code, too!

# Sparse Conditional Constant Propagation

## Unreachable Code

```
i ← 17
if (i > 0) then
    j1 ← 10
else
    j2 ← 20
j3 ← Φ(j1, j2)
k ← j3 * 17
```

## Optimism

- Initialization to **TOP** is still important.
- Unreachable code keeps **TOP**.
- $\wedge$  with **TOP** has desired result.

# Sparse Conditional Constant Propagation

## Unreachable Code

```
17  i ← 17
    if (i > 0) then
10    j1 ← 10
    else
20    j2 ← 20
    ⊥  j3 ← Φ(j1, j2)
    ⊥  k ← j3 * 17
```

All paths execute

## Optimism

- Initialization to **TOP** is still important.
- Unreachable code keeps **TOP**.
- $\wedge$  with **TOP** has desired result.

# Sparse Conditional Constant Propagation

## Unreachable Code

```
17   i ← 17
      if (i > 0) then
TOP    j1 ← 10
      else
TOP    j2 ← 20
TOP    j3 ← Φ(j1, j2)
170   k ← j3 * 17
```

With SCC  
marking  
blocks

## Optimism

- Initialization to **TOP** is still important.
- Unreachable code keeps **TOP**.
- $\wedge$  with **TOP** has desired result.

# Sparse Conditional Constant Propagation

## Unreachable Code

```
17  i ← 17
    if (i > 0) then
10   j1 ← 10
    else
TOP   j2 ← 20
10   j3 ← Φ(j1, j2)
170  k ← j3 * 17
```

With SCC  
marking  
blocks

## Optimism

- Initialization to **TOP** is still important.
- Unreachable code keeps **TOP**.
- $\wedge$  with **TOP** has desired result.

Cannot get this any other way:

- DEAD code cannot test ( $i > 0$ ).
- DEAD marks  $j_2$  as useful.

# Sparse Conditional Constant Propagation

## Unreachable Code

```

17  i ← 17
    if (i > 0) then
10   j1 ← 10
    else
TOP  j2 ← j2 < 20
10   j3 ← Φ(j1, j2)
170  k ← j3 * 17
  
```

With SCC marking blocks

## Optimism

- Initialization to **TOP** is still important.
- Unreachable code keeps **TOP**.
- $\wedge$  with **TOP** has desired result.

In general, combining two optimizations can lead to answers that cannot be produced by any combination of running them separately.

This algorithm is one example of that general principle.

Combining register allocation & instruction scheduling is another ...

# Using SSA Form for Optimizations

In general, using SSA conversion leads to:

- ◆ Cleaner formulations.
- ◆ Better results.
- ◆ Faster algorithms.

We've seen two SSA-based algorithms.

- ◆ Dead-code elimination.
- ◆ Sparse conditional constant propagation.